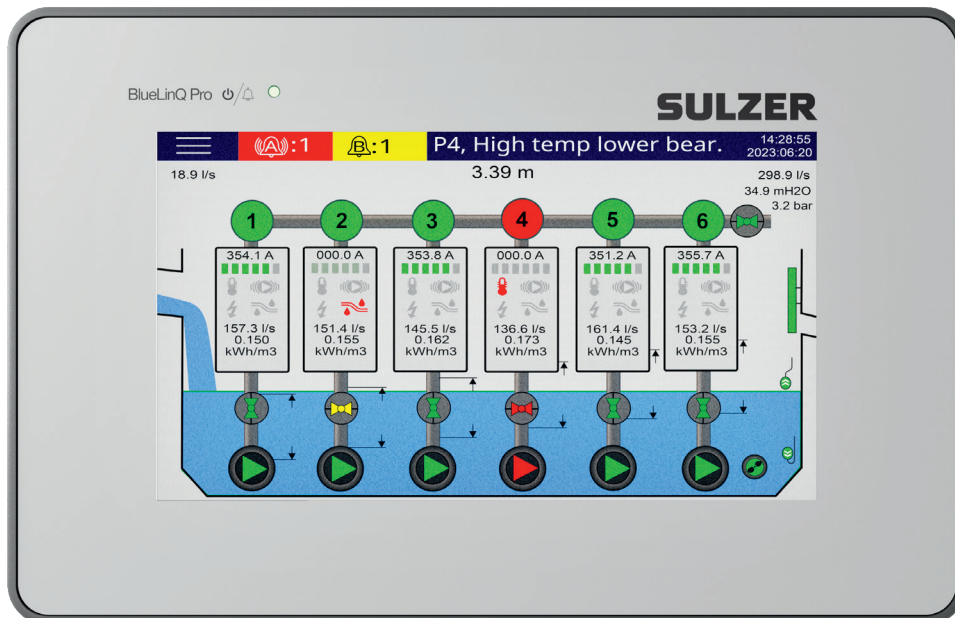


BlueLinQ Pro Controller (EC 541)



Copyright © 2023 Sulzer. All rights reserved.

This manual, as well as the software described in it, is furnished under license and may be used or copied only in accordance with the terms of such license. The content of this manual is furnished for informational use only, is subject to change without notice, and should not be construed as a commitment by Sulzer. Sulzer assumes no responsibility or liability for any errors or inaccuracies that may appear in this book.

Except as permitted by such license, no part of this publication may be reproduced, stored in a retrieval system, or transmitted, in any form or by any means, electronic, mechanical, recording, or otherwise, without the prior written permission of Sulzer.

Sulzer reserves the right to alter specifications due to technical developments.

Contents

| | |
|---|-----------|
| About this guide, audience and concepts | 6 |
| Text appearing and declaration in this guide | 7 |
| Glossary and conventions | 7 |
| 1 Overview of functions and usage | 8 |
| 1.1 BlueLinQ Pro controller (EC 541) | 9 |
| 1.1.1 BlueLinQ Pro symbols in the graphic display | 9 |
| 1.1.2 Screen appears differently with level sensor or floats..... | 10 |
| 1.1.3 Alarms..... | 11 |
| 1.1.4 The menus | 11 |
| 1.2 BlueLinQ modules | 12 |
| 1.2.1 BlueLinQ DI-12 Module (CA 811) - 12 Channel Digital Input Module | 12 |
| 1.2.2 BlueLinQ DO-8 Module (CA 821) - 8 Channel Digital Output Module | 12 |
| 1.2.3 BlueLinQ AI-6 Module (CA 831) - 6 Channel Analog Input Module | 13 |
| 1.2.4 BlueLinQ AO-6 Module (CA 841) - 6 Channel Analog Output Module..... | 13 |
| 1.2.5 BlueLinQ TI-6 Module (CA 832) - 6 Channel Temperature Input Module | 14 |
| 1.2.6 BlueLinQ LI-6 Module (CA 861) - 6 Channel Leakage Input Module..... | 14 |
| 2 Configure the BlueLinQ Pro controller (EC 541) | 15 |
| 2.1 System setup - general information | 15 |
| 2.2 Communication | 16 |
| 2.2.1 USB port | 16 |
| 2.2.2 RS485 ports..... | 16 |
| 2.2.3 RS232 port..... | 17 |
| 2.2.4 Ethernet ports (RJ45) | 17 |
| 2.2.5 Field bus modules (RS485) | 18 |
| 2.3 Configure the digital inputs, digital outputs, analog inputs and analog outputs | 18 |
| 2.4 Pump pit settings | 19 |
| 2.4.1 Station flow (recommended parameters)..... | 20 |
| 2.4.2 Overflow (optional parameter) | 20 |
| 2.4.3 Pit alarms (some parameters are recommended) | 20 |
| 2.4.4 Pump pit valve | 20 |
| 2.4.5 Cleaning control (optional parameter) | 20 |
| 2.4.6 Mixer control (optional parameter)..... | 20 |
| 2.4.7 Drain pump control (optional parameter)..... | 20 |
| 2.4.8 Motor protector auto reset (optional parameter) | 20 |
| 2.4.9 Level sensor check (optional parameter)..... | 20 |
| 2.4.10 Tariff control (optional parameter)..... | 20 |
| 2.4.11 Level above sea (optional parameter) | 20 |
| 2.5 Pump settings | 20 |
| 2.5.1 Common P1-P6 | 20 |
| 2.5.2 Pump 1-6 settings..... | 21 |
| 2.6 Set log settings and events..... | 23 |
| 2.7 Set up communications to surrounding units VFD, soft starters and energy meter..... | 24 |
| 2.8 Set up cleaner, mixer or drain pump (if used)..... | 24 |

| | | |
|---------------------|---|-----------|
| 3 | Detailed descriptions of the functions | 25 |
| 3.1 | Pump capacity calculation | 25 |
| 3.2 | Overflow flow calculation | 35 |
| 3.3 | Pump alternation | 37 |
| 3.4 | Pump reversing..... | 37 |
| 3.5 | Speed controlled pumps (VFD) | 38 |
| 3.6 | Best efficiency point pump control | 40 |
| 3.7 | Crash log | 41 |
| 3.8 | Communication | 41 |
| 3.9 | Cross reference table | 43 |
| 4. | Further explanations of functions of the analog and digital input and output signals | 45 |
| 4.1 | Digital in: personnel alarm and local mode | 45 |
| 4.2 | Digital in: block operation..... | 45 |
| 4.3 | Digital out: data register set point | 45 |
| 4.4 | Digital out: logic IO | 46 |
| 4.5 | Digital out: auto reset alert | 46 |
| 4.6 | Analog in: outlet pressure | 46 |
| 4.7 | Analog out: data register and data register 2's complement | 47 |
| 5. Appendix: | BlueLinQ Pro Menu Guidelines | 49 |
| 5.1 | Manual control | 50 |
| 5.2 | Alarm and event lists | 50 |
| 5.3 | Quick status: System | 51 |
| 5.4 | Quick status: Pump pit..... | |
| 52 | | |
| 5.5 | Quick status: Pumps..... | 54 |
| 5.6 | Quick status: Digital inputs | 59 |
| 5.7 | Quick status: Digital outputs | 59 |
| 5.8 | Quick status: Leakage inputs..... | 59 |
| 5.9 | Quick status: Analog inputs | 60 |
| 5.10 | Quick status: RTD temperature inputs..... | 60 |
| 5.11 | Quick status: Analog outputs | 61 |
| 5.12 | Detailed status: System | 61 |
| 5.13 | Detailed status: Pump pit..... | 62 |
| 5.14 | Detailed status: Pumps..... | 64 |
| 5.15 | Detailed status: PID regulator..... | 66 |
| 5.16 | Detailed status: Clock functions..... | 66 |
| 5.17 | Detailed status: Pulse channels..... | 67 |
| 5.18 | Detailed status: Inputs and outputs | 67 |
| 5.19 | Detailed status: Communication | 73 |
| 5.20 | Detailed status: Field bus modules (RS485) | 75 |
| 5.21 | Settings: System..... | 76 |
| 5.22 | Settings: Pump pit..... | 77 |
| 5.23 | Settings: Pumps..... | 80 |
| 5.24 | Settings: Clock functions | 88 |
| 5.25 | Settings: IO-bit controlled data | 89 |

| | | |
|------|--|-----|
| 5.26 | Settings: Free user data registers..... | 90 |
| 5.27 | Settings: PID regulator..... | 92 |
| 5.28 | Settings: Pulse channels | 92 |
| 5.29 | Settings: Analog logging | 93 |
| 5.30 | Settings: Inputs and outputs | 93 |
| 5.31 | Settings: Communication..... | 102 |
| 5.32 | Settings: Field bus modules (RS485)..... | 105 |
| 5.33 | Select language | 106 |
| 5.34 | Calibrate touch screen..... | 106 |

About this guide, audience and concepts

This guide describes the BlueLinQ Pro controller (EC 541). The equipment controller can either be used stand-alone or communicate values and conditions to a central SCADA system or a web based alarm and monitoring solution like AquaWeb from Sulzer.

Installation guide There is a separate document Installation guide that describes how to physically install the pump controller (printed document in the installation package, and also a PDF on www.sulzer.com).

Audience This guide is intended for system administrators and operators of the BlueLinQ Pro.

Prerequisites This guide assumes that you already are acquainted with those pumps you are set to control and have the sensors connected to BlueLinQ Pro.

The system administrator must also know and decide on the following:

1. The pump controller can either use an analog level-sensor, which measures the water level in the pit, for precise control over start and stop levels, or it can use simple float switches placed at start and stop levels.
 - Float switches can be used in addition to an analog level-sensor, as a backup, and as an additional alarm input.
 - An analog level-sensor has several advantages over float switches: it is more robust (cannot get stuck or be mechanically jammed); it is more accurate; it is more flexible (the start and stop levels can easily be changed); you can get readings of the water level in the pit, the inflow, overflow and the pump capacity; you can optimize the pump performance in various ways, including exercising, alternative stop levels, tariff control etc.
 - It is also possible to employ an alternative stop level, usually a lower level than normal, that is effective once after a number of pump starts. This can be useful if it is desirable to “completely” empty the pit once in a while.
2. You need to know if the pump(s) should be exercised in case of long idle periods. If the installation has one or two pumps, you need to decide if the pumps should alternate.
3. If the electricity has daily varying tariffs, you must know the times of high / low tariffs.
4. You must know how overflow will be measured: if it will be measured using both an overflow detector (to detect the start of the overflow) and a level sensor (to measure the actual flow), you must know the parameters (exponents and constants) to be entered as settings so that the overflow can be accurately calculated by the BlueLinQ Pro.
5. You need to know which alarm class, A-alarm or B-alarm (see Glossary and conventions), to assign each alarm.

Reading guide For installation, see the separate document Installation guide, which covers BlueLinQ Pro. Before you make any settings, or use the control panel, read [chapter 1 Overview of the display symbols](#) —it describes the general functionality and the meaning and usage of the controls on the panel.

The system administrator must ensure that all settings according to chapter 2 Setup the BlueLinQ Pro are suitable for your application.

NOTE! *The default settings are listed in the Installation guide.*

Text appearing and declaration in this guide

Most settings in chapter 2 only apply to the system administrator, but the following also apply to those who operate the controller: language selection, date and time settings, units, backlight time-out, buzzer, operator passcode, start / stop levels.

Glossary and conventions

To designate a menu item in a hierarchy, an angle bracket is used to separate the levels. Example: Settings > System means the menu item you reach by first choosing the menu item Settings, which has a number of submenus, where you choose the menu item System.

Text in blue indicates a hypertext link. If you read this document on a computer, you can click on the item, which will take you to the link destination.

- Pump exercising** Long idle periods in a corrosive contaminated environment are not good for pumps. As a countermeasure, they can be “exercised” at regular intervals, which will reduce corrosion and other detrimental effects.
- Alarm class** The alarm class can be either A-alarm or B-alarm. A-alarms are those that require immediate action, so operational staff in the field should be alerted regardless of the time of day. B-alarms are less important, but should be taken care of during normal work hours.
- Digital in** A signal that is either ON or OFF (high or low), where high is anything between 5 and 35 volts DC, and low is anything below 2 volts.
- Digital output** A signal that is either ON or OFF. At ON condition output current is sourced from the power supply and the output is high (~V+). At OFF condition the output is low but it cannot serve as a drain function (no output current). Are typically connections to relays.
- Analog output** Signal in the range 4-20 mA. Sourced from power supply.
- Analog input** Eight analog inputs used for connecting sensors. **Ain:1** to **Ain:4** are 4-20 mA inputs. **Ain:5-Ain:6** are configurable for Pt100 and PTC. **Ain:7-Ain:8** are configurable for or Pt100 and Leakage.
- Pump reversing** The controller can reverse the pump if the necessary external equipment is installed in the station. The controller can reverse the pumps on number of occasions, e.g. low capacity, pump fail, fallen motor protector, over currents and after number of starts
- RS485 modules** Refer to surrounding units connected to the RS485 bus, e.g. soft starters, VFDs, and an energy meter or to a surveillance system like a SCADA

1 Overview of functions and usage

BlueLinQ Pro is designed to control 1-6 pumps. It can operate a pump station stand alone and / or within a surveillance system together with some communication equipment. For configuration and operator interaction, use the menus which can be selected tapping on the screen, Enter and Esc keys. With the AquaProg software, configuration and back up of settings can be stored on a PC.

Add a Sulzer dedicated modem to create a full remote alarm and monitoring solution, together with an AquaWeb rental contact or by any SCADA system.

BlueLinQ Pro base unit is the module with the 7" touch screen. This unit can work alone or adding more subunits to expand the I/O signals. The base unit has 4 digital inputs and 4 digital outputs. Communication ports are two RS485 ports and one of each of USB, RS232 and a RJ45 Ethernet port. BlueLinQ Pro unit also has a MicroSD memory slot.

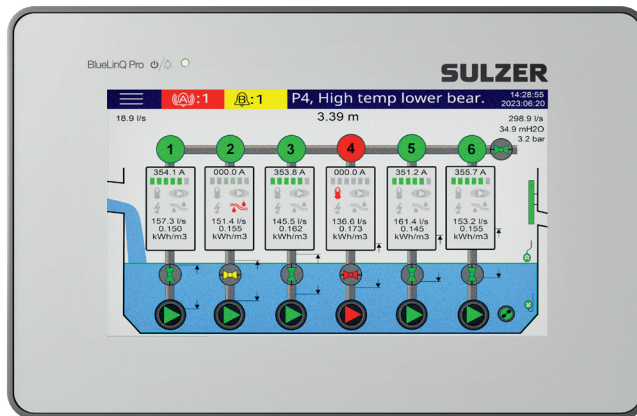


Figure 1.1: Base module BlueLinQ Pro

Expansion I/O modules

A BlueLinQ Pro system as a base unit can be expanded with multiply I/O-units to meet the needs of today and tomorrow. There are possibilities to have up to max 32 expansion various units and 9 of each kind of the following units in one BlueLinQ Pro system:

| | |
|---------------------------------------|------------------------------------|
| BlueLinQ DI-12 Module (CA 811) | 12 Channel Digital Input Module |
| BlueLinQ DO-8 Module (CA 821) | 8 Channel Digital Output Module |
| BlueLinQ AI-6 Module (CA 831) | 6 Channel Analog Input Module |
| BlueLinQ TI-6 Module (CA 832) | 6 Channel Temperature Input Module |
| BlueLinQ AO-6 Module (CA 841) | 6 Channel Analog Output Module |
| BlueLinQ LI-6 Module (CA 861) | 6 Channel Leakage Input Module |



Figure 1.2: Extension modules

The system can be complemented with modem to communicate to a surveillance/SCADA system.

Sulzer wireless modem (max. 1 unit/system)

Other protocol converters are available on the open market.



Figure 1.3: Sulzer Modem

1.1 BlueLinQ Pro controller (EC 541)

The BlueLinQ Pro controller is the heart of the BlueLinQ Pro system. The default screen (top-level view) of the display on the BlueLinQ Pro controller dynamically shows the operating status of the pumps and conditions in the pit, displaying just about everything you need to know about the current situation. Figure 1-1 shows symbols and explains their meanings. The unit will always revert to this view after 10 minutes of inactivity in any other view (such as showing menus or submenus).

In the submenus you can always return to the default screen by pressing ESC.

Power and Alarm LED

- Green:
Power On -No active alarms
- Red blinking:
Non acknowledge alarm/s is active
- Red solid:
At least one acknowledged alarm is active,

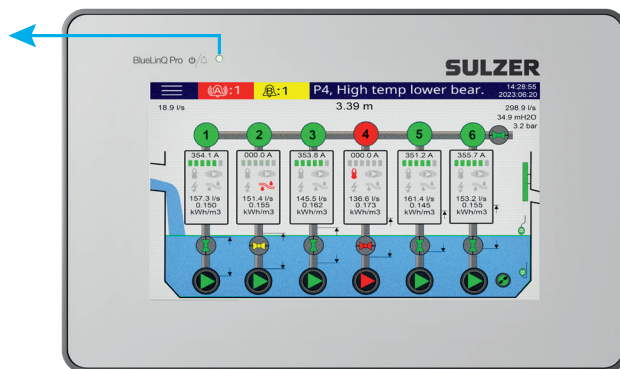


Figure 1.4: Power and alarm LED

1.1.1 BlueLinQ Pro symbols in the graphic display

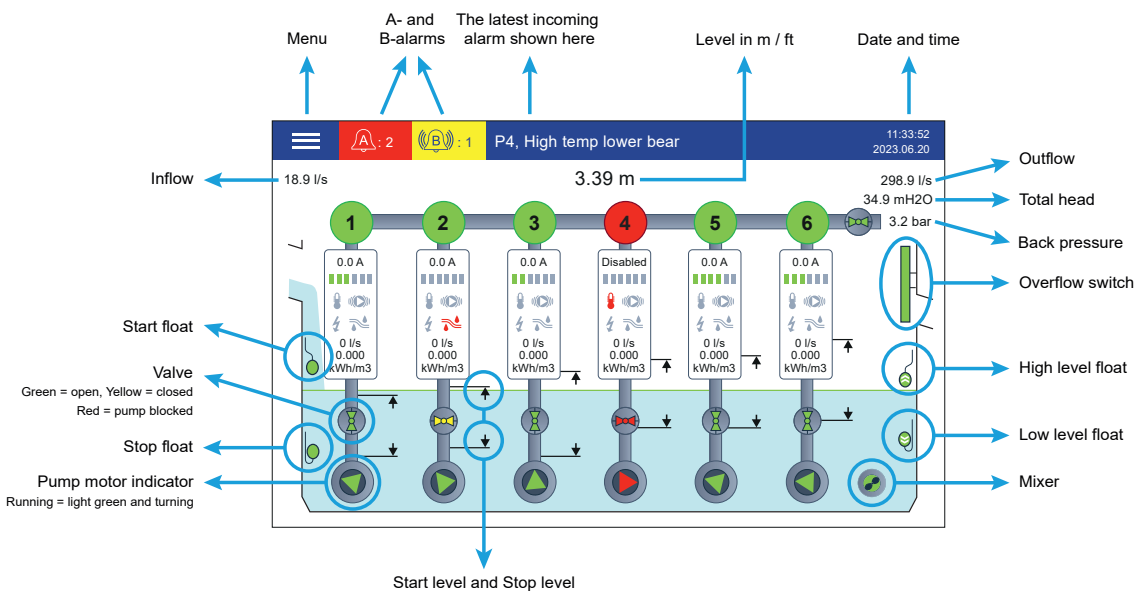


Figure 1.5: Graphic display

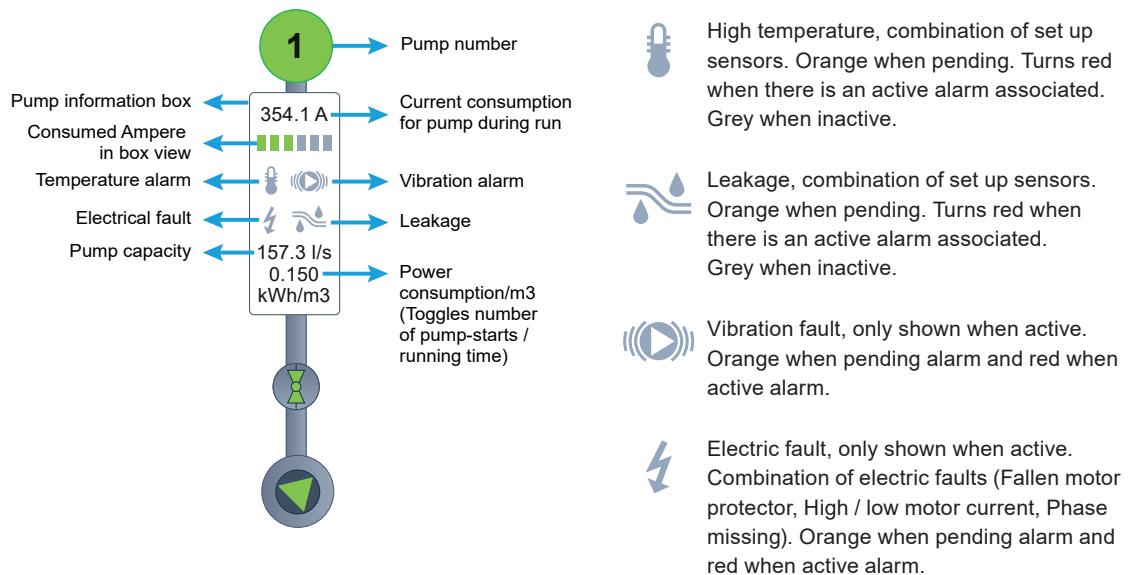


Figure 1.6: Graphic display - pump line

1.1.2 Screen appears differently with level sensor or floats

The top screen appears differently depending on if there is a level sensor in the system or not. There is no level value presented if the pit is without a level sensor. If no analog input is dedicated for Level sensor, the controller assumes there are Start / Stop floats. The start / stop floats are animated and must have a dedicated input if they are to appear on the display.

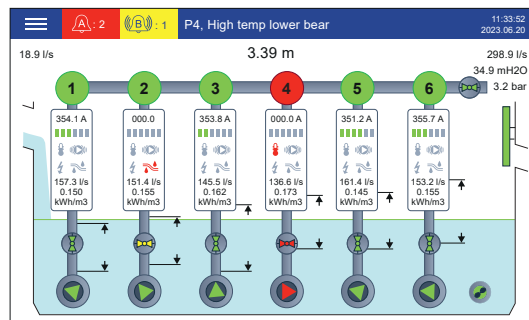


Figure 1.7: Appearance with level sensor

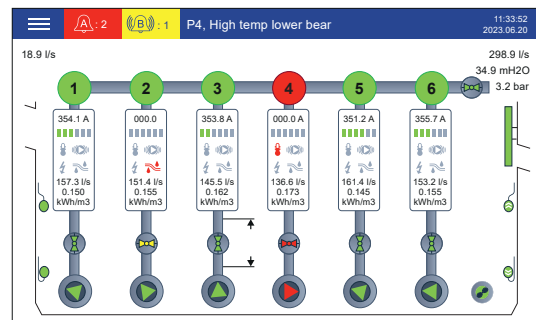


Figure 1.8: Appearance with start/stop floats

Level and the dynamic field

If level sensor is installed on one of the analog inputs, the height of the level in the pit is presented, shown with two decimal places, and by means of a visual water level indicator on the graphics display. Level can be referenced from sea level (if set). If there is a high-level alarm setup and it gets activated, the dynamic field turn into red. If the system runs on floats, no level or visual water level indicator will be shown on the display.

Outlet value on the display

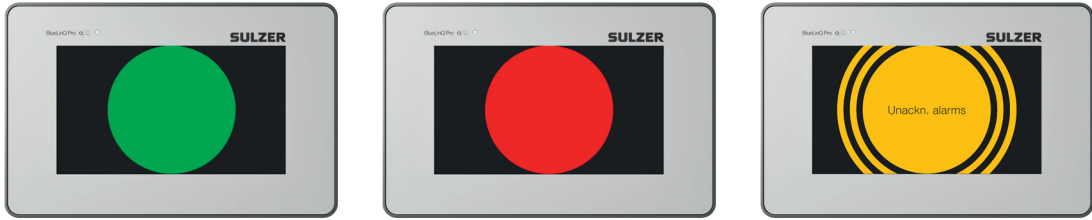
Outflow: After the controller has calculated the pump capacity, a value appears on the display when the pump or pumps run. See the section 3.1 Pump capacity calculation for information on how the calculation is done and which parameters are necessary to set. Outlet pressure: If there is an outlet pressure sensor installed, the value appears on the display. See the section 3.1 Pump capacity calculation for information on how the calculation is done and which parameters are necessary to set.

Floats and overflow sensor on the display

High- and low level floats are green in normal mode. They switch position (animated) and are flashing red when activated. Start / stop floats are gray in non-active mode, and blue when activated. Overflow sensor is green in normal mode, turn to flashing red when activated.

Screensaver

When the screen has been inactive for 3 minutes (default), the screen saver starts. The screensaver has a dark background with a flashing green / red / yellow circle, depending on its' status.



Solid green circle: No active alarms

Solid red circle: At least one active acknowledged A-Alarm

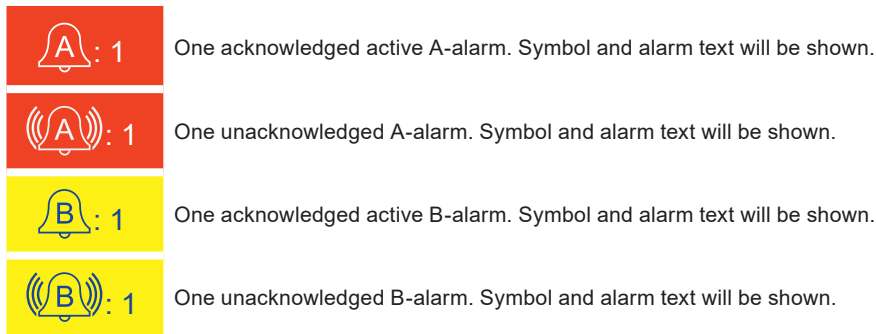
Red circle with brackets: At least one unacknowledged A-Alarm

Solid yellow circle: At least one active acknowledged B-Alarm

Yellow circle with brackets: At least one unacknowledged B-Alarm

1.1.3 Alarms

When alarms occur, the symbols for A-alarm or B-alarm will be colored on the first line in the main screen. If the bell is tremble, that symbolize unacknowledged alarms. The number in the alarm box will say how many active alarms there are and in each category.



1.1.4 The menus

To enter the main menu, tap the menu symbol in the upper left corner.



Figure 1.9: Menu icon on the BlueLinQ Pro controller screen

From the main menu, the submenus are available.

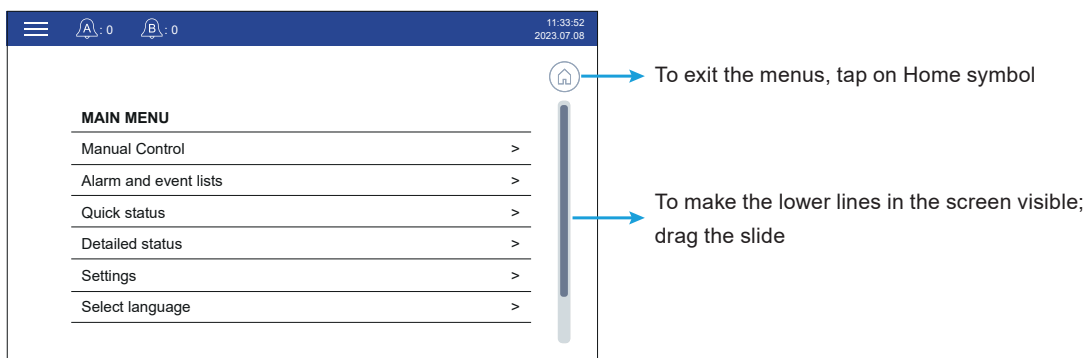


Figure 1.10: BlueLinQ Pro controller main menu screen

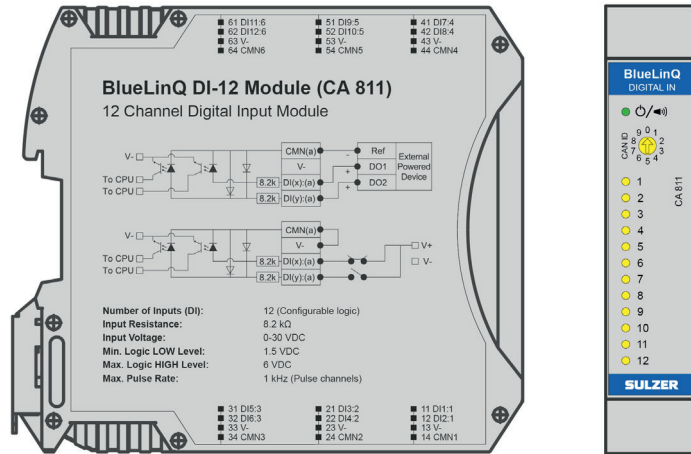
1.2 BlueLinQ modules

A maximum of 30 expansion units can be used, in addition to 9 of the following modules:

Note: *The first unit in the system shall have CAN ID = 1, remaining units must have unique IDs in ascending order.*

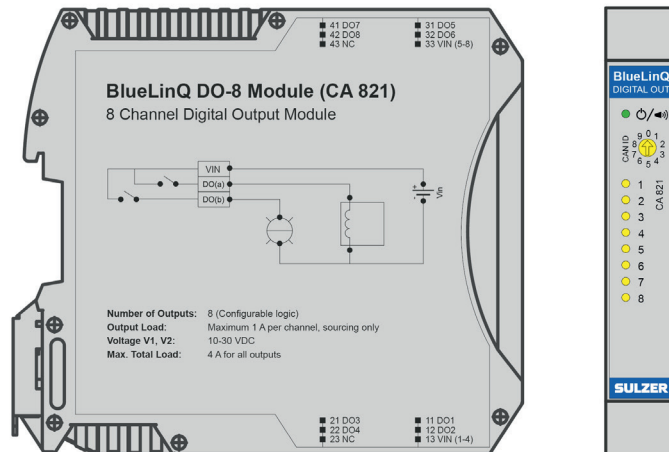
1.2.1 BlueLinQ DI-12 Module (CA 811) - 12 Channel Digital Input Module

BlueLinQ DI-12 has 12 Digital Inputs in one module. The input voltage must not exceed the BlueLinQ Pro supply voltage.



- Every group of 2 inputs are galvanic isolated. Pulse input rate is 1kHz with 50% symmetrical duty cycle.
- Port active and assigned yellow lamp lit
- Port inactive (physical state of port) yellow lamp off
- Port active and not assigned yellow lamp flashing
- PTC or bimetal temperature sensors are connected between V+ and input in series

1.2.2 BlueLinQ DO-8 Module (CA 821) - 8 Channel Digital Output Module

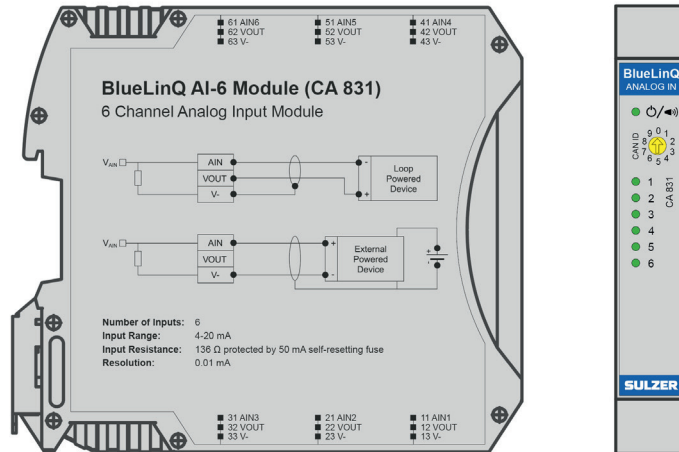


- An alternative supply from the BlueLinQ Pro can be used if there is a risk to the output being overloaded.
- Eight voltage outputs for driving LED's, relays and signaling to other devices. Configurable logic.
- Max. load 1 A/output, max. total load (8 outputs) = 4 A.
- < 30 VDC (sourcing from power supply), only sourcing - no drain.
- With address switch in first position, module also works as bus terminator and bus power feeder
- Port active and assigned = yellow LED lit
- Port inactive (physical state of port) = yellow LED off
- Output overloaded = yellow LED flashing

When power sourcing field bus

- System BusPwr LED when power is within limit = Green
- Critical low = Red flashing
- Power save activated = Orange

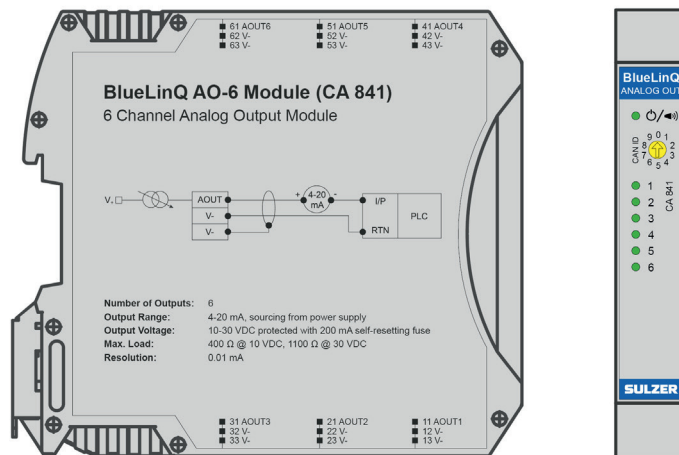
1.2.3 BlueLinQ AI-6 Module (CA 831) - 6 Channel Analog Input Module



- Six current inputs for sensor 4-20 mA signaling interface. Sample frequency 10 Hz, 0.5 % Accuracy.
- Port active and assigned = green LED's lit
- Port unassigned = LED's off
- Open loop or over current (and assigned) = green LED flashing
- Current flowing and unassigned = green LED flashing

Note: The recommended connection cable is twisted and shielded

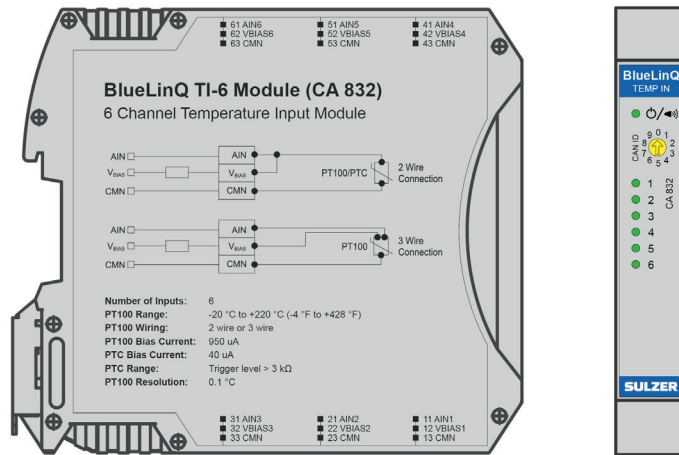
1.2.4 BlueLinQ AO-6 Module (CA 841) - 6 Channel Analog Output Module



- Six current output 4-20 mA signaling for meters, PID control, etc. Resolution 1 μA, precision 1%
- Indicator LED's on device
- Port active and assigned = green LED's lit
- Port unassigned = LED's off
- Open loop (and assigned) = green LED flashing
- Current flowing and unassigned = green LED flashing

Note: The recommended connection cable is twisted and shielded

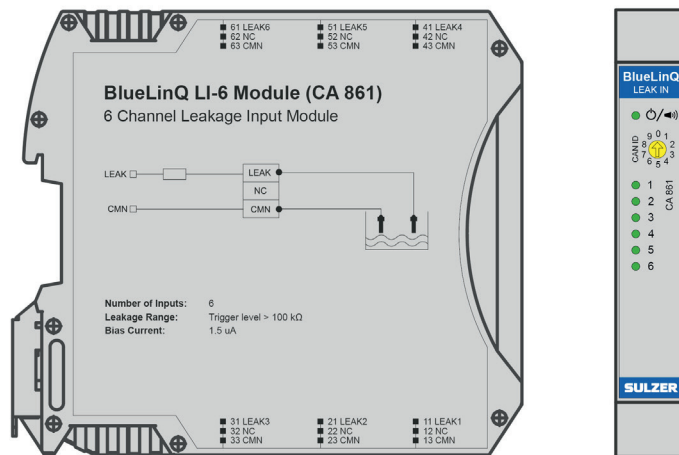
1.2.5 BlueLinQ TI-6 Module (CA 832) - 6 Channel Temperature Input Module



- Temperature sensing, 6 channels three/two wire connection. Module galvanically isolated from field bus. Precision 0.1 %. Pt100 or PTC (bi-metal).
- Indicator lamps on device is working like this
- Port active and assigned = green LED's lit
- Port unassigned = LED's off
- Open loop or shorted (and assigned) = green LED flashing
- Connected and unassigned = green LED flashing

Note: The recommended connection cable is twisted and shielded

1.2.6 BlueLinQ LI-6 Module (CA 861) - 6 Channel Leakage Input Module



- Moisture or water intrusion detection. Module galvanically isolated from field bus. Uses pulsating output and measures saturation. Default trip value 100 kΩ ± 10 %
- Indicator LED's:
 - Port active and assigned = yellow LED lit
 - Port unassigned = LED off
 - Flashing LED when triggered

Note: The recommended connection cable is twisted and shielded

2 Configure the BlueLinQ Pro controller (EC 541)

Overview of settings

Every station will have its own unique configuration but the procedure to setup the station is similar. This chapter will guide you through the basic settings in the BlueLinQ Pro controller. Note this does not cover all configuration, you must consider your prerequisites.

Before starting to setup the controller, its highly recommended to make a reset of the unit. The BlueLinQ Pro controller reset button is accessed through a small hole on one of the edges. To activate place a straightened paperclip or similar into the hole and hold for 10 seconds, this will restore the unit's configuration to factory default.

The menu item Settings has 12 submenus with many settings that need to be entered by the system administrator (although they all have default values). The notes below are a recommended procedure to setup the BlueLinQ Pro controller

2.1 System setup - general information

2.2 Communication

2.3 Configure the digital inputs, digital outputs, analog inputs and analog outputs

2.4 Pump pit settings

2.5 Pump settings

2.6 Set log settings and events

2.7 Set up communications to surrounding units VFD, soft starters and energy meter

2.8 Set up cleaner, mixer or drain pump (if used)

Each of the 12 submenus under settings are described in separate tables in appendix.

Most of the settings require a passcode for System, except some settings under the submenu System, and the start / stop levels under submenus for the pumps, which only require a passcode for the Operator.

Default passcodes: For operator = 1. For admin = 2.

All the settings can be configured locally from the menus or by AquaProg. The advantage of AquaProg is that you can save the configuration on your PC and easily restore the controller if needed.

2.1 System setup - general information

Here are some important parameters to set:

- Station ID
- Date format
- Metric or US units
- System Alarms
- Appearance of the graphical display
- SD card settings

Station ID is very important if there is a SCADA as a surveillance system communication with the controller. In AquaWeb environment this parameter is crucial.

If personnel alarm is used, here is the time settings for that function.

After setting up the station ID, the recommendation is to setup the communication for facilitate further work with the settings by using Aquaprogram.

2.2 Communication

See section 3.8 for more detailed information.

2.2.1 USB port

The USB port is normally used as a local service port and there shall the connection be done to your laptop/PC. The BlueLinQ Pro USB service port supports USB2.0 and is of Mini-B connection type, see Figure 4 and Table 1 in Installation guide. It is primarily used to download configuration information and updating firmware using AquaProg. The port supports Modbus RTU or Modbus TCP and cross reference in settings. When connecting the BlueLinQ Pro via USB to a PC for the first time a driver appears, just follow the instructions on your PC.

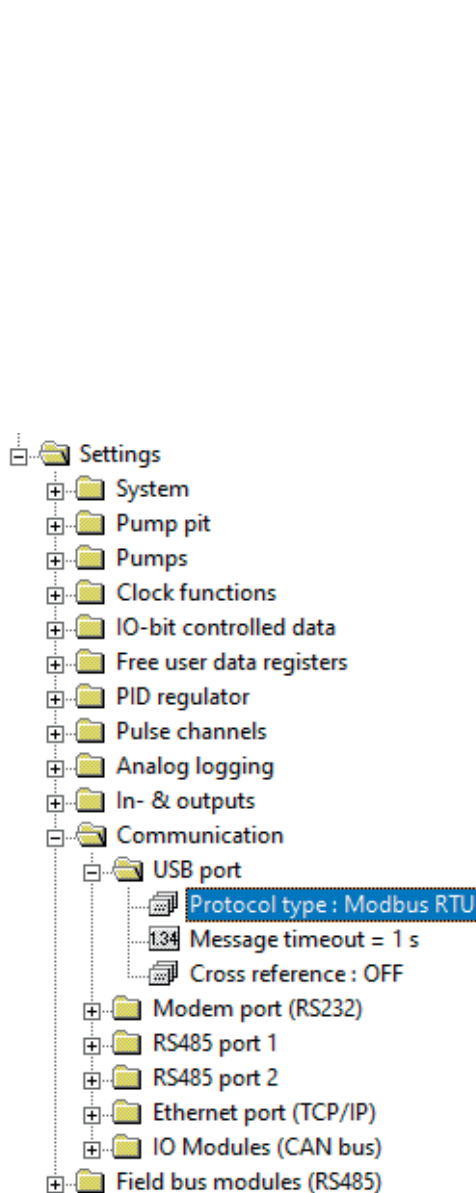


Figure 2.1: AquaProg view of the Communication settings

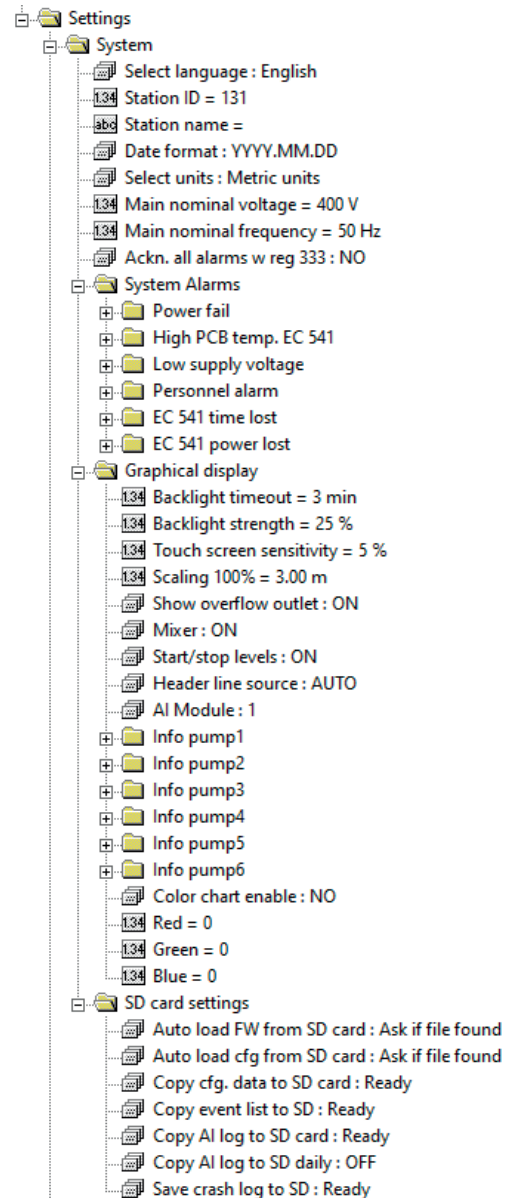


Figure 2.2: AquaProg view of the System settings

2.2.2 RS485 ports

There are two RS485 serial ports on BlueLinQ Pro. They can act as a Master or Slave and use protocol type Modbus RTU or Modbus TCP independently of each other. If there are any Motor Drives or Power monitors connected to BlueLinQ Pro via RS485, the parameters for these must be set in the Section "Field bus modules" further down in this document. Here under the settings for Communication and RS485 port, the baud rate, parity, protocol type and Application protocol must be set. Baud rate, parity and protocol type must harmonize the surrounding units which

communicate with this port. An RS485 communication line must be terminated in both ends. The BlueLinQ Pro has a jumper for termination in the controllers end.

Application protocol:

- If the RS485 port communicates with the motor drives or power monitors, the application protocol must be set as 'Modbus Master'. Poll intervals are usually set to 1 second. If the electrical environment is noisy, this interval can be increased.
- If the port communicates with a SCADA or PLC, the port must be set as Modbus slave and a protocol ID must be set.

Note: *If using 6 motor drivers, it's recommended to put three motor drivers on the first RS485 port, and the other three on port number 2.*

2.2.3 RS232 port

The RS232-port is design for modem and handle Hayes commands which is crucial for 3G, 4G and 5G modems. If using GPRS modem, the application protocol must be GPRS Hayes enable. If other protocol converter is used on the port, the application protocol can be set Transparent.

Other settings are set in relation to the connected device.

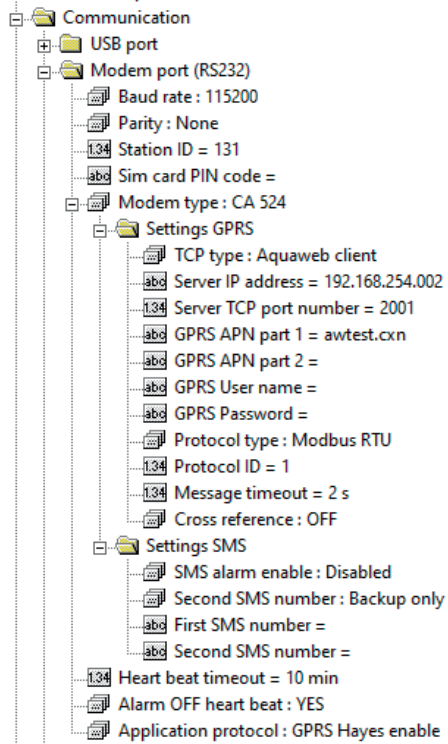


Figure 2.3: Aquaprogram view of the Communication settings

2.2.4 Ethernet ports (RJ45)

The ethernet port handles up to 10 simultaneous connections.

There is an advantage if both ends can communicate with Modbus TCP, the communication speed increases.

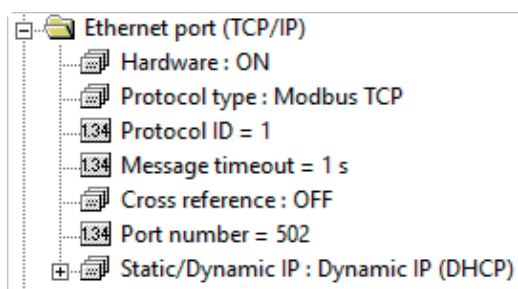


Figure 2.4: Aquaprogram view of the Ethernet settings

2.2.5 Field bus modules (RS485)

Motor drives and power monitor settings are provided in this section.

BlueLinQ Pro supports up to seven power monitors and six motor drives. Ensure a unique Modbus ID is set up on each connected unit.

Select manufacturer and model.

Note: When using both RS485 ports, every unit on the RS485 bus must have a unique ID.

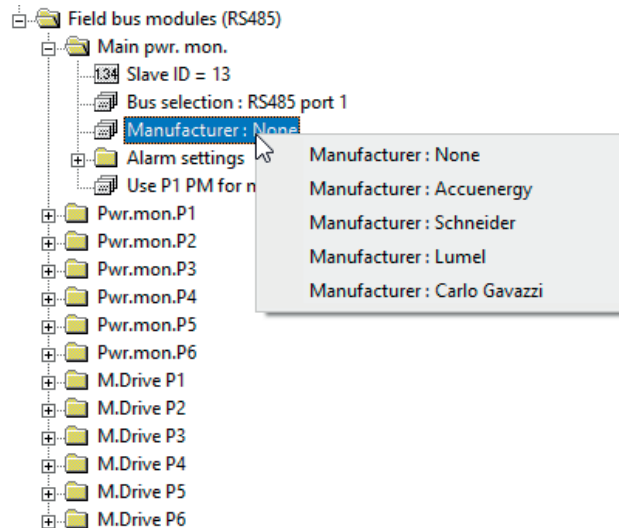


Figure 2.5: Aquapro view of setting for Field bus options:

2.3 Configure the digital inputs, digital outputs, analog inputs and analog outputs

Set designated IO-functions according to the electrical wiring drawing. See your drawings of the station. Under **Settings > Digital inputs**; choose each input and output according to tables 2.1 and 2.2 below.

Table 2.1

| Digital inputs |
|------------------------|
| OFF |
| Run indication |
| Manual start |
| Set manual |
| Set auto |
| Start float |
| Pump failure |
| Motor protector |
| High motor temp. pump |
| Leakage pump |
| Stop float |
| Low level float |
| Overflow sensor |
| High level float |
| Start float drain pump |
| Local mode |
| Alarm reset |
| Power fail |
| DI pulse channel 1-4 |
| Block PID controller |
| Alarm input |
| Block operation |

Table 2.2

| Digital outputs |
|-------------------------|
| OFF |
| Pump control |
| Reset motor protector |
| Pump fail |
| Not enough pumps avail. |
| One pump fail |
| Mixer control |
| Drain pump control |
| Cleaner control |
| Com timeout control |
| Remote control |
| Personnel alarm |
| High level |
| Alarm alert |
| Not acknowledged alarm |
| Active alarm |
| Pump reversing |
| Logic IO |
| Data register setpoint |
| Auto reset alert |
| Valve control |
| Valve open |

Table 2.1

| Digital inputs |
|-----------------------------|
| Leakage mixer-drain pump |
| High temp. mixer-drain pump |
| Emergency power mode |
| Block remote data |
| Acknowledge pump alarms |
| Valve open |
| Valve close |

Table 2.2

| Digital outputs |
|-----------------|
| Valve close |
| Time relay |
| Pulse timer |

Under Settings, Inputs and outputs, Analog inputs, Module X, choose each input according to table 2.3 and analog outputs in table 2.4.

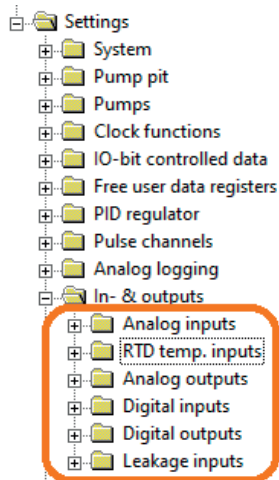
Table 2.3

| Analog inputs |
|---------------------|
| OFF |
| Pit level |
| Motor current |
| Outlet pressure |
| Vibration |
| Outflow meter |
| Motor temperature |
| Secondary pit level |
| Free choice |

Table 2.4

| Analog outputs |
|------------------------|
| OFF |
| Pit level |
| Pit inflow |
| Pit outflow |
| Pit overflow |
| Pulse channel 1-4 |
| PID Ctrl output |
| Data register |
| Data register 2-compl. |
| Set freq. P1-P6 |

If using temperature modules (BlueLinQ TI-6) and/or leakage modules (BlueLinQ LI-6), select the setting here in accordance to the pump configuration.



2.6: Aquaprogram view of Analog/digital inputs/outputs settings

2.4 Pump pit settings

It is recommended to set up the pit area under station flow, to ensure the pump calculations perform as accurately as possible. They are bound to energy calculation, pump capacity and outlet calculations. Use the outlet pressure sensor for the most accurate pump capacity and pumped volume calculations

Table 2.5

| Pit settings |
|------------------|
| Station flow * |
| Overflows |
| Pit alarms |
| Pump pit value |
| Cleaning control |
| Mixer control |

Table 2.5 continued

| Pit settings |
|----------------------------|
| Drain pump control |
| Motor protector auto reset |
| Level sensor check |
| Tariff control |
| Level above sea |
| Free choice |

* Necessary for accurate pump capacity calculation

2.4.1 Station flow (recommended parameters)

Under Meas. parameters set the Inflow calculation=ON and your pit shape, also the function Emptying or Filling the pit must be set. System curve at duty point is used if there isn't any Outlet pressure sensor.

2.4.2 Overflow (optional parameter)

Overflow can be detected by an overflow detector (MD 131) or by the certain level. See more information about overflows in section 3.2

2.4.3 Pit alarms (some parameters are recommended)

There are several alarms which can be set under Pit alarms. Each alarm is configurable to be A- or B-alarms. Consult your drawings and verify which are important for your installation. See section 3.7 for further information about crash log.

2.4.4 Pump pit valve

Time settings for the characteristics of the pump pit valve

2.4.5 Cleaning control (optional parameter)

Start on at pump start or pump stop. Configurable running time in second and interval. To disable function; set time and interval to zero. A dedicated digital output controls the cleaner.

2.4.6 Mixer control (optional parameter)

Mixer can be controlled by number of pump starts and/or by a time interval. Require a digital out signal to control the Mixer.

2.4.7 Drain pump control (optional parameter)

Drain pump require a digital input signal allocated as Start float drain pump and a digital output as Drain pump control to control starts and stops of the drain. Drain pump is running in configurable time in seconds

2.4.8 Motor protector auto reset (optional parameter)

Pulse time and delay must be set as maximum number of attempts. A digital output controls the reset.

2.4.9 Level sensor check (optional parameter)

Level sensor check It is possible to check the level sensor reading compared to the installed floats. See the settings under Level sensor check set this up.

2.4.10 Tariff control (optional parameter)

This function is to reduce energy consumption in hours of high cost of energy. You can set this up for separate days in the week.

2.4.11 Level above sea (optional parameter)

If you type in a value here, this value will be added in the pit level but not affect the start/stop levels.

2.5 Pump settings

2.5.1 Common P1-P6

Settings – Pumps – Common P1-P6

To avoid possible station problems this option has many useful functions like, Pump exercising, Pump reversing, Max number pumps running, Min relay intervals, Alternations and Pump blocking.

Pump exercising: It is possible to exercise a pump if required. A maximum pump off time and exercising time can be set. The level must be within the parameters.

Pump reversing: Several parameters can trigger reversing.

Max. number of pump running: To save energy and/or minimize load on the grid.

Min. number of pumps available: Before the alarm: "Min. pump are available"

Min. relay interval: To minimize load on the grid

Pump alternation: See section 3.3.

Pump blocking: Which circumstances shall block the pumps

Calculation pump capacity: Function On or Off, preferences of calculation

Alternative stop level: Start on fast change

Backup run: When High level float activates, dedicated pumps start for adjustable time. Extra secure against overflow.

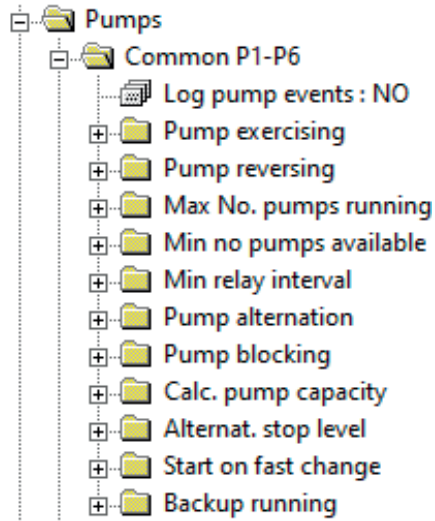


Figure 2.6: Aquaprog view of Pump settings

2.5.2 Pump 1-6 settings

Setting up the pumps and their alarms

Important parameters to configure for each pump:

- Type of pump control
- Running indication
- Start / stop level
- Pump alarms
- Pump valve (if used)
- Optional parameters: Pump curve

Type of pump control

- Pump disabled
If not using all pumps in BlueLinQ Pro, recommended is to let pumps with higher number to be disabled.
- ON / OFF control
A digital output starts the pump without any RS485 communication to VFD or soft starter
- VFD manual speed
Start a VFD which has predefined frequency
- VFD PID control
Start / stop pump with digital output and VFD controlled by 4-20 mA analog output from the controller
- VFD best efficiency point
Require RS485 communications to VFD

Select run indication

- Any discrete source
Output signal or digital input
- Output signal
No return signal from the pump, just activated output signal from the relay contact
- Motor current
Current transformers connected to an analog input

- Fieldbus RS485
RS485 communication to / from VFD or soft starter
- And current threshold (if applicable).
Select Power monitor if used

Start / Stop levels for each pump

Recommended is to have different start levels for the pumps and that no pump has the same start level as another. Same stop level for several or all pumps is fine.

Time settings

On/Off delays, maximum runtime

Pump curve

Recommended to enter the pump curve

Pump alarms

There are several pump alarms to setup. Each alarm is configurable to be A- or B-alarms. The first part, table 2-8 below, is to setup the types of alarm (A- or B), alarm delay and if the alarm shall trigger the crash log.

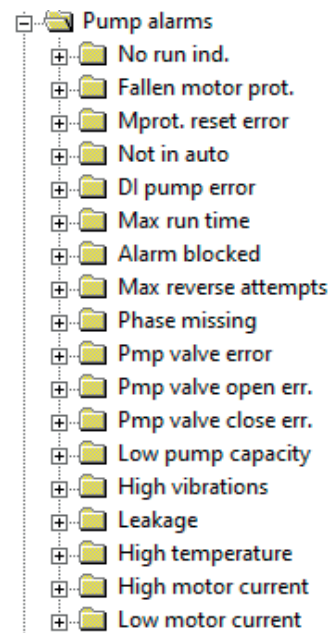


Figure 2.7: Aquaprolog view of pump alarms

Block pump on alarm

These alarms must be acknowledged on site or remotely to allow the pump to start again.

Hold pump on alarm

All the alarms here will block the pump when the alarm is active. When the criteria for the alarm have returned to normal state, the pump starts again automatically.

Best efficiency point

Best efficiency point is a function which require VFDs and RS485 communication to VFDs.

Pump valve

Time settings for individual valve for each pump.

Pump Tag name

Give the pump a name, max. 11 characters

Block pump on alarm

These alarms must be acknowledged on site or remotely to allow the pump to start again.

Hold pump on alarm

All the alarms here will block the pump when the alarm is active. When the criteria for the alarm have returned to normal state, the pump starts again automatically.

Best efficiency point

Best efficiency point is a function which require VFDs and RS485 communication to VFDs.

Pump valve

Time settings for individual valve for each pump.

Pump Tag name

Give the pump a name, maximum 11 characters

2.6 Set log settings and events

There are 32 configurable analog log channels on the EC 541. It is recommended to use the log channels in sequential order from channel 1, as having log channels disabled between active channels will cause unnecessary data traffic to the surveillance system.

The logs are kept in the controller for 31 days and the oldest will be deleted when the memory is full.

The settings are:

- Log signal
- Log function
- Log interval

There are 39 Log signals which can be logged. The Log functions can be set as follows:

- Closed
- Actual value
- Average value
- Min. value
- Max. value

Closed: No logging.

Actual value: A momentarily value will be stored at the log sequence.

Average value: An average value during the log interval will be stored.

Min. and max. value: The min or the max value in the interval will be stored.

The log interval can be set from 1 minute to 65535 minutes.

Table 2.6

| Log signals |
|------------------------|
| Level pit |
| Inflow pit |
| Outflow pit |
| Overflow level |
| Overflow flow |
| Outlet pressure |
| Motor current |
| Pump capacity |
| Power factor |
| Temperature motor |
| Temp. stator wiring L1 |
| Temp. stator wiring L2 |
| Temp. stator wiring L3 |

Table 2.6

| Log signals (cont.) |
|-----------------------|
| Temp. upper bearing |
| Temp lower bearing |
| Vibration |
| Main voltage |
| Main frequency |
| Free choice AI |
| Free choice RTD |
| Power supply |
| Pulse channel 1-4 |
| PID control output |
| Data register |
| Data register 2-compl |
| Set frequency |

Table 2.6

| Log signals (cont.) |
|------------------------------|
| Actual frequency |
| Motor power |
| Torque |
| Outflow meter |
| PCB temperature BlueLinQ Pro |
| BEP frequency |
| BEP efficiency |
| Mains power |
| Actual head |
| Secondary pit level |
| Pit level difference |
| Free choice AI |

Events

Event list stores individual events such as pump starts / stops, alarms, alarm types and when the alarms occur and when it was acknowledged. The controller stores 4096 time-stamped events.

The event list is always active for alarms. To activate event list for pump starts / stops, **Settings – Common P1-P6 – Log pump events - Yes**

2.7 Set up communications to surrounding units VFD, soft starters and energy meter

See installation guide how to connect the surrounding units. Note that all the surrounding units must have unique Modbus IDs and same communication parameters.

BlueLinQ Pro controller has BIAS-jumpers for high and low signals which by default are active in the controller. If any of the other units also have this BIAS feature, it can be necessary to take out the BIAS-jumpers from BlueLinQ Pro controller. Consult the manuals for all units connected to RS485 bus if there are other units using BIAS pull-up / down resistors.

2.8 Set up cleaner, mixer or drain pump (if used)

If using cleaner, mixer or drain pump, a corresponding digital output must be configured.

Cleaner:

The settings for cleaner are to be found:

Settings – Pump pit – Cleaning control

The cleaning can be done at pump start or at pump stop.

Running time in seconds.

Start counter interval is how many starts / stops before cleaning starts.

Mixer:

The settings for Mixer is to be found:

Settings – Pump pit – Mixer control

The mixer can be started after a certain number of regular pump starts or after a time interval. There is also a criterion to set the level to be within a certain span. The mixer run time must also to be set.

The mixer status is visibly on the main screen on BlueLinQ Pro.

Drain pump:

A drain pump requires a start float to be connected to a digital input which is configured with the start float drain pump option. The setting for drain pump is to be found:

Settings – Pump pit – Drain pump control

The Drain pump starts on a digital input configured as Start drain pump. Drain pump runs only on time settings, there is no stop float for the drain pump. A digital output must also be configured as Drain pump control.

3 Detailed descriptions of the functions

In this section we will explain more in depth how different functions work and how the controller calculates flows. Explanations will also be given for different input and output types.

Each chapter contains examples on how to configure functions in the controller and in some cases, where to find the settings when using Aquaprog.

3.1 Pump capacity calculation

This covers the importance of choosing the right scaled level sensor for the application, shape and size of the pump pit, pump curve and the parameters for each pump which must be set.

3.2 Overflow flow calculation

Here is explained the number of ways to calculate overflows and how it can be detected by the controller. Also lists the advantages and disadvantages of the different calculation methods used to detect overflows.

3.3 Pump alternation

Describes the different options, normal-, asymmetrical- and runtime alternation. The max number of pumps running is also explained here.

3.4 Pump reversing

Pump reversing is explained and what criteria are used by the controller to reverse the pumps.

3.5 Speed controlled pumps (VFD)

How to setup a speed-controlled pump and how the PID regulator works.

3.6 Best efficiency point

Best efficiency point is a function which require VFDs and RS485 communication to VFDs.

3.7 Crash log

The crash log is explained here, and how to read out the crash log from the controller.

3.8 Communication

Describes the communication ports and how to set up communication to external system.

3.9 Cross reference table

How to setup cross reference table is explained here.

3.1 Pump capacity calculation

In the BlueLinQ Pro controller there are some crucial parameters which have to be set for accurate calculation of in / outflow and pump capacity. We will describe each parameter in general terms later in this document. The parameters considered for pump capacity calculation in the controllers are:

- Level sensor
- Shape and size of the pump pit
- Pump curve
- Parameters under settings in Calculation of pump capacity
- Option: outlet pressure sensor

Level sensor:

There must be a level sensor or an accurate level measuring device (from now on referred as: level sensor) present in the system so the controller can track the level and changes in level in detail. The sensor shall be connected to an analog input signal, normally "Ain:1" which has the highest resolution. The analog input channel shall be scaled as the property of the sensor.

Note *The smaller span the level sensor has, the greater is the accuracy.*

Table 3.1: Accuracy of the level sensor to be expected

| The resolution of a flow calculation, based on a 1,8 m diameter round pit --> | | | | | | | | | | | | |
|---|---------|--|----------------------|------------------|----------------------|------------------|----------------------|-------------------|-----------------------|-------------------|-----------------------|---|
| Enter pit diameter in meters: | | 3,57 | | | | | | | | | | |
| Area m ² | | 10,00982 | | | | | | | | | | |
| Impact of the monitoring device technical capability | | | | | | | | | | | | |
| Bit | Digits | Resolution depending on range using a 0 – 20 mA input: | | | | | | | | | | Unit |
| | | 0 - 2 m in mm | 0 - 2 m in litres | 0 - 4 m in mm | 0 - 4 m in litres | 0 - 5 m in mm | 0 - 5 m in litres | 0 - 10 m in mm | 0 - 10 m in litres | 0 - 40 m in mm | 0 - 40 m in litres | |
| 10 | 1024 | 1,9531 | 19,550 | 3,9063 | 39,101 | 4,8828 | 48,876 | 9,766 | 97,752 | 39,0625 | 391,009 | Many older PLC's EC531 (Ain 1) PCx (Ain 1) |
| 12 | 4096 | 0,4883 | 4,888 | 0,9766 | 9,775 | 1,2207 | 12,219 | 2,4414 | 24,438 | 9,7656 | 97,752 | |
| 14 | 16384 | 0,1221 | 0,1221 | 0,2441 | 2,444 | 0,3052 | 3,055 | 0,6104 | 6,110 | 2,4414 | 24,438 | |
| 15 | 32768 | 0,0610 | 0,0610 | 0,1221 | 1,222 | 0,1526 | 1,527 | 0,3052 | 3,055 | 1,2207 | 12,219 | |
| 20 | 1048576 | 0,0019 | 0,0019 | 0,0038 | 0,038 | 0,0048 | 0,048 | 0,0095 | 0,095 | 0,0381 | 0,382 | |
| Impact of the monitoring device technical capability | | | | | | | | | | | | |
| Bit | Digits | Resolution depending on range using a 0 – 20 mA input: | | | | | | | | | | Unit |
| | | 0 - 2 m in mm | 0 - 2 m in litres | 0 - 4 m in mm | 0 - 4 m in litres | 0 - 5 m in mm | 0 - 5 m in litres | 0 - 10 m in mm | 0 - 10 m in litres | 0 - 40 m in mm | 0 - 40 m in litres | |
| 10 | 1024 | 2,4414 | 24,438 | 4,8828 | 48,876 | 6,1035 | 61,095 | 12,207 | 122,207 | 48,8281 | 488,761 | Many older PLC's EC531 (Ain 1) PCx (Ain 1) |
| 12 | 4096 | 0,6104 | 6,110 | 1,2207 | 12,219 | 1,5259 | 15,274 | 3,052 | 30,548 | 12,2070 | 122,190 | |
| 14 | 16384 | 0,1526 | 1,527 | 0,3052 | 3,055 | 0,3815 | 3,818 | 0,763 | 7,637 | 3,0518 | 30,548 | |
| 15 | 32768 | 0,0763 | 0,764 | 0,1526 | 1,527 | 0,1907 | 1,909 | 0,381 | 3,818 | 1,5259 | 15,274 | |
| 20 | 1048576 | 0,0024 | 0,024 | 0,0048 | 0,048 | 0,0060 | 0,060 | 0,012 | 0,119 | 0,0477 | 0,477 | |

Shape and size of the pump pit shape

In the settings in BlueLinQ Pro controller where it is possible to set the shape of the pit. To get an accurate calculation at all levels, the pit shape must be defined as the calculation is different for different geometrical shapes. A shape that ends in a point is set as conical; if it ends as a wedge (2 parallel sides) it is set as rectangular shape, see figures below.

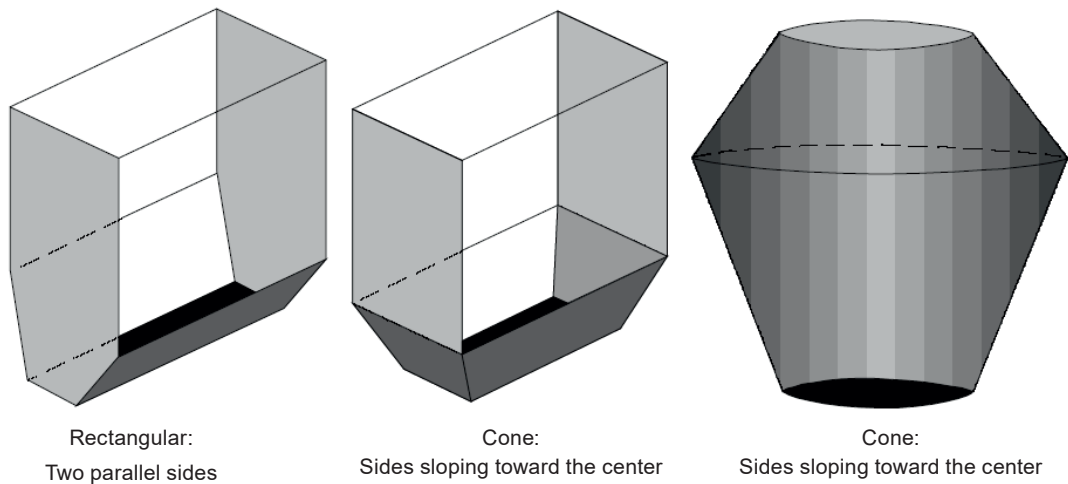


Figure 3.1: Pit shapes

Size of the pit

The continuous flow measurement is based on the fact that the BlueLinQ Pro can calculate the volume by measuring the level difference during a set calculation time. For this calculation to be accurate, it is essential that the area and the level should always be known. This can be achieved by setting the level and area for all levels where the pit changes shape, up to nine break points plus the area at zero point can be set. Those nine points shall be distributed along whole range of the pit up to the maximum fill level, with emphasis on areas where the pit shape changes form.

When the controller has the level sensor installed and it's correctly scaled, and the shape and size of the pit is known; the BlueLinQ Pro can easily calculate the volume. Any changes in the level are directly proportional to the amount of in / outflow and to the volume in the pit.

Pump curve

If you imagine a very deep pit or well, the out pumping from the pit is much easier when the level is very high. That's because the water pressure from the surface down to the pump "helps" the pump to lift the water. So in principle you can say that the pump lifts the water only from the surface and out – rather than from bottom and out. Depending on where the level is; the duty of the pump is shifting. Dependent on the motor and impeller type each pump will have a different Pump curve, see figure 3.2. From the pump curve three points within the range where the pit will operate can be taken, these three points are named as Hmax, Hmid, Hmin and stands for Total head max, Total head middle and Total head min. Check the Sulzer software ABSEL for the pump curve for your pump.

In BlueLinQ Pro controller (EC 541)

Under settings for each pump it is possible to set three points for the Pump curve and it's flow at the given points; Head (max); Head (mid) and Head (min) which correspond to Hmax, Hmid and Hmin. Total head can also be configured as a fixed value. If there is an Outlet pressure sensor in the system, then the Total head value is replaced in the calculation with the value from the outlet pressure sensor as Actual static head.

Typical the mid value is the best BEP and recommended operating range define Hmax and Hmin.

Hmax: (at pump outlet to pit outlet); is the highest lifting point and lowest level in the pit. At this point the pump has hardest load and is least efficient.

Hmin: (the highest point the surface of the level can reach; to the level of overflow etc.); is the highest level the pit can reach and lowest lifting point for the actual system and most efficient pumping.

Hmid: is a value somewhere in between Hmax and Hmin.

If sensor is mounted according to figure 3.3 below in example 1 where the pit bottom is 0.4 m below pump outlet, set parameter **Total head zero level = 18 + 0.4 = 18.4 m.**

Type in pump curve parameters in BlueLinQ Pro:

In the menu of BlueLinQ Pro:

Settings – Pump X (X = Pump 1–6) – Pump curve (QH)

- Point 1 head (max) = X.XX m (ft.) There XX is manually replaced with new value
- Point 1 flow (min) = X.X l/s (gal./min)
- Point 2 head (mid) = X.XX m (ft.)
- Point 2 flow (mid) = X.X l/s (gal./min)
- Point 3 head (min) = X.XX m (ft.)
- Point 3 flow (min) = X.X l/s (gal./min)
- Total head = X.XX m (ft.)

Example 1

A pit where the pump(s) has the lifting height of 18 meter from the pump outlet to pit's outlet. Therefore the H_{max} is 18 meters. We have also an overflow outlet 5 meters from the pump(s) outlet where the overflow sensor is placed. The level can never be higher than 5 meters. H_{min} is then $18 - 5 = 13$ meter and H_{mid} is 15.5 meter, see figure 3.2 below.

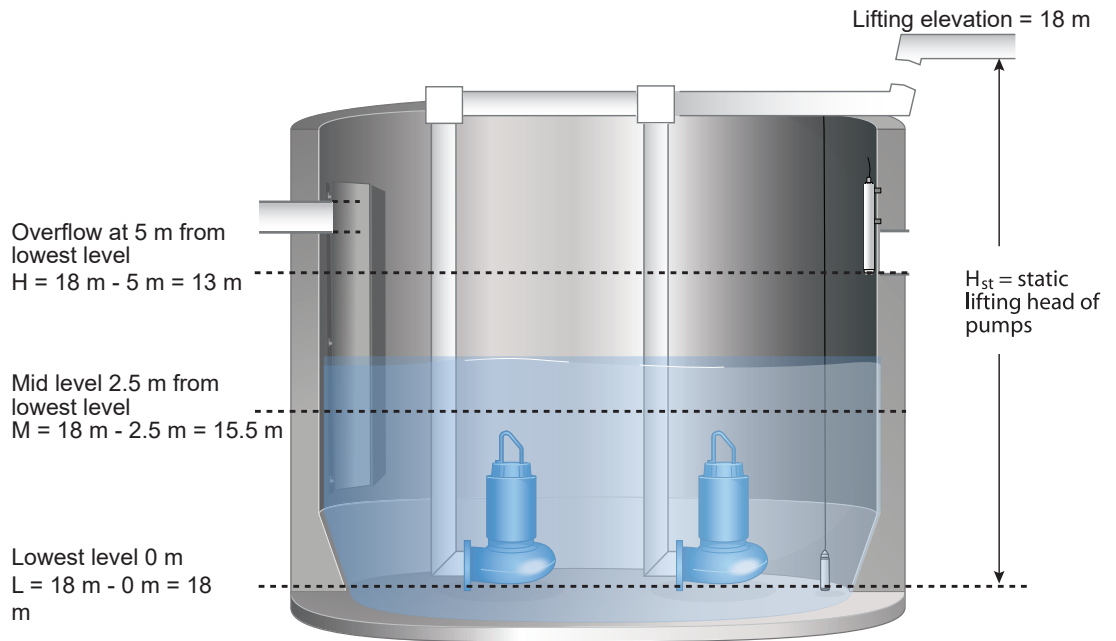


Figure 3.2: Explanation of H_{max} , H_{mid} and H_{min}

From pump curve, we can find the corresponding flow rate for each of; H_{max} , H_{mid} and H_{min} .

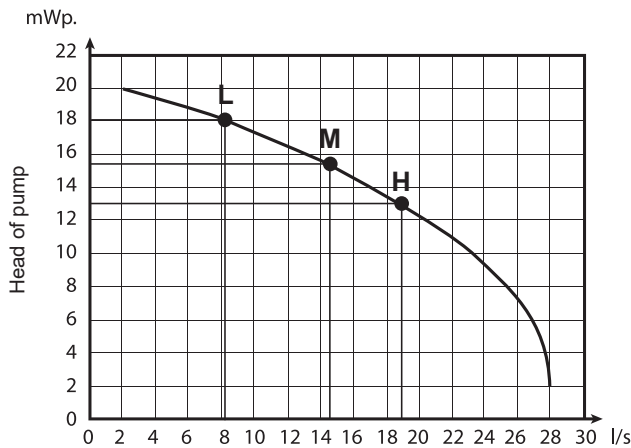


Figure 3.3: H_{max} , H_{mid} and H_{min} in the chart

Actual static head

If using an analog input sensor allocated as Outlet pressure, on the outgoing mains the value of Total head is replaced with value from the sensor in outlet and pump capacity calculations. Actual static head makes the calculation much more accurate than a fixed value for Total head in the settings for each pump

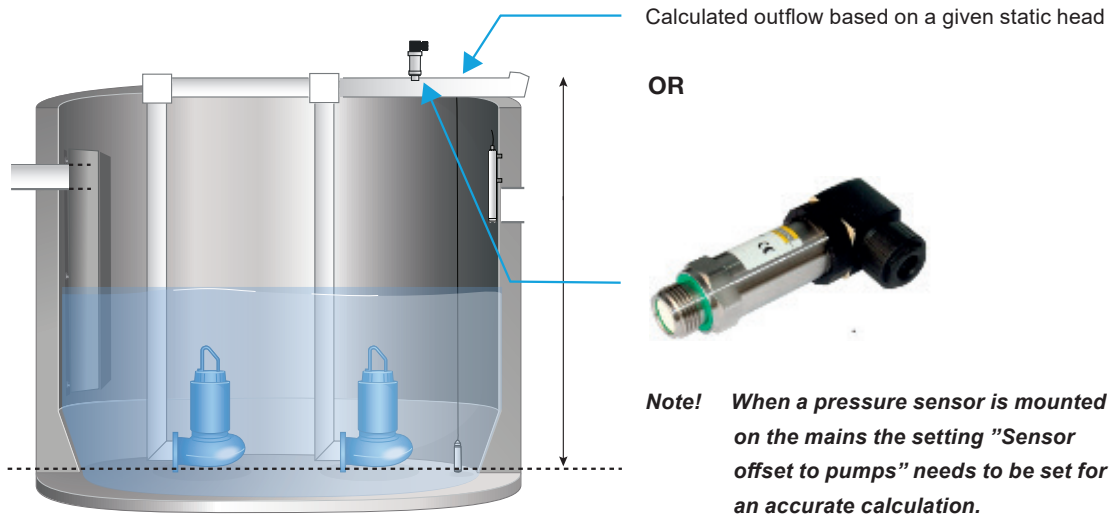


Figure 3.4: Actual static head explained

A pump is almost always used in a system of pipelines and valves. These give losses that the pump must overcome for a specific flow. The outlet pressure sensor gives the sum of the dynamic height and pipeline system losses at a specific flow (total head). It could be assumed that if two pumps of the same type are running in parallel then the outflow would increase by two, however sometimes due to the increase in back pressure the outflow will increase by less than this. This is because the pipeline losses increase with increased flow and higher back pressure thus the total lift height. If you do not compensate for this, the calculation of the output flow and pumped volume will be less accurate in the case of several pumps running. This is especially true when we have large pressure losses in the pipes in relation to the static height. This can happen, for example, when several pump stations are working in the same pipe system or if the pipes are partially blocked or if air entrapment occurs. An outlet pressure sensor considers all this.

As in the general description of the pump curve above, the back pressure is dependent on the level in the pit, but also on the flow rate in the pipes, number of pumps running and the outlet pressure. We have two ways to handle this; by Flow compensation and or use an Outlet pressure sensor.

Flow compensation has fixed calculation factors depending on the number of pumps running which is multiplied with the pump capacity for each pump but does not consider the level, flow rate and outlet mains-pressure.

Outlet pressure sensor considers the level, pressure on the outlet, the number of pumps running, pump capacities and pipe losses.

Therefore, with an outlet pressure sensor the calculation is much more accurate compared to using only the Flow compensation and a fixed value for static head.

Calculations

Inflow

If the controller knows the shape and size of the pit and together with a level sensor; the unit will at all times know the momentary volume of the pit and its inflow.

Pump capacity

A pump capacity calculation is performed every time the pump starts alone with no other pump running. If two pumps are running, the BlueLinQ Pro Controller will not perform any new calculation and will use the existing nominal pump capacity for the outflow calculation.

Important parameters to perform automatic calculations of pump capacity

All the important parameters for pump capacity calculation are to be found in the menu of BlueLinQ Pro Controller under:

Settings – Pumps – Common P1-P6 – Calc. pump capacity

- **Calculation ON / OFF:** must be ON (default OFF)
- **Min. level for calculation:** default 0.30 meter
- **Start delay:** default 10 sec.

- **Calculation time:** default 5 sec.
- **Stop delay:** default 5 sec.
- **Max. level for calculation:** default 3.00 meter

Note: *It may be necessary to adjust above parameters for accurate measurement of the capacity.*

Pump capacity calculation rules

- Only one pump is allowed to run during the whole sequence, otherwise no new calculations will start.
- The level must be over “Min level for calculation” during the whole calculation sequence .
- The level must be under “Max level for calculation” during the whole calculation sequence.
- The level after calculation must be lower than when the calculation started.
- The Calculation delay time must be long enough for the pump to reach full speed and for the water to reach full velocity in the pipes.
- All the times in Calculation delay + Calculation time + Stop delay must be in one and the same. pump sequence

When one pump starts alone

- The actual indicated inflow value is frozen when the pump starts and is temporarily stored in BlueLinQ Pro.
- The outflow is now ramped up for a configurable time frame set in settings for “Start delay”.
- When the pump is running at full speed and the water has full velocity in the pipes after the “Start delay”, the pump capacity is calculated over the time defined in the “Calculation time” setting.
- After the “Calculation time”, there is a “Stop delay” and when this time has passed, the inflow value is updated again.
- The BlueLinQ Pro does this calculation five times for each pump, the two most divergent results are removed and an average of the three remaining results is taken to give the new pump capacity value.

Example of calculation cycle:

1. No pump is running, level increasing due to inflow that is then calculated based on the area/level and time settings.
2. Start level reached.
3. Current inflow stored.
4. Time delay before pump capacity measurement, this to enable the flow to pick up speed depending on size of pit, pump, head and collection network design.
5. Measure speed of level reduction during a preset time to a pump capacity value is now obtained.
6. This capacity value is now adjusted to the pump curve (if entered).
7. Release the inflow calculation.
8. The inflow is now a function of the pump capacity and entered pump curve.
9. If yet a pump starts the outflow and inflow is then also adjusted according to the system curve.
10. If a pump is running and there is a stable level reading, this would indicate that the inflow matches the outflow.
11. If the level increases, it indicates that the inflow is higher than the pump capacity and the calculation is rejected.

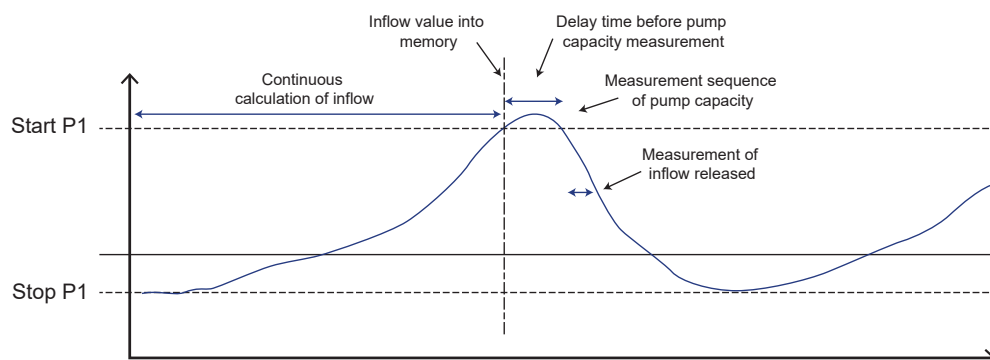


Figure 3.5: Pump calculation explained

Increased calculation accuracy

To improve the calculation accuracy and alarm handling, especially with varying start levels we recommend that the pump curves are entered. For a more accurate outflow calculation, the use of an outlet pressure sensor is recommended in the system. In this case the BlueLinQ Pro will recalculate and adjust the outflow calculation based on the momentary level.

Presentation of the pump capacity calculation

The pump capacity is presented as Pump capacity and Last sample value in BlueLinQ Pro Controller

Pump capacity

The nominal pump capacity is calculated from five readings of a single point on the "Pump curve". From these five values the two most divergent are removed and the average of the three remaining give the pump capacity.

Last pump capacity:

As it sounds, the last calculation, unfiltered and without compensation for Pump curve and it is just a raw value. Five of the "Last pump capacity" -values will create a new Pump capacity-value after all other parameters which are involved are set as described above.

In order for the BlueLinQ Pro to change the calculated Pump capacity (nominal-) value, there has to be five starts and stops for each pump and that pump must have been running alone those times.

Outflow

The internal outflow calculations are closely linked to the pump capacity calculation. When the pump starts and the running indicator is on, the BlueLinQ Pro Controller calculates the outflow by multiplying run time with the capacity of the pump(s). The calculation will also take into account the Pump curve, Outlet pressure and number of pumps running. If there is an analog input assigned as Outlet pressure sensor in the system, the Total head-parameter in the calculation is replaced with the value from the outlet pressure sensor.

If there is an analog input assigned as Outflow meter, BlueLinQ Pro Controller will ignore internal calculation of the outflow and only store the value from outflow meter. Neither the pump curve nor outlet pressure is in the value of outflow when using an Outflow meter

Example 2

How to read out the expected pump capacity based on the mains pressure and actual basin level.

The figure below gives an estimated pump flow as at new conditions of approximately 26 l/s.

Estimated theoretical pump capacity at start level

Bar → m H₂O = 10.1972

Mains pressure = 1.95 bar → 19.89 m

Static head = 3 m

Start level = 0.5 m

Geodetic head = 0.5 m

Total head at start level =
 $19.89 + (3 - 0,5) = 22.39$ m

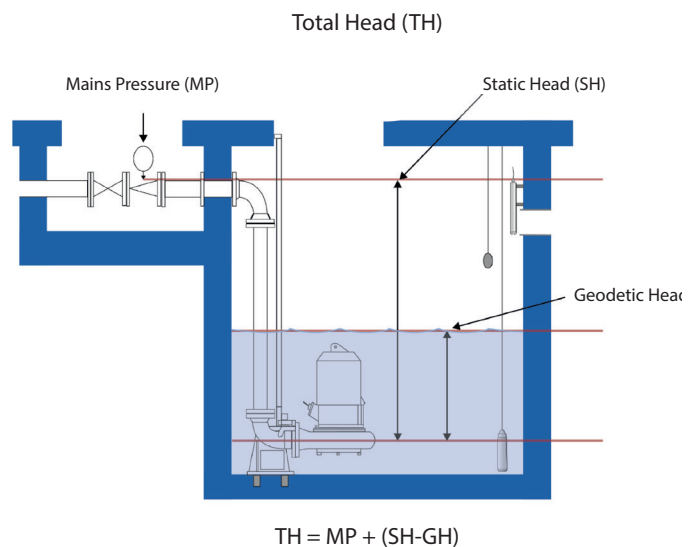


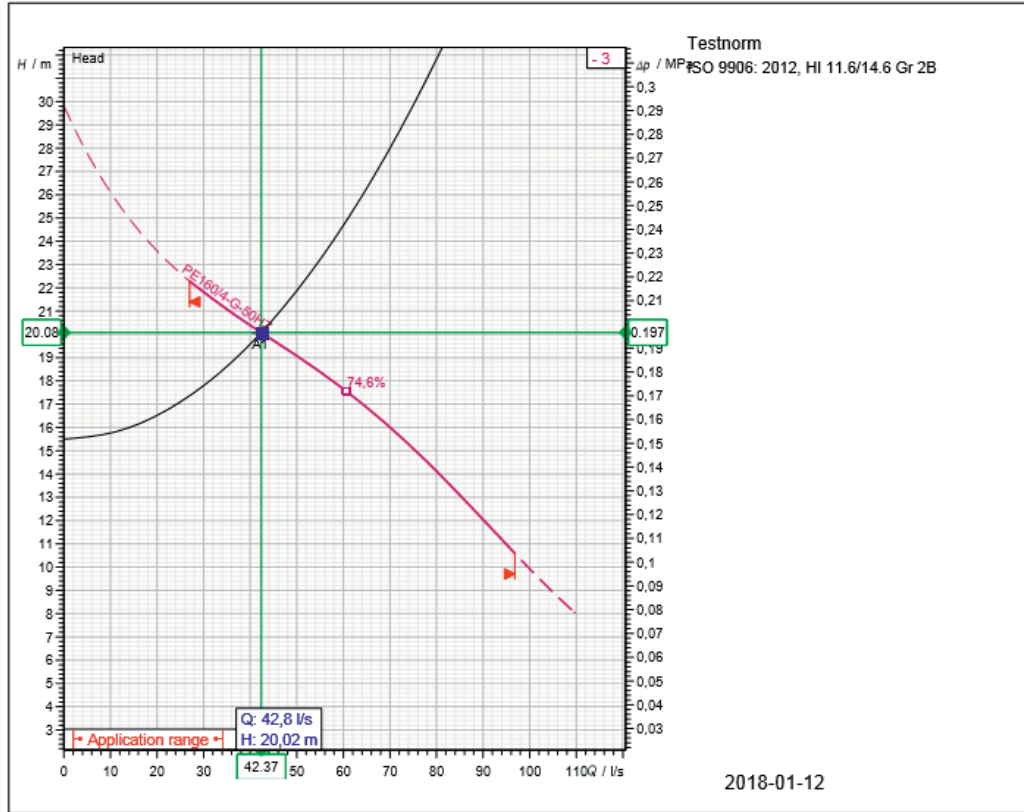
Figure 3.6: Relation between pump curve and the pit

In practice

A fictional station with two Sulzer pumps, XFP 150G CB1 50 Hz and a BlueLinQ Pro Controller. The data sheet for the pump:

SULZER

XFP150G CB1 50HZ



| | | | |
|-------------------------------------|-------------------------|----------------------|-----------------------------------|
| Operating data specification | | | |
| Flow | 42,4 l/s | Head | 20,1 m |
| Efficiency | 71,2 % | Shaft power | 11,7 kW |
| NPSH | 1,97 m | Fluid | Water |
| Temperature | 20 °C | Nature of system | Single head pump |
| No. of pumps | 1 | | |
| Pump data | | | |
| Type | XFP150G CB1 50HZ | Make | SULZER |
| Series | XFP PE1-PE3 | Impeller | Contrablock Plus impeller, 1 vane |
| N° of vanes | 1 | Impeller size | 275 mm |
| Free passage | 100 mm | Suction flange | DN150 |
| Discharge flange | DN150 | Type of installation | Not chosen |
| Moment of inertia | 0,104 kg m ² | | |
| Motor data | | | |
| Rated voltage | 400 V | Frequency | 50 Hz |
| Rated power P2 | 16 kW | Nominal Speed | 1470 1/min |
| Number of poles | 4 | Efficiency | 92,2 % |
| Power factor | 0,758 | Rated current | 33,1 A |
| Starting current | 317 A | Rated torque | 104 Nm |
| Starting torque | 440 Nm | Degree of protection | IP 68 |
| Insulation class | H | No. starts per hour | 15 |

Sulzer reserves the right to change any data and dimensions without prior notice and can not be held responsible for the use of information contained in this software.

Spaix® 4, Version 4.3.4 - 2017/03/02 (Build 578)
Data version Mar-2017

Figure 3.7: Example of data sheet

Data from graph

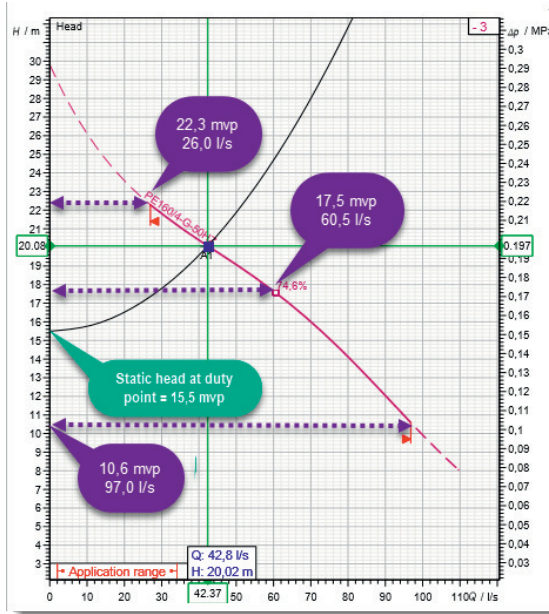


Figure 3.8: Example from a data sheet

Settings / Pump 1 / QH curve (pump curve)

Pump curve (QH)

- 1.34 Point 1 head (max) = 0.00 m
- 1.34 Point 1 flow (min) = 0.0 l/s
- 1.34 Point 2 head (mid) = 0.00 m
- 1.34 Point 2 flow (mid) = 0.0 l/s
- 1.34 Point 3 head (min) = 0.00 m
- 1.34 Point 3 flow (max) = 0.0 l/s
- 1.34 Total head = 0.00 m
- 1.34 Pump curve Q-H exponent = 0.0000

Note: If not using an outlet pressure sensor – a value for Total head must be given; in this case: 20.1 m

| | | | |
|--|--|---|--|
| <p>Operating data specification</p> <p>Flow 42.4 l/s</p> <p>Efficiency 71.2 %</p> <p>NPSH 1.97 m</p> <p>Temperature 20 °C</p> <p>No. of pumps 1</p> | | <p>Head 20.1 m</p> <p>Shaft power 11.7 kW</p> <p>Fluid Water</p> <p>Nature of system Single head pump</p> | |
|--|--|---|--|

Figure 3.9: Example from a data sheet

Other parameters needed for the flow calculation set-up:

Settings / Station flow / Pit area

Station Flow

- Meas. Parameters
- Pit Area
 - Level 0 = 0.00 m
 - Area 0 = 10.0 m2
 - Level 1 = 4.70 m
 - Area 1 = 10.0 m2
 - Level 2 = 2.00 m
 - Area 2 = 0.0 m2
 - Level 3 = 0.00 m
 - Area 3 = 0.0 m2
 - Level 4 = 0.00 m
 - Area 4 = 0.0 m2
 - Level 5 = 0.00 m
 - Area 5 = 0.0 m2
 - Level 6 = 0.00 m
 - Area 6 = 0.0 m2
 - Level 7 = 0.00 m
 - Area 7 = 0.0 m2
 - Level 8 = 0.00 m
 - Area 8 = 0.0 m2
 - Level 9 = 0.00 m
 - Area 9 = 0.0 m2

Pit area settings:

Up to nine different areas can be defined for different levels in the basin

STATION FLOW:PIT AREA

| | |
|---------|------------|
| Level 0 | 0.00 m > |
| Area 0 | 10.00 m2 > |
| Level 1 | 0.50 m > |
| Area 1 | 10.00 m2 > |
| Level 2 | 1.00 m > |
| Area 2 | 10.00 m2 > |

Figure 3.10: Examples from Aquaprog and menus

Station flow settings

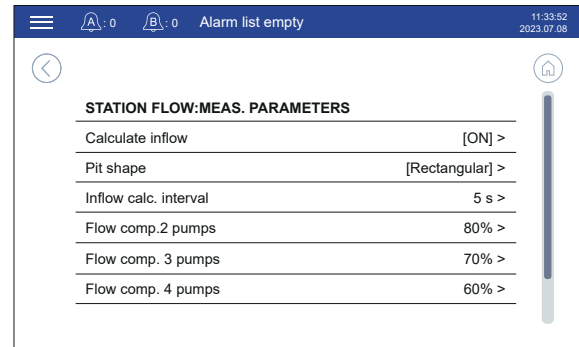
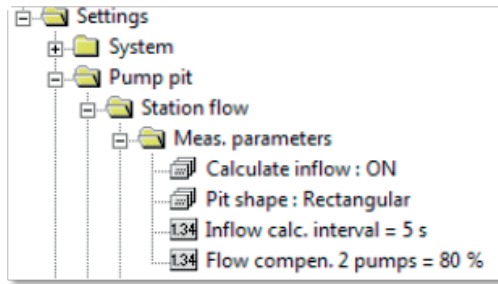
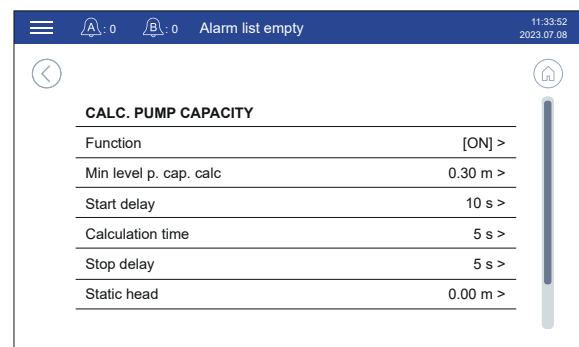
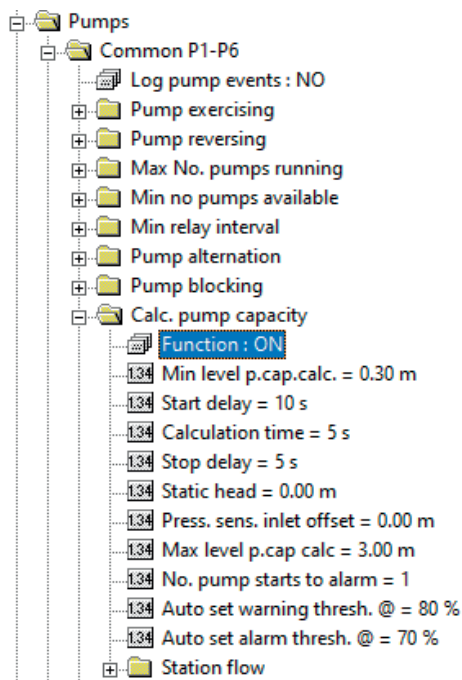


Figure 3.11 Examples from Aquaprog and menus

Settings of criteria for calculation of pump capacity



The level settings will set boundaries for the possible levels in the basin where calculations can be conducted.

The start delay time is a crucial setting, verify that the flow rate in the pipe has reached full velocity before the calculation is executed.

Figure 3.12 Examples from Aquaprog and menus

Example from a run sequence based on a described set data in the BlueLinQ Pro shown in AquaWeb.

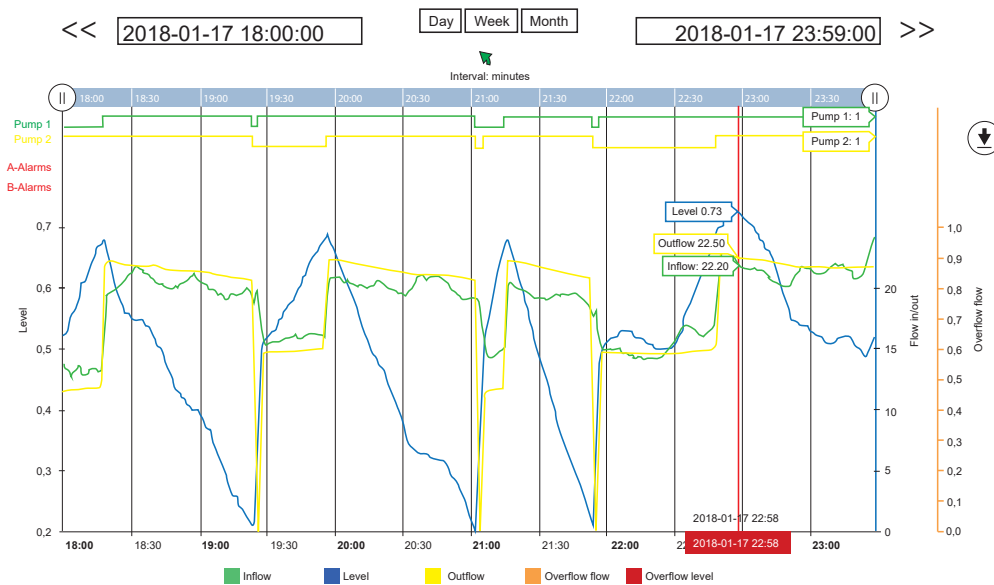


Figure 3.13: Example of Aquaweb chart

If the start delay time is set too short, the calculated capacity is often too low.

If the inflow value “jumps” at every pump sequence this is normally because of:

- Wrongly set calculation parameters
- Back flush valve not working correctly

3.2 Overflow flow calculation

There are three main methods that can be used to measure and calculate overflow rate:

1. Use a conventional flow meter.

Advantage: In most cases for standard PLC-systems this will increase the accuracy on the measurement.

Drawbacks: Expensive. Also during normal operating conditions, sensors which only measure overflow, can accumulate dirt which will affect their readings; therefore the sensor must be cleaned regularly to ensure accurate measurements.

2. Use the same sensor that is used for the level measurement in the pit remove and start the flow measurement on an analog set point.

Advantage: The investment cost is low, and the sensor will not need regular cleaning.

Drawbacks: The system must have very good resolution on the input to be able to measure the overflow correctly and a very accurate 0-point otherwise the measurement will be inaccurate.

3. Use the same level sensor that is used for the level measuring in the pit and use a level switch to start the overflow measurement.

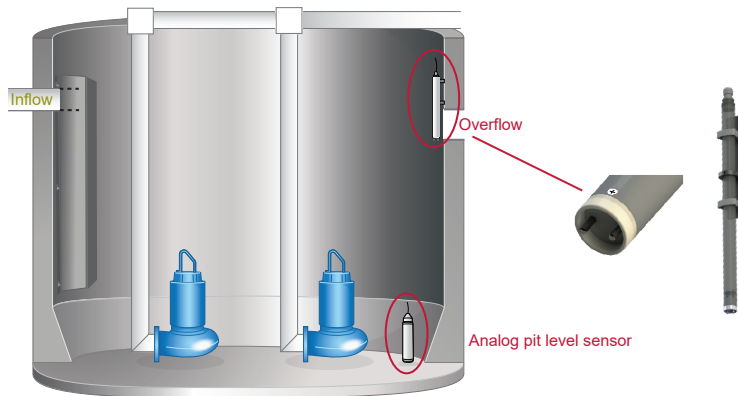
Advantage: The Investment cost is low and the sensor does not require regular cleaning. The accuracy of the 0-point does not affect the measurement as the switch is used as the 0-point.

Drawbacks: The analog input needs to have very good resolution to be able to measure the signal. The BlueLinQ Pro controller does not have this problem, for example a sensor with the range of 10 meters the BlueLinQ Pro controller has the resolution of < 0.7 mm.

Note: The third method is the preferred one to be used in the BlueLinQ Pro.

A digital overflow switch, like Sulzer MD 131 connected to a digital input indicates if an overflow is occurring independent of what the level signal shows. The BlueLinQ Pro locks this actual level and starts calculating the overflow level / flow from this value.

This means that the level is measured with a very high accuracy with an accurate 0- point. If an exact flow measurement is needed a weir or channel should be used.



The BlueLinQ Pro program has all the functions available for calculating flow in weirs and channels. Number of overflows, overflow time and overflow level and the flow are logged.

Figure 3.14: Pump pit with level and overflow sensor

The levels sensor is used as the actual level signal, when the switch is activated, it sets the 0- point for the flow measurement. If no level switch is connected to the BlueLinQ Pro the 0- point for the overflow can be set in:

Settings – Pump pit – Overflow – High level limit

Overflow / Overflow detect “manually”. Overflow will be registered when the level exceeds pre-set overflow level on the usual level sensor.

Note: *This set point has no function if a digital input (overflow switch) is set for overflow indication in the pump pit.*

A delay can be set to prevent disturbances or waves that could trigger the switch. After this delay the flow measurement starts and the time of the overflow is recorded. A counter keeps track of how many times the pit has overflowed. The overflow time is only triggered when the level is higher than the stored (set) 0- point. If a float sensor is used for a pump pit, which has no level sensor, the overflow time counts all the time the float is active.

Once the float goes back to normal, the overflow alarm will cease after the configured stop delay duration to avoid errors in the counter and to compensate for the start delay.

Note: *Overflow alarm and counter is only detected if alarm is enabled.*

How to calculate overflows by using constants and exponents

- In Settings – Pump pit – Overflow

you can type in the constant and exponents manually.

There are two different exponents and two constants which can be set in BlueLinQ Pro which are dependent on manufactures and nature of the weirs. Those constants shall normally be provided by the manufactures. If you don't have the e2 and c2 values, you can put e2 and c2 to 0 (zero), only use the left side of the equation. For the basic weir types, the c2 constant is set to 0 (zero).

Overflow= $he_1 c_1 + he_2 c_2$ [m3/s]

| Type of weir | Exponent | Constant |
|-------------------|----------|----------|
| Thompson 30° | 2.5 | 0.373 |
| Thompson 45° | 2.5 | 0.569 |
| Thompson 60° | 2.5 | 0.789 |
| Thompson 90° | 2.5 | 1.368 |
| Straight weir 1 m | 1.5 | 1.76 |

For other width on straight weirs, multiply the constant with the width in meters. Ex. $c = b * 1.76$ (b in meters)

Note: *If "Locked on inflow" is chosen, it assumes overflow will be the last calculation of inflow in the pit minus the capacity of the pumps which are running.*

3.3 Pump alternation

The BlueLinQ Pro has three different methods in order to alternate pumps.

1. Normal alternation

Pumps are started alternately according to a rotating schedule. The pump that started first in the previous pump cycle, will start last in the next cycle. In this way the running time is divided equally between alternating pumps. Pumps that are not set for alternation, start and stop at their own defined levels.

One can choose that alternation occurs at each pump stop or when all pumps are stopped.

It is preferred that alternation at each pump stop is used when the inflow is so high that the pumps don't have enough capacity to fully empty the pit. This prevents the situation where one pump is running continuously.

It is preferred that alternation at all pumps stopped is used when the inflow is such that the pumps have enough capacity to fully empty the pit.

2. Asymmetrical alternation

It is possible to set a pump to be the main pump and let the other pump run less in time. This is to save one of the pump so that the maintenance does not occur simultaneously on both pumps, which avoids a total stop for the entire station.

P1 run time ratio = 70% - means that the pump 1 will run 70% of the time.

3. Runtime alternation

The pumps can also be alternated based on continuous runtime. At exceeded maximum run time the pump will stop and an alternative pump will be started. The pump will only stop if the other pump is available and ready to run.

Max. number of pumps running

If the piping system cannot take the pressure when two pumps are running there is a possibility to set the max. number of pump that is allowed to run at the same time to one. It could also be used when there is a limit for the power load in the station.

If max. number of pump is set to one the system will not allow the other pump to start. A pump is running when the relay of the pump is activated or there is a run confirmation from the pump.

If max number of pump is running and the run confirmation is lost or some other errors that block the pump occur. The following will happen.

- Alarm for the error will be indicated.
- The faulty pump stops.
- If alternation is active, after a delay the other pump will be start.
- If alternation is not active the other pump will start at the next start level.

3.4 Pump reversing

The reverse pumps may be triggered on

- Digital input "Pump fail"
- Tripped motor-protection
- High motor current
- Low capacity
- After number of pump starts

- In Settings – Pumps – Common P1-P6 – Pump reversing

These are the events that can trigger pump reversing

1. Reverse on Pump fail

Reverse cycle start when digital input signal Pump fail goes active.

The signal must go back to inactive state before the pump start reversing, if not reversing cycle is aborted.

2. Reverse on Fallen motor-protector

Reverse cycle start when the digital input signal Motor protector goes active. Motor protector will be reset before the pump start reversing. You must enable auto reset motor protector function for the pump. Set the cold down time and pulse time in the auto reset menu. If the motor protector reset fails reversing cycle is aborted.

3. Reverse on High current
Reverse cycle start when alarm for High motor current is activated. For this function to work you need to enable the alarm in the pump alarm menu. Use the alarm delay time to delay the start of reversing (don't trigger on pump start current).
4. Reverse on Low pump capacity
Reverse cycle start when alarm for Low pump capacity is activated. For this function to work you need to enable the alarm in the pump alarms menu. After reversing the function is disabled until at least 10 new pump capacity calculations have been done.
5. Reverse on After number of pump starts
Counter for cyclic reversing of pump.

Other settings regarding pump reversing:

Settings – Pumps – Common P1-P6 – Pump reversing

- Set [**Reversing pump x**] to [**Yes**].
- Set [**Start rev. delay time**]. The time to hold the pump in off position before the start of pump reversing
- Set [**Rev. run time**]. The reversing run time.
- Set [**Max no. attempts**] After the reversing the pump will start again.
- Set [**Max attempts reset time**]
- Set [**Stop second pump**] to [**Yes**] if you want the other pumps to stop and stay blocked when reversing cycle run.
- Set [**Pump relay when rev.**]

If the pump fails again, a new reversing cycle will begin. Here you set max number of attempts. The reversing has succeeded if the pump has been running for the same time as the [**Start rev. delay time**] without any pump error. If successful the attempt counter is reset to 0.

If the attempts counter reach max number of attempts, an alarm will be generated and all further reversing stopped until motor protector alarm or pump fail alarm have been reset manually.

If [**Pump relay when rev**] is set to [**ON**], the pump relay will be activated 1 sec after the reversing re-ly and will be set to OFF 1 sec before the reversing relay goes off. Here pump relay is used to control the pump (**ON / OFF**) and reversing relay is used to shift two phases before reversing.

If [Pump rel. when rev] is set to [**OFF**] only the reversing relay is activated during reversing. Pump relay is always off.

3.5 Speed controlled pumps (VFD)

The BlueLinQ Pro has two Modbus RS485 interface which can communicate with VFDs. It is highly recommended to use this feature when there are VFDs in the system.

VFD pumps are mainly controlled by start / stop level and the digital outputs like fixed speed pumps. The best way to control the VFDs is via the RS485 bus which can control the speed, read the information from the pumps such as currents, speeds and loads. It is also possible to use the analog output signals to control the speed in VFD unit(s) which drive the pumps. Normal start and stop levels are used to start and stop the VFD pump(s). The built-in PID controller is used according to the con-stant level control method and outputs frequency set points to the VFD. The PID controller will raise the frequency when the water level tends to rise above the set level and lower the frequency when the water level tends to fall below the set level. In some cases, the control logic will override the output signal from the PID controller.

At start level the pump will always start at max frequency. Output signal is kept at max freq. until the set level is reached. If calculation of pump capacity is enabled the pump will run at max frequency, until the calculation is completed. If the pump is running at min frequency for an adjustable time you can set a force speed for pumping out the pit. The pump will go on force speed until stop level is reached (or set level).

If the pump is exercised, the pump will run on max frequency. When reversing the pump, the specified reverse speed value will be used (50% default). In high tariff pre pump down mode the pump will run on the same force speed as specified for min freq. timeout.

If there is more than one pump connected to VFD, the pumps will be synchronized. The output signals will always be the same if the scaling is the same. The VFD is responsible for speeding up and down the pump. BlueLinQ Pro controller doesn't handle ramp times. The min and max frequency for the pump normally is set on the VFD. The PID controller also has adjustable min and max value for the output signal that can be used.

There is a possibility to run VFD pumps with two different set points connected to, day and night settings. PID operator settings are found under:

Settings – PID controller

Setup BlueLinQ Pro controller for VFD pump(s)

In Settings – Pump x menu:

Set Type of pump to [VFD manual speed or VFD PID control or VFD best efficiently point] (see section 2.4 for explanations of different types). If a second VFD pump is used. Set the same type for that one.

In Settings / Pump x menu:

Set the start and stop level for the pump the start level should be higher than the set level on the PID controller. The stop level should be lower than the set level.

In Settings / Analog outputs / Analog output 1 menu:

Set output function to [PID controller].

The same for Analog output 2, if a second VFD pump is used, the output should be connected to the frequency input on the VFD

In Settings / Digital outputs;

Set output function [Pump relay] as for fixed pumps. The output should be connected to the "Run input" on the VFD.

In the Settings – PID regulator menu:

- External set point (On/Off)
If using external input for set point, specify the analogue input here or set to OFF.
- AI Module
Select AI module 1-9 if used
- Setpoint tracking (Yes / No)
Rarely used. Is that the internal setpoint follows the external that comes via an analogue input. When you then switch to the internal setpoint, it has the same starting value as the external (AI) had before wrapping. Is to prevent the setpoint from jumping to when switching between external and internal setpoint.
- Setpoint when start:
Last: last value, Setup start: start value, Extern: value according to specified input.
- Max set point and Min set point
Levels for the set point and a start set point. Here you can set max and min values to corresponding levels for the output signal (min / max freq). Value at Min level = 4 mA and Max level = 20 mA. What frequencies these correspond to depends on the settings in the VFD.
- Setpoint
Set point value
- Setpoint high tariff
The set point value at high tariff
- Start setpoint
Behavior when the controller is powered on
- Output state when start
Last state, Auto, Manual or Internally blocked. Only valid when the controller is powered up.
- Output when blocked
Freeze output or Setup block signal Behavior when the PID gets blocked
- Block output (%)
Percentage of output signal when blocked
- Max output change
The change speed of the output signal (%/s)

- Max output
Normally 100% (20mA)
- Min Output
Normally 0% (4mA)
- Start output (%)
Which output regulator should have after booting (e.g. after network interruption)
- Direct / Reverse effect
Direct: The pumps start at full speed and decrease in speed as the level decreases Reverse: The pumps start at low speed and increase in speed as the level decreases.
- P-band
Amplifying factor
- I-time (s)
Integration time
- D-time (s)
Derivation time
- Zero dev. output (%)
- Is which output regulator should when the Setpoint = actual value thus at zero-deviation normally not used (normally 0%). Mostly used for clean P regulation.
- Calc. pump cap. At max speed (Yes/No)
- Min speed (%)
Here you set the minimum pump speed
- Locked speed pumping out (%)
The speed of the pump when it has run for an adjustable time at lower speed and starts to pump out.
- Lock speed delay
If the pump is running at min frequency for an adjustable time you can set a force (lock) speed for pumping out the pit. If locked speed delay = 0 the function is disabled.

3.6 Best efficiency point pump control

Offers many advantages:

- Reduced energy cost
- Extended bearing life
- Longer maintenance intervals (slower degradation)

Instead of trimming impeller, a variable frequency drive is used to optimize performance. This is possible whenever actual operating point is on the right side of BEP in pump curve, the normal for most wastewater pump installations.

BlueLinQ Pro connects to most variable frequency drives with the RS485 Fieldbus for monitoring and control. With just a level sensor and a supported VFD attached, the pump will always run at the BEP.

By also setting up the pit area, required for pump capacity calculation, comparable data in engineering units opens for benchmarking between pump stations, and easy finding the worst behaviors and best pay-off of new improvements.

The BlueLinQ Pro is continuously searching for the best efficiency point to get out as many m³ water / kWh as possible.

Calculation is done every time a pump starts alone by calculating a new efficiency index and a new BEP in kWh/m³ from a snapshot of energy consumption and change in pit volume short after the set motor RPM is reached. Some conditions require full speed of the pumps. Following reasons can be configured in BlueLinQ Pro controller for full pump speed.

- Start at full speed every n (adjustable number-) of pump start for a preset time frame to flush pipes.
- At high inflow, if both pumps are running for a preset time.
- High level alarm

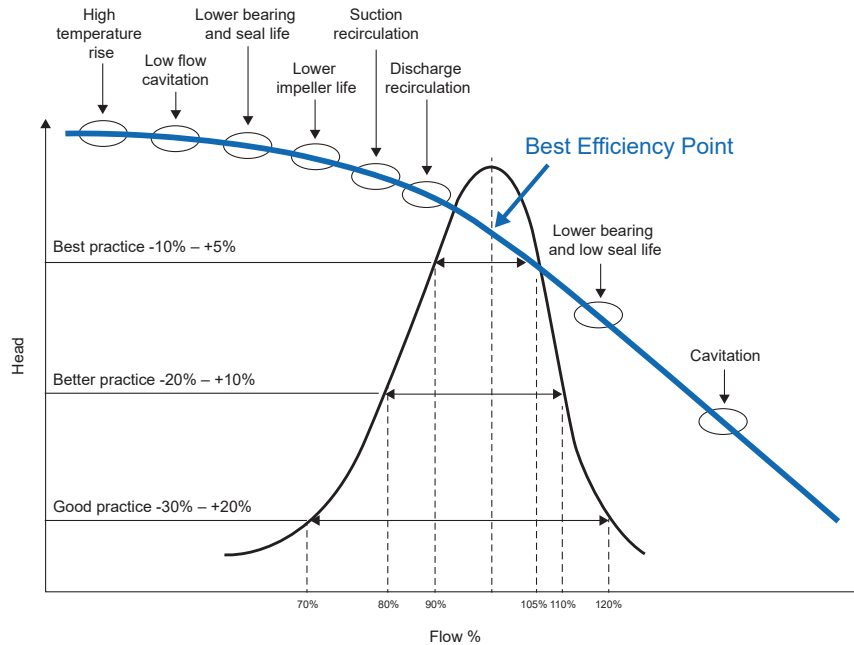


Figure 3.15: Example of a curve in BEP

3.7 Crash log

In case of any type of a severe equipment or station problem, a crash log can provide useful and detailed information in four different crash logs. This can provide us with the data needed to reveal problems not otherwise detectable in a normal 1-minute average log. Every alarm which can be configured in the controller, can also generate a crash log. The shortest interval for the ordinary logs is 1 min (60 sec.). The crash log has the interval of 1 second (not adjustable). When crash log initiates, the controller store values 6 minutes before the event and 2 minutes after the event which has triggered the crash log. The controller keeps the past four crash logs in memory and each crash block contains data for 480 seconds of 138 fixed log parameters. The four crash blocks are stored with a time stamp, ID no and alarm no for the trigger alarm.

The BlueLinQ Pro controller is continuously saving raw analog input data every second.

The data and up to four crash blocks are stored and can be retrieved to a PC with the AquaProg tool.

3.8 Communication

There are six ports for communication. One USB for updating firmware and uploading/downloading configuration, and one RS232 which can be connected to a modem or a protocol converter. One Ethernet and two ports for RS485 to surrounding units like VFD, soft starters and energy meters or to a SCADA. The protocols are Modbus RTU or Modbus TCP. If other protocols are needed to an external SCADA system, it could be available if there is an external converter from Modbus to the requested protocol. One CAN-bus to BlueLinQ Pro expansion units.

Modem port (terminals 18 – 22)

This port is designed for Sulzer 4G (CA 524 modem) communication and has protocol Modbus RTU or Modbus TCP. This port also supports CA 521 to send text messages. CA 524 can also send text messages (SMS).

Default this port has Modbus RTU,

Baud rate: 115200 Parity: none
 Handshake: off Protocol ID: 1
 Message time out: 2 s Optional: station name.

On this port it is possible to change the properties; baud rate (300 – 115200), protocol ID (1 – 255) and station ID (1 – 65535), parity (none, odd, even) and handshake (on / off) as well.

Note: The PIN code on the SIM card can be deleted with a cell phone.

GPRS modem

Sulzer modems CA 521 – CA 524 is based on internal TCP / IP stack in Cinterion (former Siemens) GSM / GPRS modules. All data access is via the Hayes commands are defined by Cinterion. Default is that the pump controller connects to the TCP server in Sulzer ABS AquaWeb system. Set PIN code if SIM card is equipped with one (deleted on AquaWeb SIM cards).

The heartbeat interval is set at 10 mins (default) but can be adjusted (lower interval may lead to extra costs). Server TCP port; must be the same as in GPRS server (default 2000 for AquaWeb). Servers IP address: the public / global IP (normally in fire wall / router) address to the GPRS / 3G server must be a static IP address. APN is provided by SIM card supplier. GPRS APN part 1 and GPRS part 2. If APN string is long, it can be divided between the two parts. (Default is AquaWeb APN). SMS fallback: 0046708728550 for AquaWeb only.

Settings under Communication – Modem port– Modem type in the BlueLinQ Pro should be set too.

Set GPRS username and password if demanded from subscription provider. GPRS event log and heart beat operator scan for error search only. Default 10 minute.

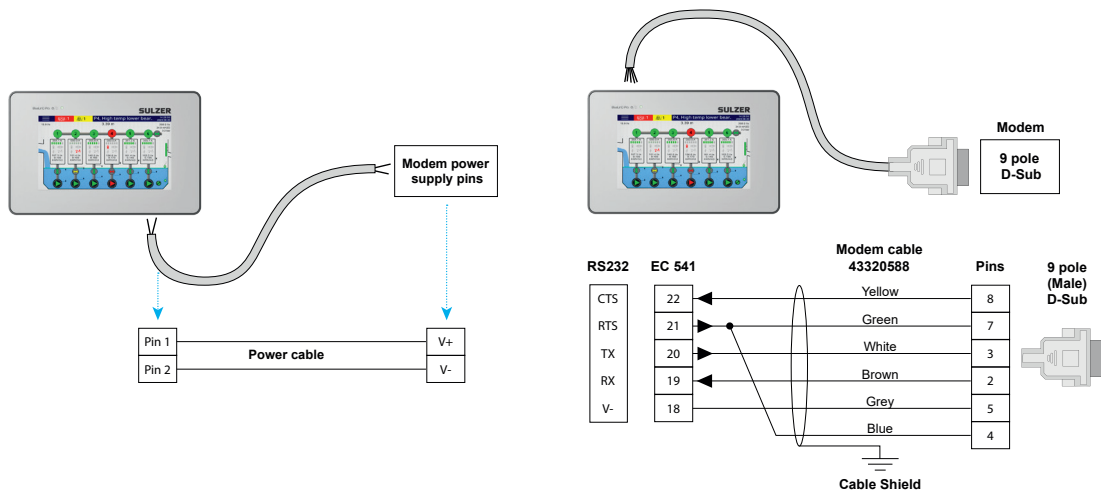


Figure 3.16: Connect BlueLinQ Pro to 9-pole D-Sub. Cable item no 43320588

TCP-Server

If you have a SIM card subscription with a fixed IP address, then you can connect the station by GPRS on a local network by using any of the CA-modems. Set the function in GPRS settings to TCP type server (fixed IP) which demands a SIM with fixed IP address from the provider on the station so that an external SCADA can contact remotely.

Settings under Communication – Modem – Modem type – settings GPRS in BlueLinQ Pro controller shall be set to [TCP type: TCP server (fixed IP)] or [TCP type: TCP server + heart beat].

Other types of modems

Profibus gateway and radio modems etc.

Connect CA-modem according to figure 3-16 to the com port on BlueLinQ Pro controller.

RS485 port (terminal 23-25 and 26-28)

There are two RS485 ports on BlueLinQ Pro controller for communication to surrounding units or to a SCADA-system. All the units in the RS485 network must be using the same communication parameters; baud rate, parity and stop bits. Compare the setting in the menu of BlueLinQ Pro and consult the manuals for surrounding units.

RS485 network is multi-drop which means that all units are connected in parallel on the same cable. In a RS485 network every unit must be connected in a line and have a unique address or Modbus ID-number. The RS485 bus shall be terminated with 120 ohms resistor at both cable ends. BlueLinQ Pro has a built-in jumper for end termination in terminal beside the connection terminals. The cable must be a shielded twisted pair cable.

The two RS485 busses on BlueLinQ Pro is galvanic isolated from the power supply and each other. If the surrounding units also have isolated communication ports, the common should be connected to ground potential in one point. The two ports operate independently of each other, so one port can work as a Master port, the other as Slave.

BlueLinQ Pro set as Master

If the BlueLinQ Pro is set to be the master in the RS485 network, all the surrounding units must be set as slaves. When BlueLinQ Pro act as a Master, the surrounding units can only be supported VFD's, Energy meters and Soft starters according to .

BlueLinQ Pro set as Slave

When BlueLinQ Pro controller is set as a "Slave" on the RS485 port, another master in the system request values from BlueLinQ Pro. The RS485 port act as communication port to a SCADA-system or similar.

USB port (USB type mini-B)

This port is only for updating firmware and upload / download configuration by using AquaProg.

RJ45 Ethernet port

BlueLinQ Pro controller has support for direct Ethernet communication through the RJ45 TCP / IP-port and handle up to 10 simultaneity connections.

In Settings – Communication – Ethernet port(TCP/IP)

Hardware [ON / OFF] Protocol [Modbus RTU or TCP]

Protocol ID, [1-255] Message timeout (1 sec, default)

Cross reference [ON / OFF] Port number (502 – default AquaProg)

Static / Dynamic IP (Dynamic DHCP – default)

When using only the TCP / IP port for communication, the modem port shall be set to OFF:

Communication – Modem – Modem connected [OFF]

BlueLinQ Pro controller has support for sending SMS simultaneously as Ethernet communications.

Field bus port (terminal 3-7 on BlueLinQ Pro controller)

The Field-bus port communicate with a CAN network interface. The protocol is unique for Sulzer and only Sulzers units can be connected to this bus. This CAN-bus is of multi drop type which means that all units are connected in parallel on the same cable. In a CAN network every type of unit must have a unique address or ID-number.

All the Sulzers different types of expansion units connected to the CAN-bus, have in a fact two bits addresses. The first byte is built-in in each module and can't be changed and says which type of module it is, and the second byte is the address switch in the front which can be changed.

3.9 Cross reference table

Cross reference table can be set-up in AquaProg to optimize the data flow in Modbus to the supervision system.

Register 0-254 can be defined to hold preferred data by a cross reference table and can be set for data for any register. See further information in Modbus register manual.

Together with the cross-reference table, it is possible to set an individual scale factor for each position in the cross-reference list, e.g running time in seconds can be rescaled to minutes with the factor 60. The scale factor can be between 0-32767, with the factor 0 no rescaling is done.

When reading data, the value is divided with corresponding scale factor. When writing data, the value will be multiplied with corresponding scale factor. Scale factor is ignored when set to 0. For data in double registers (32 bits), the highest register number should be used together with scale factors. Writing to the highest double register number will also set data in the lower register number if scale factor is set. If scale factor is set to zero, each register is handled individually. Many registers allow negative values (signed 2's complement data). This can cause some systems to treat negative data as large positive numbers (ex. -1 is read as 65535 by the system). To avoid these causing problems there is the possibility to individually set cross reference registers to only positive data. Negative values will give zero readout.

Note: *Cross reference tables are only available to configure in AquaProg. In the menus of BlueLinQ Pro controller you have the possibility to activate or deactivate the table on each port separately.*

Settings – Communication – [any port] – Cross ref; Set to [ON or OFF]

For the modem port:

Settings – Communication – Modem port – Settings GPRS – Cross ref; Set to [ON or OFF]

By using AquaProg you can also save and download your cross-reference table to any other BlueLinQ Pro controller units.

4. Further explanations of functions of the analog and digital input and output signals

4.1 Digital in: personnel alarm and local mode

This alarm is for the safety of service personnel. When digital input Local mode is set, a timer starts to elapse (Max time to reset). When timer has reached zero, a digital output can activate a connected buzzer or warning light to remind the service personnel to acknowledge their presence in the station by pressing any key on the controller. If the service personnel don't acknowledge the alarm within a certain time (Alarm delay), a callout will be done.

The Local mode input can for example be connected so that service personnel entering a station and turn on an indoor light (or similar) start the function

Required settings:

Setting – System – System alarms – Personnel alarm:

Type of alarm (A- or B-alarm) Max time to reset cyclic interval for personnel to acknowledge presence, typically 15-20 minutes Alarm delay: time between missed acknowledge and alarm call out, typically 120 seconds

Settings – In- & outputs – Digital input:

A digital input allocated as Local mode which is triggered by ta signal in the station (e.g. light switch) that indicates the service personnel is in the station. An active local mode signal will inhibit remote writing to most Modbus registers and IO-bits (USB and DSUB ports excluded). (Toggling of input signal Local mode or pressing key on display will reset alert timer Max time to reset.)

Settings – In- & outputs – Digital output:

Output signal Personnel alarm connected to a flashing light or buzzer can be used to get attention from the service personnel, to acknowledge the alert before an alarm goes active. (Toggling of input signal Local mode or pressing key on display will reset alert timer)

4.2 Digital in: block operation

This function enables a digital input to block the pump, mixer or drain pump. When the signal is active the pump / mixer / drain pump stops and blocks. The blocking will be released when the state of the input returns to a normal state.

4.3 Digital out: data register set point

A digital output can be configured with a Data register set point which can be associated with an internal or external analogue signal. By using the registers defined in the Modbus manual and entering them in the function as in the example below, you can achieve this function.

Example We have a sulfuric gas monitoring device connected to an analog input signal. We use first AI-module and last input, Ain:1:6 for the sulfuric meter. In this case we want a switch on digital output 1 on the first DO-module when the concentration of gas is equal to or above 10.0 ppm. We also want the output signal to switch off at 1.0 ppm (a hysteresis of 9 ppm). This digital output 1 controls a fan which evacuates the gas from the station.

The Modbus manual:

| 3.7 Analog IOs | | | |
|----------------|----|--|---------|
| Analog inputs | | Module 1-9 AI 1-6 | |
| Current | RO | Signed2030 +(signal number -1) +(Module number -1)*6 | 0.01 mA |

Figure 4.1: Above chart is an extract from the Modbus register manual

According to Modbus register manual, analog input number 6 on the first IO-module, have register number: 2030
+(signal number -1) +(Module number-1)*6 give us:

$$2030+(6-1)+(1-1)*6 = 2035$$

So register 2035 shall affect digital out 1:1 at 10 ppm to start a fan, and the fan shall stop at 1 ppm.

The property of the sulfuric meter is 20 mA at 20.0 ppm gas and 4 mA at 0.0 ppm. The start current from the sensor is then 12.0 mA and stop current at 4.8 mA.

The scaling of the modbus register is 0.01 mA gives 12.0mA the value 1200 and 4.8 mA gives 480. In Aquaprog it looks like this:

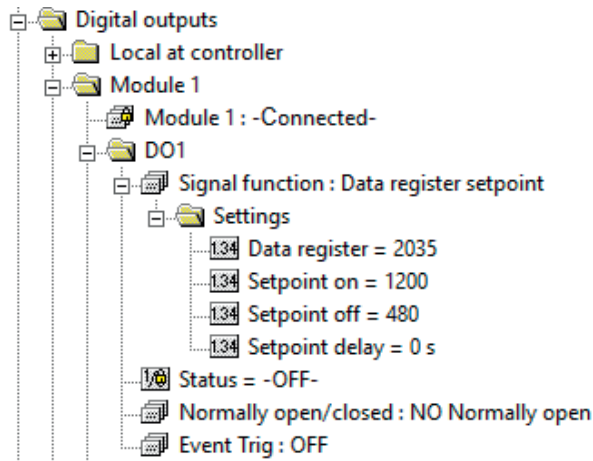


Figure 4.2: Data register setpoint example

4.4 Digital out: logic IO

One of the options in the functions of Digital out is **Logic IO**. This function is especially useful if you want to trigger an output signal when more than one criterion or events must occur to enable an output signal. There are up to four different criteria that can be used to trigger the output signal.

Those IO bits can be **Logical OR, NOR, And** or **NAND** functions or as a combination of these. The output signal can be set to Normally closed or Normally open (NC / NO).

This IO can be used to get a specific output signal from one or several indicators (up to 4 IO-bits). See table 4.1 below as an example of an output been driven by the state of 3 inputs.

4.5 Digital out: auto reset alert

Auto reset alert is active when a digital input is defined as Alarm reset. In the settings for Alarm reset input, there is a time delay value which can be set. This delay is the time the digital output Auto reset alert is active before the actual reset is performed.

Example The pumps are blocked because one or several alarms.

When pushing Alarm reset button, locally or remotely, which can imply that the pumps are about to start and there is a possibility of personnel being exposed to danger. The intention of this output is to give personnel a warning, if connected to buzzer or flashing light, that a reset of all alarms is about to happen, and the pumps might start.

4.6 Analog in: outlet pressure

If there is an outlet pressure sensor in the system, it will replace the system curve. Considering the backpressure, the level in the pit and the actual head. The signal from this sensor is recalculated into **Actual head** and used in the equation for the pump capacity calculation. This is a more accurate value for total head. When an outlet sensor is used, the total head parameter can be set to zero.

4.7 Analog out: data register and data register 2's complement

Data register

16-bit register from 0 to 65535. Only positive values. This type of register doesn't handle negative values. If there is a risk that the value could become negative, the register contains a very large value.

Data register 2's complement

16-bit register from -32767 to +32767. This type of register handles negative values.

With the analog output type data register, any analog signal, actual or calculated can be used as a 4-20 mA output signal. By using the registers defined in the Modbus manual and entering them in the function, you can achieve this function.

Example We want to have a 4-20 mA analog output signal tied to stator temperature L1 on pump 1. We also want the output signal to be 4 mA at 0°C and 20mA at 150 °C. We assume this temperature value never to be negative or goes below zero, even if the register type is "signed".

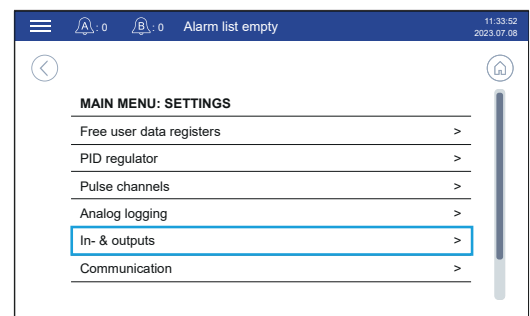
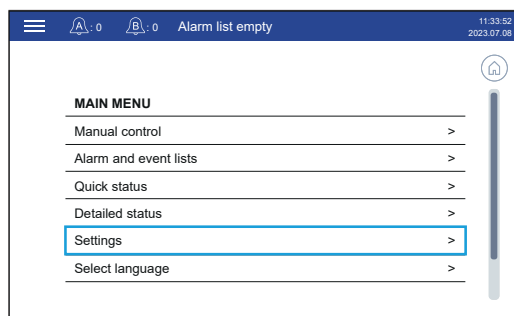
According to Modbus reference manual the temperature Stator L1 pump 1 is in register 703; see figure 4.3 below. We note as well that the scale factor is 0.1 (i.e. the value in reg.703 is multiplied by 0.1 to get accurate value in engineering units).

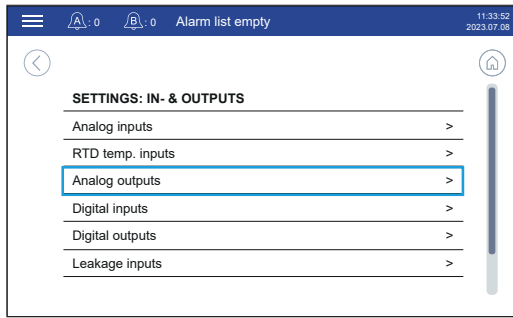
| Temperature | | | | | |
|---------------|----|--------|---------------------------|-----------------------------------|--|
| Stator L1 | RO | Signed | 703 +(pump number -1)*180 | 0.1 °C, 0.1 °F | |
| Stator L2 | RO | Signed | 704 +(pump number -1)*180 | 0.1 °C, 0.1 °F | |
| Stator L3 | RO | Signed | 705 +(pump number -1)*180 | 0.1 °C, 0.1 °F | |
| Upper bearing | RO | Signed | 706 +(pump number -1)*180 | 0.1 °C, 0.1 °F | |
| Lower bearing | RO | Signed | 707 +(pump number -1)*180 | 0.1 °C, 0.1 °F | |
| Generic | RO | Signed | 708 +(pump number -1)*180 | 0.1 °C, 0.1 °F | |
| Vibration | RO | Signed | 713 +(pump number -1)*180 | 0.1 mm/s ² , 0.01 in/h | |

Figure 4.1: Above chart is an extract from the Modbus register manual

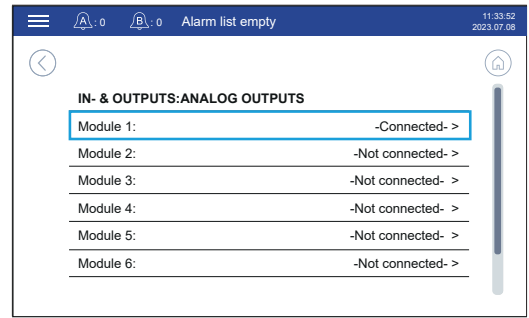
The function is setup in the BlueLinQ Pro menus according to figure 4.4 below;

Settings – In- & outputs - Analog outputs – Module 1 – AO1: – to [Data register] – Settings – Set data register = 703

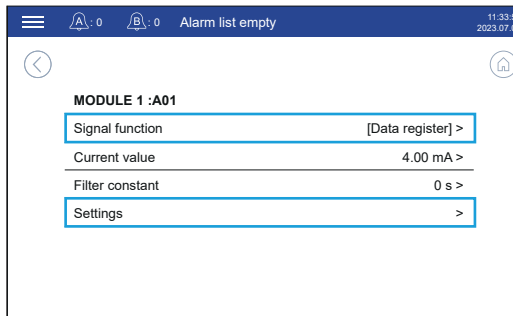




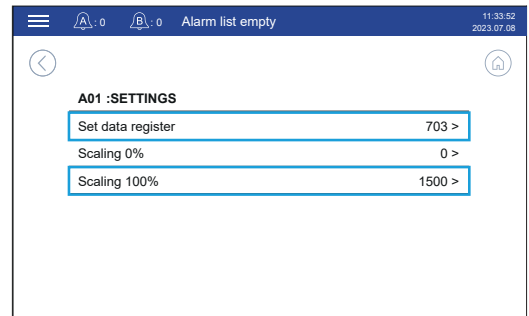
3



4



5



6

Figure 4.4 Data register setpoint example by the menus

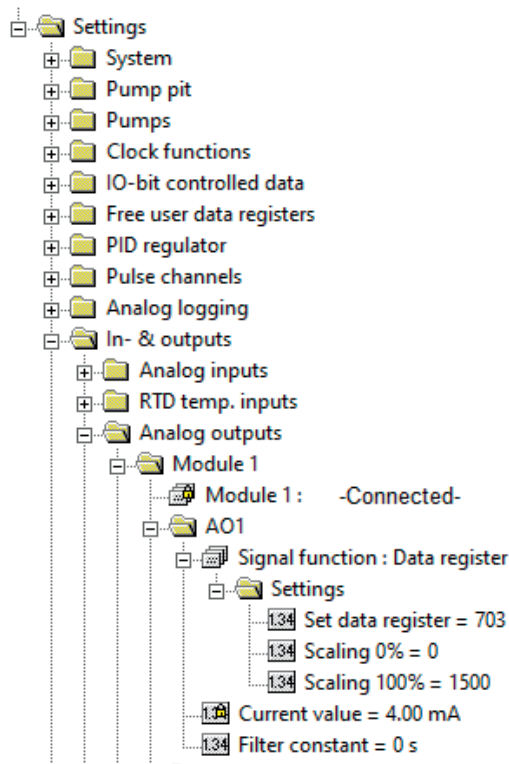


Figure 4.5: Analog output data register in Aquaprog

5. Appendix: BlueLinQ Pro Menu Guidelines

- 5.1 Manual control
- 5.2 Alarm and event lists
- 5.3 Quick status: System
- 5.4 Quick status: Pump pit
- 5.5 Quick status: Pumps
- 5.6 Quick status: Digital inputs
- 5.7 Quick status: Digital outputs
- 5.8 Quick status: Leakage inputs
- 5.9 Quick status: Analog inputs
- 5.10 Quick status: RTD temp. inputs
- 5.11 Quick status: Analog outputs
- 5.12 Detailed status: System
- 5.13 Detailed status: Pump pit
- 5.14 Detailed status: Pumps
- 5.15 Detailed status: PID regulator
- 5.16 Detailed status: Clock functions
- 5.17 Detailed status: Pulse channels
- 5.18 Detailed status: Inputs and outputs
- 5.19 Detailed status: Communication
- 5.20 Detailed status: Field bus modules (RS485)
- 5.21 Settings: System
- 5.22 Settings: Pump pit
- 5.23 Settings: Pumps
- 5.24 Settings: Clock functions
- 5.25 Settings: IO-bit controlled data
- 5.26 Settings: Free user data registers
- 5.27 Settings: PID regulator
- 5.28 Settings: Pulse channels
- 5.29 Settings: Analog logging
- 5.30 Settings: Inputs and outputs
- 5.31 Settings: Communication
- 5.32 Settings: Field bus modules (RS485)
- 5.33 Select language
- 5.34 Calibrate touch screen

5.1 Manual control

Table 5.1 shows the complete view for manual control.

Table 5.1

| Submenu | Submenu | Setting / Value | Comment |
|-----------------------|-----------------------|--------------------------------|-------------------------------------|
| Ackn. personnel alarm | | NO, YES | Status value |
| Pump1 | Manual start | NO, YES | Status value |
| | Pump reversing | NO, YES | Status value |
| | Fallen motor protect | NO, YES | Status value |
| | Reset motor prot. | NO, YES | Status value |
| | Reset temp. prot. | -OK-/ [YES], -Tripped- | Status value |
| | State of M-0-A switch | MANUAL, Pump not in auto, AUTO | Status value |
| | VFD frequency | 0.01 Hz | Status value |
| | Set manual frequency | 0.1 Hz | Status value |
| Pump2 | | | Menu selection, Identical to above. |
| Pump3 | | | Menu selection, Identical to above. |
| Pump4 | | | Menu selection, Identical to above. |
| Pump5 | | | Menu selection, Identical to above. |
| Pump6 | | | Menu selection, Identical to above. |
| Mixer control | Start/Stop | STOP, START | Status value |
| | Run indication | NO, YES | Status value |
| | Reset motor prot. | NO, YES | Status value |
| Cleaning control | Start/Stop | STOP, START | Status value |
| Drain pump control | Start/Stop | STOP, START | Status value |
| | Run indication | NO, YES | Status value |
| | Reset motor prot. | NO, YES | Status value |

5.2 Alarm and event lists

Table 5.2 shows the complete view for alarm and event lists.

Table 5.2

| Submenu | Submenu | Setting / Value | Comment |
|-------------------------|---|-----------------|--------------|
| Unackn. alarms | One or none of lines below, depending on port function. | | |
| | Special Menu | | |
| Active alarms | One or none of lines below, depending on port function. | | |
| | Special Menu | | |
| | One or none of lines below, depending on port function. | | |
| IO events | One or none of lines below, depending on port function. | | |
| | Special Menu | | |
| | One or none of lines below, depending on port function. | | |
| All events | One or none of lines below, depending on port function. | | |
| | Special Menu | | |
| | One or none of lines below, depending on port function. | | |
| Group alarm acknowledge | Ackn. all pump 1 alarms | NO, YES | Status value |
| | Ackn. all pump 2 alarms | NO, YES | Status value |
| | Ackn. all pump 3 alarms | NO, YES | Status value |
| | Ackn. all pump 4 alarms | NO, YES | Status value |

| Submenu | Submenu | Setting / Value | Comment |
|-------------------------|-------------------------|-----------------|--------------|
| Group alarm acknowledge | Ackn. all pump 5 alarms | NO, YES | Status value |
| | Ackn. all pump 6 alarms | NO, YES | Status value |
| | Ackn. all pump alarms | NO, YES | Status value |
| | Acknowledge all alarms | NO, YES | Status value |

5.3 Quick status: System

Table 5.3 shows the complete view for quick status under the submenu **System**.

Table 5.3

| Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | |
|------------------------|------------------------|----------------------|-------------------------|-----------------|-----------------|---|
| EC 541 version | EC 541 version | | | 0.01 [Unitless] | Status value | |
| | Option | | | 1 [Unitless] | Status value | |
| | Hardware version | | | 1 [Unitless] | Status value | |
| | Revision | | | [Text String] | Status value | |
| | Src timestamp: | | | [Text String] | Status value | |
| | Detailed status | SW build information | Module | | [Text String] | Status value |
| | | | Status | | [Text String] | Status value |
| | | | Comp.Ver: Build number: | | [Text String] | Status value |
| | | | Src timestamp: | | [Text String] | Status value |
| | | SW build information | | | | Menu selection, with preview, identical to above. |
| | | SW build information | | | | Menu selection, with preview, identical to above. |
| | | SW build information | | | | Menu selection, with preview, identical to above. |
| | | SW build information | | | | Menu selection, with preview, identical to above. |
| | I/O module SW versions | CA 811 | | | 0.01 [Unitless] | Status value |
| | | CA 821 | | | 0.01 [Unitless] | Status value |
| | | CA 831 | | | 0.01 [Unitless] | Status value |
| | | CA 832 | | | 0.01 [Unitless] | Status value |
| | | CA 841 | | | 0.01 [Unitless] | Status value |
| | | CA 861 | | | 0.01 [Unitless] | Status value |
| | I/O module HW versions | CA 811 | | | 1 [Unitless] | Status value |
| | | CA 821 | | | 1 [Unitless] | Status value |
| | | CA 831 | | | 1 [Unitless] | Status value |
| | | CA 832 | | | 1 [Unitless] | Status value |
| | | CA 841 | | | 1 [Unitless] | Status value |
| | | CA 861 | | | 1 [Unitless] | Status value |
| | Supply voltage | | | | 0.1 V DC | Status value |
| | PCB temperature | | | | 1 °C, 1 °F | Status value |
| Remote config. blocked | | | | NO, YES | Status value | |
| SD card ready | | | | NO, YES | Status value | |
| System time | | | | [Text String] | Status value | |
| Power monitor | Current | | | 0.1 A | Status value | |
| | Line current L1 | | | 0.1 A | Status value | |
| | Line current L2 | | | 0.1 A | Status value | |
| | Line current L3 | | | 0.1 A | Status value | |
| | Average LN voltage | | | 0.1 V | Status value | |
| | Line voltage L1 | | | 0.1 V | Status value | |
| | Line voltage L2 | | | 0.1 V | Status value | |

| Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment |
|---------------------------|--------------------|---------|---------|-------------------------|--------------------------|
| Power monitor | Line voltage L3 | | | 0.1 V | Status value |
| | Average LL voltage | | | 0.1 V | Status value |
| | L1-L2 voltage | | | 0.1 V | Status value |
| | L2-L3 voltage | | | 0.1 V | Status value |
| | L3-L1 voltage | | | 0.1 V | Status value |
| | Power | | | 0.1 kW | Status value |
| | Current frequency | | | 0.01 Hz | Status value |
| | Power factor | | | 0.01 [Unitless] | Status value |
| Power on time | Total | | | 1 s, displayed as h:m:s | Setting, System Password |
| | Today | | | 1 s, displayed as h:m:s | Setting, System Password |
| | Yesterday | | | 1 s, displayed as h:m:s | Setting, System Password |
| Number of power on (boot) | Total | | | 1 [Unitless] | Setting, System Password |
| | Today | | | 1 [Unitless] | Setting, System Password |
| | Yesterday | | | 1 [Unitless] | Setting, System Password |

5.4 Quick status: Pump pit

Table 5.4 shows the complete view for quick status under the submenu **Pump pit**.

Table 5.4

| Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment |
|--------------------|------------------------|---------|---------|------------------------------|--------------|
| Pit level | | | | 0.01 m, 0.01 ft | Status value |
| Inflow | | | | 0.1 l/s, 1 GPM | Status value |
| Outflow | | | | 0.1 l/s, 1 GPM | Status value |
| Outlet pressure | | | | 0.1 bar, 0.1 PSI | Status value |
| Total pump head | | | | 0.01 m, 0.01 ft | Status value |
| Actual pump head | | | | 0.01 m, 0.01 ft | Status value |
| Overflow level | | | | 1 mm, 0.01 in | Status value |
| Overflow flow | | | | 0.1 m ³ /h, 1 GPM | Status value |
| High tariff active | | | | NO, YES | Status value |
| High level | | | | NO, YES | Status value |
| Low level | | | | NO, YES | Status value |
| High-level float | | | | NO, YES | Status value |
| Low-level float | | | | NO, YES | Status value |
| High inflow | | | | NO, YES | Status value |
| Low inflow | | | | NO, YES | Status value |
| Backup start | | | | NO, YES | Status value |
| High pressure | | | | NO, YES | Status value |
| Low pressure | | | | NO, YES | Status value |
| Overflow sensor | | | | NO, YES | Status value |
| Overflow level | | | | NO, YES | Status value |
| Sensor error | Sensor error | | | NO, YES | Status value |
| | Incor. lvl. low float | | | NO, YES | Status value |
| | Incor. lvl. high float | | | NO, YES | Status value |
| | Level is not changing | | | NO, YES | Status value |
| | Pit level | | | 0.01 m, 0.01 ft | Status value |
| Detailed status | Pit level | | | 0.01 m, 0.01 ft | Status value |
| | Pit volume | | | 1 l, 1 gal | Status value |

| Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | |
|-----------------|--------------------|----------------------|-----------|--------------------------|--------------------------|--------------------------|
| Detailed status | Pumped volume | Total | | 0.1 m3, 1 gal | Setting, System Password | |
| | | Today | | 0.1 m3, 1 gal | Setting, System Password | |
| | | Yesterday | | 0.1 m3, 1 gal | Setting, System Password | |
| | Energy consumption | Total | | 0.1 kWh | Setting, System Password | |
| | | Today | | 0.1 kWh | Setting, System Password | |
| | | Yesterday | | 0.1 kWh | Setting, System Password | |
| | Pit efficiency | Average | | 0.001 kWh/m3, 1 kWh/Mgal | Setting, System Password | |
| | | Today | | 0.001 kWh/m3, 1 kWh/Mgal | Setting, System Password | |
| | | Yesterday | | 0.001 kWh/m3, 1 kWh/Mgal | Setting, System Password | |
| | All pumps run # | Total | | 1 [Unitless] | Setting, System Password | |
| | | Today | | 1 [Unitless] | Setting, System Password | |
| | | Yesterday | | 1 [Unitless] | Setting, System Password | |
| | All pumps run time | Total | | 1 s, displayed as h:m:s | Setting, System Password | |
| | | Today | | 1 s, displayed as h:m:s | Setting, System Password | |
| | | Yesterday | | 1 s, displayed as h:m:s | Setting, System Password | |
| | Pit overflow | Overflow | | NO, YES | Status value | |
| | | Overflow level | | 1 mm, 0.01 in | Status value | |
| | | Overflow flow | | 0.1 l/s, 1 GPM | Status value | |
| | | Overflow time | Total | | 1 s, displayed as h:m:s | Setting, System Password |
| | | | Today | | 1 s, displayed as h:m:s | Setting, System Password |
| | | | Yesterday | | 1 s, displayed as h:m:s | Setting, System Password |
| | | Overflow volume | Total | | 0.1 m3, 1 gal | Setting, System Password |
| | | | Today | | 0.1 m3, 1 gal | Setting, System Password |
| | | | Yesterday | | 0.1 m3, 1 gal | Setting, System Password |
| | | No. of overflows | Total | | 1 [Unitless] | Setting, System Password |
| | | | Today | | 1 [Unitless] | Setting, System Password |
| | | | Yesterday | | 1 [Unitless] | Setting, System Password |
| | | Main pwr. mon. | | | NO, YES | Status value |
| | | Secondary pit level | | | 0.01 m, 0.01 ft | Status value |
| | | Pit level difference | | | 0.01 m, 0.01 ft | Status value |
| | Pump pit valve | Valve state | | Closed, Open | Status value | |
| | | Open detect | | NO, YES | Status value | |
| | | Close detect | | NO, YES | Status value | |
| | Drain pump | Drain pump float | | OFF, ON | Status value | |
| | | Terminal I/O status | | OFF, ON | Status value | |
| | | Run indication | | NO, YES | Status value | |
| | | Fallen motor protect | | NO, YES | Status value | |
| | | High temperature | | NO, YES | Status value | |

| Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | |
|-----------------|----------------------|---------------------|---------------------|-----------------|-------------------------|--------------------------|
| Detailed status | Drain pump | Leakage | | NO, YES | Status value | |
| | | Externally blocked | | NO, YES | Status value | |
| | | Running time | Total | | 1 s, displayed as h:m:s | Setting, System Password |
| | | | Today | | 1 s, displayed as h:m:s | Setting, System Password |
| | | | Yesterday | | 1 s, displayed as h:m:s | Setting, System Password |
| | | Number of starts | Total | | 1 [Unitless] | Setting, System Password |
| | | | Today | | 1 [Unitless] | Setting, System Password |
| | | | Yesterday | | 1 [Unitless] | Setting, System Password |
| | | Mixer | Terminal I/O status | | OFF, ON | Status value |
| | Run indication | | | NO, YES | Status value | |
| | Fallen motor protect | | | NO, YES | Status value | |
| | High temperature | | | NO, YES | Status value | |
| | Leakage | | | NO, YES | Status value | |
| | Externally blocked | | | NO, YES | Status value | |
| | Running time | | Total | | 1 s, displayed as h:m:s | Setting, System Password |
| | | | Today | | 1 s, displayed as h:m:s | Setting, System Password |
| | | | Yesterday | | 1 s, displayed as h:m:s | Setting, System Password |
| | Number of starts | | Total | | 1 [Unitless] | Setting, System Password |
| | | | Today | | 1 [Unitless] | Setting, System Password |
| | | | Yesterday | | 1 [Unitless] | Setting, System Password |
| | Cleaner | Terminal I/O status | | OFF, ON | Status value | |

5.5 Quick status: Pumps

Table 5.5 shows the complete view for quick status under the submenu **Pumps**.

Table 5.5

| Submenu | Submenu | Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment |
|---------|------------------|-----------|---------|---------|---------|-------------------------|--------------------------|
| Pump1 | Running time | Total | | | | 1 s, displayed as h:m:s | Setting, System Password |
| | | Today | | | | 1 s, displayed as h:m:s | Setting, System Password |
| | | Yesterday | | | | 1 s, displayed as h:m:s | Setting, System Password |
| | Number of starts | Total | | | | 1 [Unitless] | Setting, System Password |
| | | Today | | | | 1 [Unitless] | Setting, System Password |
| | | Yesterday | | | | 1 [Unitless] | Setting, System Password |
| | Start level | | | | | 0.01 m, 0.01 ft | Status value |
| | Stop level | | | | | 0.01 m, 0.01 ft | Status value |
| | Pump capacity | | | | | 0.1 l/s, 1 GPM | Status value |
| | Pump flow | | | | | 0.01 l/s, 1 GPM | Status value |

| Submenu | Submenu | Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | | | | |
|---------|---------------------------|--------------------|--------------------|--------------------|--------------------|-----------------------|--------------|--------------|--------------|--------------|--------------|
| Pump1 | Calc. pump flow | | | | | 0.01 l/s, 1 GPM | Status value | | | | |
| | External meter pump flow | | | | | 0.01 l/s, 1 GPM | Status value | | | | |
| | Motor current | | | | | 0.1 A | Status value | | | | |
| | Motor power | | | | | 0.1 kW | Status value | | | | |
| | Last pump capacity | | | | | 0.1 l/s, 1 GPM | Status value | | | | |
| | Starts since pump reverse | | | | | 1 [Unitless] | Status value | | | | |
| | Blocked | Externally blocked | Blocked | | | | NO, YES | Status value | | | |
| | | | Externally blocked | | | | NO, YES | Status value | | | |
| | | | | Pump not in auto | | | | NO, YES | Status value | | |
| | | | | Remote blocking | | | | NO, YES | Status value | | |
| | | | | Outlet pressure | | | | NO, YES | Status value | | |
| | | | | Mixer control | | | | NO, YES | Status value | | |
| | | | | Phase missing | | | | NO, YES | Status value | | |
| | | | | Over voltage | | | | NO, YES | Status value | | |
| | | | | Under voltage | | | | NO, YES | Status value | | |
| | | | | Unbalanced voltage | | | | NO, YES | Status value | | |
| | | | Error blocked | Error blocked | | | | NO, YES | Status value | | |
| | | | | | Fallen temp. prot. | | | | NO, YES | Status value | |
| | | | | | Pump blocking | Pump blocking | | | NO, YES | Status value | |
| | | | | | | No run indication | | | | NO, YES | Status value |
| | | | | | | Fallen motor prot. | | | | NO, YES | Status value |
| | | | | | | High motor current | | | | NO, YES | Status value |
| | | | | | | DI pump error | | | | NO, YES | Status value |
| | | | | | | High vibrations | | | | NO, YES | Status value |
| | | | | | | Max. reverse attempts | | | | NO, YES | Status value |
| | | | | Pump valve error | | | | | NO, YES | Status value | |
| | | | Valve open error | | | | | NO, YES | Status value | | |
| | | | Valve close error | | | | | NO, YES | Status value | | |
| | | | Leakage | Generic | | | NO, YES | Status value | | | |
| | | | | Oil chamber | | | | NO, YES | Status value | | |
| | | | | Motor housing | | | | NO, YES | Status value | | |
| | | | | Electr. con. box | | | | NO, YES | Status value | | |
| | | Temperature | Generic | | | NO, YES | Status value | | | | |
| | | | Stator L1 | | | | NO, YES | Status value | | | |
| | | | Stator L2 | | | | NO, YES | Status value | | | |
| | | | Stator L3 | | | | NO, YES | Status value | | | |
| | | Pump blocking | Temperature | Upper bearing | | NO, YES | Status value | | | | |
| | | | | Lower bearing | | | | NO, YES | Status value | | |

| Submenu | Submenu | Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | | |
|---------------|-----------------|-----------------------|------------------|--------------------|----------------------|-----------------|---|--------------|--------------|
| Pump1 | Blocked | Error blocked | Pump holding | Pump holding | | NO, YES | Status value | | |
| | | | | Fallen motor prot. | | NO, YES | Status value | | |
| | | | | DI pump error | | NO, YES | Status value | | |
| | | | | Phase missing | | NO, YES | Status value | | |
| | | | | M.Drive com. error | | NO, YES | Status value | | |
| | | | | M.Drive error | | NO, YES | Status value | | |
| | | | | High vibrations | | NO, YES | Status value | | |
| | | | | Leakage | Generic | | NO, YES | Status value | |
| | | | | | Oil chamber | | NO, YES | Status value | |
| | | | | | Motor housing | | NO, YES | Status value | |
| | | | | | Electr. con. box | | NO, YES | Status value | |
| | | | | Temperature | Generic | | NO, YES | Status value | |
| | | | | | Stator L1 | | NO, YES | Status value | |
| | | | | | Stator L2 | | NO, YES | Status value | |
| | | | | | Stator L3 | | NO, YES | Status value | |
| | Upper bearing | | NO, YES | | Status value | | | | |
| | Lower bearing | | NO, YES | | Status value | | | | |
| | Detailed status | Tag name | | | | | [Text String] | Status value | |
| | | Pump control | | | | | OFF, ON | Status value | |
| | | Run indication | | | | | OFF, Ready to run, Running, Error run, Blocked, Error blocked, Pump reversing | Status value | |
| | | State of M-0-A switch | | | | | MANUAL, Pump not in auto, AUTO | Status value | |
| | | Pump fail | | | | | NO, YES | Status value | |
| | | Pump exercising | | | | | NO, YES | Status value | |
| | | Reverse | | | | | NO, YES | Status value | |
| | | Reverse attempt cnt | | | | | 1 [Unitless] | Status value | |
| | | Reverse status | | | | | -OK-, Timer blocked, !NOT DEFINED TEXT! | Status value | |
| | | Leakage | Leakage | | | | | NO, YES | Status value |
| | | | Generic | | | | | NO, YES | Status value |
| | | | Oil chamber | | | | | NO, YES | Status value |
| | | | Motor housing | | | | | NO, YES | Status value |
| | | | Electr. con. box | | | | | NO, YES | Status value |
| | | Temperature | Temperature | | | | | NO, YES | Status value |
| Generic | | | | | | | 0.1 °C, 0.1 °F | Status value | |
| Stator L1 | | | | | | | 0.1 °C, 0.1 °F | Status value | |
| Stator L2 | | | | | | | 0.1 °C, 0.1 °F | Status value | |
| Stator L3 | | | | | | | 0.1 °C, 0.1 °F | Status value | |
| Upper bearing | | | | | | | 0.1 °C, 0.1 °F | Status value | |
| Lower bearing | | | | | | 0.1 °C, 0.1 °F | Status value | | |
| Vibration | | | | | 0.1 mm/s2, 0.01 in/h | Status value | | | |

| Submenu | Submenu | Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | |
|---------------|-----------------|-----------------------|-------------------------|--------------------|--------------------------|--------------------------------|--------------------------|--------------------------|
| Pump1 | Detailed status | Best efficiency point | Filtered effic. index | | | [User defined Unit] | Status value | |
| | | | Last raw effic. index | | | [User defined Unit] | Status value | |
| | | | Drive start ramp | | | 1 s | Status value | |
| | | | Energy efficiency | | | 0.0001 kWh/m3, 0.0001 kWh/Mgal | Status value | |
| | | | BEP frequency | | | 0.01 Hz | Setting, System Password | |
| | | | BEP last step direction | | | -Decrease-, -Increase-, Retune | Setting, System Password | |
| | | | BEP step | | | 0.01 Hz | Setting, System Password | |
| | | | BEP override | Pump at max. freq. | | | NO, YES | Status value |
| | | | | Pump start counter | | | NO, YES | Status value |
| | | | | All pumps running | | | NO, YES | Status value |
| | | | | High level alarm | | | NO, YES | Status value |
| | | | Pump valve | Valve state | | | Closed, Open | Status value |
| | | | | Open detect | | | NO, YES | Status value |
| | | Close detect | | | | NO, YES | Status value | |
| | | Logs | Running time | Total | | | 1 s, displayed as h:m:s | Setting, System Password |
| | | | | Today | | | 1 s, displayed as h:m:s | Setting, System Password |
| | | | | Yesterday | | | 1 s, displayed as h:m:s | Setting, System Password |
| | | | Number of starts | Total | | | 1 [Unitless] | Setting, System Password |
| | | | | Today | | | 1 [Unitless] | Setting, System Password |
| | | | | Yesterday | | | 1 [Unitless] | Setting, System Password |
| | | | Energy consumption | Total | | | 0.1 kWh | Setting, System Password |
| | | | | Today | | | 0.1 kWh | Setting, System Password |
| | | | | Yesterday | | | 0.1 kWh | Setting, System Password |
| | | | Pump efficiency | Average | | | 0.001 kWh/m3, 1 kWh/Mgal | Setting, System Password |
| | | | | Today | | | 0.001 kWh/m3, 1 kWh/Mgal | Setting, System Password |
| | | | | Yesterday | | | 0.001 kWh/m3, 1 kWh/Mgal | Setting, System Password |
| Pumped volume | Total | | | | 1 l, 0.1 gal | Setting, System Password | | |
| | Today | | | 1 l, 0.1 gal | Setting, System Password | | | |

| Submenu | Submenu | Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | | |
|---|-----------------|--------------|---------------|--------------------|---------|-----------------|--------------------------|---|--------------|
| Pump1 | Detailed status | Logs | Pumped volume | Yesterday | | 1 l, 0.1 gal | Setting, System Password | | |
| | | | Pump capacity | Reference head | | | 0.01 m, 0.01 ft | Status value | |
| | | | | Today | | | 0.1 l/s, 1 GPM | Setting, System Password | |
| | | | | Yesterday | | | 0.1 l/s, 1 GPM | Setting, System Password | |
| | | Pwr.mon. | Pwr. mon. | Connected | | | | -Not connected-, -Connected- | Status value |
| | | | | Com. error | | | | -OK-, -Error- | Status value |
| | | | Status | Current | | | | 0.1 A | Status value |
| | | | | Line current L1 | | | | 0.1 A | Status value |
| | | | | Line current L2 | | | | 0.1 A | Status value |
| | | | | Line current L3 | | | | 0.1 A | Status value |
| | | | | Average LN voltage | | | | 0.1 V | Status value |
| | | | | Line voltage L1 | | | | 0.1 V | Status value |
| | | | | Line voltage L2 | | | | 0.1 V | Status value |
| | | | | Line voltage L3 | | | | 0.1 V | Status value |
| | | | | Average LL voltage | | | | 0.1 V | Status value |
| | | | | L1-L2 voltage | | | | 0.1 V | Status value |
| | | | | L2-L3 voltage | | | | 0.1 V | Status value |
| | | | | L3-L1 voltage | | | | 0.1 V | Status value |
| | | | | Power | | | | 0.1 kW | Status value |
| | | | | Current frequency | | | | 0.01 Hz | Status value |
| | | Power factor | | | | 0.01 [Unitless] | Status value | | |
| | | M.Drive | M.Drive | Connected | | | | -Not connected-, -Connected- | Status value |
| | | | | error | | | | -OK-, -Error- | Status value |
| | | | | Com. error | | | | -OK-, -Error- | Status value |
| | | | Drive status | M.Drive not ready | | | | OFF, ON | Status value |
| | | | | Drive status | | | | OFF, Running, Tune in, Fault, Unknown state | Status value |
| | | | | Current frequency | | | | 0.01 Hz | Status value |
| | | | | Rotation speed | | | | 1 rpm | Status value |
| | | | | Motor voltage | | | | 0.1 V | Status value |
| | | | | Motor power | | | | 0.1 kW | Status value |
| | | | | Current | | | | 0.1 A | Status value |
| | | Torque Nm | | | | 1 Nm, 1 lbf.ft | Status value | | |
| | | Torque % | | | | 0.1 % | Status value | | |
| Pump2 - Pump6 = Menu selection, Identical to above. | | | | | | | | | |

5.6 Quick status: Digital inputs

Table 5.6 shows the complete view for quick status under the submenu **Digital inputs**.

Table 5.6

| Submenu | Setting / Value | Comment |
|---------------------|---|----------------|
| Local at controller | [Graphical representation] | Status value |
| Module 1 | [Graphical representation] | Status value |
| Module 2 | [Graphical representation] | Status value |
| Module 3 | [Graphical representation] | Status value |
| Module 4 | [Graphical representation] | Status value |
| Module 5 | [Graphical representation] | Status value |
| Module 6 | [Graphical representation] | Status value |
| Module 7 | [Graphical representation] | Status value |
| Module 8 | [Graphical representation] | Status value |
| Module 9 | [Graphical representation] | Status value |
| Settings | Logical I/O status, Terminal I/O status | Direct Setting |

5.7 Quick status: Digital outputs

Table 5.7 shows the complete view for quick status under the submenu **Digital outputs**.

Table 5.7

| Submenu | Setting / Value | Comment |
|---------------------|---|----------------|
| Local at controller | [Graphical representation] | Status value |
| Module 1 | [Graphical representation] | Status value |
| Module 2 | [Graphical representation] | Status value |
| Module 3 | [Graphical representation] | Status value |
| Module 4 | [Graphical representation] | Status value |
| Module 5 | [Graphical representation] | Status value |
| Module 6 | [Graphical representation] | Status value |
| Module 7 | [Graphical representation] | Status value |
| Module 8 | [Graphical representation] | Status value |
| Module 9 | [Graphical representation] | Status value |
| Settings | Logical I/O status, Terminal I/O status | Direct Setting |

5.8 Quick status: Leakage inputs

Table 5.8 shows the complete view for quick status under the submenu **Leakage inputs**.

Table 5.8

| Submenu | Setting / Value | Comment |
|----------|----------------------------|--------------|
| Module 1 | [Graphical representation] | Status value |
| Module 2 | [Graphical representation] | Status value |
| Module 3 | [Graphical representation] | Status value |
| Module 4 | [Graphical representation] | Status value |
| Module 5 | [Graphical representation] | Status value |
| Module 6 | [Graphical representation] | Status value |

5.9 Quick status: Analog inputs

Table 5.9 shows the complete view for quick status under the submenu **Analog inputs**.

Table 5.9

| Submenu | Submenu | Setting | Setting / Value | Comment | |
|--|----------|---|--|--------------|--|
| Module 1 | Module 1 | | -Not connected-, -Reconnecting-, -Not connected-, -Connected-, -Error-, -Error-, -Not connected-, CAN ID error, CAN ID error | Status value | |
| Module 1 | AI1 | Signal function | OFF, Pit level, Motor current, Outlet pressure, Vibrations, Outflow meter, Motor temperature, Secondary pit level, Free choice | Status value | |
| | | One or none of lines below, depending on port function. | | | |
| | | Current value | 0.1 A | Status value | |
| | | Current value | 0.1 bar, 0.1 PSI | Status value | |
| | | Current value | 0.1 mm/s ² , 0.01 in/h | Status value | |
| | | Current value | 0.1 l/s, 1 GPM | Status value | |
| | | Current value | 0.1 °C, 0.1 °F | Status value | |
| | | Current value | 0.01 m, 0.01 ft | Status value | |
| | | Current value | [User defined Unit] | Status value | |
| | | One or none of lines below, depending on port function. | | | |
| | | Object | Pump pit, Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6 | Status value | |
| | | Object | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6 | Status value | |
| | | Designation | [Text String] | Status value | |
| | | One or none of lines below, depending on port function. | | | |
| | | Measure point | Generic, Stator L1, Stator L2, Stator L3, Upper bearing, Lower bearing | Status value | |
| | | Current | 0.01 mA | Status value | |
| | | AI2 - AI6 = Menu selection, with preview, identical to above. | | | |
| Module 2 - 9 = Menu selection, with preview, identical to above. | | | | | |

5.10 Quick status: RTD temperature inputs

Table 5.10 shows the complete view for quick status under the submenu **RTD temperature inputs**.

Table 5.10

| Submenu | Submenu | Submenu | Setting / Value | Comment | |
|----------|------------------|---|--|--------------|--|
| Module 1 | Module 1 RTD1 | | -Not connected-, -Reconnecting-, -Not connected-, -Connected-, -Error-, -Error-, -Not connected-, CAN ID error, CAN ID error | Status value | |
| | | Signal function | OFF, Motor temperature, Free choice | Status value | |
| | | One or none of lines below, depending on port function. | | | |
| | | Object | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6 | Status value | |
| | | One or none of lines below, depending on port function. | | | |

| Submenu | Submenu | Submenu | Setting / Value | Comment | |
|--|---|---|--|--------------|--|
| Module 1 | RTD1 | Measure point | Generic, Stator L1, Stator L2, Stator L3, Upper bearing, Lower bearing | Status value | |
| | | Designation | [Text String] | Status value | |
| | | One or none of lines below, depending on port function. | | | |
| | | Current value | 0.1 °C, 0.1 °F | Status value | |
| | | Current value | -OK-, -Tripped- | Status value | |
| | RTD2 - RTD6 = Menu selection, with preview, identical to above. | | | | |
| Module 2 - 9 = Menu selection, with preview, identical to above. | | | | | |

5.11 Quick status: Analog outputs

Table 5.11 shows the complete view for quick status under the submenu **Analog outputs**.

Table 5.11

| Submenu | Submenu | Setting / Value | Comment |
|--|----------|--|--------------|
| Module 1 | Module 1 | -Not connected-, -Reconnecting-, -Not connected-, -Connected-, -Error-, -Error-, -Not connected-, CAN ID error, CAN ID error | Status value |
| | AO1 | 0.01 mA | Status value |
| | AO2 | 0.01 mA | Status value |
| | AO3 | 0.01 mA | Status value |
| | AO4 | 0.01 mA | Status value |
| | AO5 | 0.01 mA | Status value |
| | AO6 | 0.01 mA | Status value |
| Module 2 - 9 = Menu selection, with preview, identical to above. | | | |

5.12 Detailed status: System

Table 5.12 shows the complete view for detailed status under the submenu **System**.

Table 5.12

| Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment |
|----------------|------------------------|----------------------|-------------------------|-----------------|---|
| EC 541 version | Detailed status | EC 541 version | | 0.01 [Unitless] | Status value |
| | | Option | | 1 [Unitless] | Status value |
| | | Hardware version | | 1 [Unitless] | Status value |
| | | Revision | | [Text String] | Status value |
| | | Src timestamp: | | [Text String] | Status value |
| | | SW build information | Module | [Text String] | Status value |
| | | | Status | [Text String] | Status value |
| | | | Comp.Ver: Build number: | [Text String] | Status value |
| | | | Src timestamp: | [Text String] | Status value |
| | | SW build information | | | Menu selection, with preview, identical to above. |
| | | SW build information | | | Menu selection, with preview, identical to above. |
| | | SW build information | | | Menu selection, with preview, identical to above. |
| | | SW build information | | | Menu selection, with preview, identical to above. |
| EC 541 version | I/O module SW versions | CA 811 | | 0.01 [Unitless] | Status value |
| | | CA 821 | | 0.01 [Unitless] | Status value |
| | | CA 831 | | 0.01 [Unitless] | Status value |
| | | CA 832 | | 0.01 [Unitless] | Status value |

| Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment |
|---------------------------|------------------------|---------|-----------------|-------------------------|--------------------------|
| EC 541 version | I/O module SW versions | CA 841 | | 0.01 [Unitless] | Status value |
| | | CA 861 | | 0.01 [Unitless] | Status value |
| | I/O module HW versions | CA 811 | | 1 [Unitless] | Status value |
| | | CA 821 | | 1 [Unitless] | Status value |
| | | CA 831 | | 1 [Unitless] | Status value |
| | | CA 832 | | 1 [Unitless] | Status value |
| | | CA 841 | | 1 [Unitless] | Status value |
| | | CA 861 | | 1 [Unitless] | Status value |
| Supply voltage | | | | 0.1 V DC | Status value |
| PCB temperature | | | | 1 °C, 1 °F | Status value |
| Remote config. blocked | | | | NO, YES | Status value |
| SD card ready | | | | NO, YES | Status value |
| System time | | | | [Text String] | Status value |
| Power monitor | Current | | | 0.1 A | Status value |
| | Line current L1 | | | 0.1 A | Status value |
| | Line current L2 | | | 0.1 A | Status value |
| | Line current L3 | | | 0.1 A | Status value |
| | Average LN voltage | | | 0.1 V | Status value |
| | Line voltage L1 | | | 0.1 V | Status value |
| | Line voltage L2 | | | 0.1 V | Status value |
| | Line voltage L3 | | | 0.1 V | Status value |
| | Average LL voltage | | | 0.1 V | Status value |
| | L1-L2 voltage | | | 0.1 V | Status value |
| | L2-L3 voltage | | | 0.1 V | Status value |
| | L3-L1 voltage | | | 0.1 V | Status value |
| | Power | | | 0.1 kW | Status value |
| | Current frequency | | | 0.01 Hz | Status value |
| Power factor | | | 0.01 [Unitless] | Status value | |
| Power on time | Total | | | 1 s, displayed as h:m:s | Setting, System Password |
| | Today | | | 1 s, displayed as h:m:s | Setting, System Password |
| | Yesterday | | | 1 s, displayed as h:m:s | Setting, System Password |
| Number of power on (boot) | Total | | | 1 [Unitless] | Setting, System Password |
| | Today | | | 1 [Unitless] | Setting, System Password |
| | Yesterday | | | 1 [Unitless] | Setting, System Password |

5.13 Detailed status: Pump pit

Table 5.13 shows the complete view for detailed status under the submenu **Pump pit**.

Table 5.13

| Submenu | Submenu | Submenu | Setting / Value | Comment |
|--------------------|-----------|---------|-----------------|--------------------------|
| Pit level | | | 0.01 m, 0.01 ft | Status value |
| Pit volume | | | 1 l, 1 gal | Status value |
| Pumped volume | Total | | 0.1 m3, 1 gal | Setting, System Password |
| | Today | | 0.1 m3, 1 gal | Setting, System Password |
| | Yesterday | | 0.1 m3, 1 gal | Setting, System Password |
| Energy consumption | Total | | 0.1 kWh | Setting, System Password |
| | Today | | 0.1 kWh | Setting, System Password |
| | Yesterday | | 0.1 kWh | Setting, System Password |

| Submenu | Submenu | Submenu | Setting / Value | Comment |
|----------------------|----------------------|----------------|--------------------------|--------------------------|
| Pit efficiency | Average | | 0.001 kWh/m3, 1 kWh/Mgal | Setting, System Password |
| | Today | | 0.001 kWh/m3, 1 kWh/Mgal | Setting, System Password |
| | Yesterday | | 0.001 kWh/m3, 1 kWh/Mgal | Setting, System Password |
| All pumps run # | Total | | 1 [Unitless] | Setting, System Password |
| | Today | | 1 [Unitless] | Setting, System Password |
| | Yesterday | | 1 [Unitless] | Setting, System Password |
| All pumps run time | Total | | 1 s, displayed as h:m:s | Setting, System Password |
| | Today | | 1 s, displayed as h:m:s | Setting, System Password |
| | Yesterday | | 1 s, displayed as h:m:s | Setting, System Password |
| Pit overflow | Overflow | | NO, YES | Status value |
| | | Overflow level | 1 mm, 0.01 in | Status value |
| | | Overflow flow | 0.1 l/s, 1 GPM | Status value |
| | Overflow time | Total | 1 s, displayed as h:m:s | Setting, System Password |
| | | Today | 1 s, displayed as h:m:s | Setting, System Password |
| | | Yesterday | 1 s, displayed as h:m:s | Setting, System Password |
| | Overflow volume | Total | 0.1 m3, 1 gal | Setting, System Password |
| | | Today | 0.1 m3, 1 gal | Setting, System Password |
| | | Yesterday | 0.1 m3, 1 gal | Setting, System Password |
| | No. of overflows | Total | 1 [Unitless] | Setting, System Password |
| | | Today | 1 [Unitless] | Setting, System Password |
| | | Yesterday | 1 [Unitless] | Setting, System Password |
| Main pwr. mon. | | | NO, YES | Status value |
| Secondary pit level | | | 0.01 m, 0.01 ft | Status value |
| Pit level difference | | | 0.01 m, 0.01 ft | Status value |
| Pump pit valve | Valve state | | Closed, Open | Status value |
| | Open detect | | NO, YES | Status value |
| | Close detect | | NO, YES | Status value |
| Drain pump | Drain pump float | | OFF, ON | Status value |
| | Terminal I/O status | | OFF, ON | Status value |
| | Run indication | | NO, YES | Status value |
| | Fallen motor protect | | NO, YES | Status value |
| | High temperature | | NO, YES | Status value |
| | Leakage | | NO, YES | Status value |
| | Externally blocked | | NO, YES | Status value |
| | Running time | Total | 1 s, displayed as h:m:s | Setting, System Password |
| | | Today | 1 s, displayed as h:m:s | Setting, System Password |
| | | Yesterday | 1 s, displayed as h:m:s | Setting, System Password |
| | Number of starts | Total | 1 [Unitless] | Setting, System Password |
| | | Today | 1 [Unitless] | Setting, System Password |
| Yesterday | | 1 [Unitless] | Setting, System Password | |
| Mixer | Terminal I/O status | | OFF, ON | Status value |
| | Run indication | | NO, YES | Status value |
| | Fallen motor protect | | NO, YES | Status value |
| | High temperature | | NO, YES | Status value |
| | Leakage | | NO, YES | Status value |
| | Externally blocked | | NO, YES | Status value |
| | Running time | Total | 1 s, displayed as h:m:s | Setting, System Password |
| | | Today | 1 s, displayed as h:m:s | Setting, System Password |
| | | Yesterday | 1 s, displayed as h:m:s | Setting, System Password |
| | Number of starts | Total | 1 [Unitless] | Setting, System Password |
| Mixer | Number of starts | Today | 1 [Unitless] | Setting, System Password |
| | Yesterday | 1 [Unitless] | Setting, System Password | |
| Cleaner | Terminal I/O status | | OFF, ON | Status value |

5.14 Detailed status: Pumps

Table 5.14 shows the complete view for detailed status under the submenu **Pumps**.

Table 5.14

| Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | | |
|---------|-----------------------|-------------------------|--------------------|---|---|--------------------------|--------------|
| Pump1 | Tag name | | | [Text String] | Status value | | |
| | Pump control | | | OFF, ON | Status value | | |
| | Run indication | | | OFF, Ready to run, Running, Error run, Blocked, Error blocked, Pump reversing | Status value | | |
| | State of M-0-A switch | | | MANUAL, Pump not in auto, AUTO | Status value | | |
| | Pump fail | | | NO, YES | Status value | | |
| | Pump exercising | | | NO, YES | Status value | | |
| | Reverse | | | NO, YES | Status value | | |
| | Reverse attempt cnt | | | 1 [Unitless] | Status value | | |
| | Reverse status | | | -OK-, Timer blocked, !NOT DEFINED TEXT! | Status value | | |
| | Leakage | Leakage | | | NO, YES | Status value | |
| | | Generic | | | NO, YES | Status value | |
| | | Oil chamber | | | NO, YES | Status value | |
| | | Motor housing | | | NO, YES | Status value | |
| | | Electr. con. box | | | NO, YES | Status value | |
| | Temperature | Temperature | | | NO, YES | Status value | |
| | | Generic | | | 0.1 °C, 0.1 °F | Status value | |
| | | Stator L1 | | | 0.1 °C, 0.1 °F | Status value | |
| | | Stator L2 | | | 0.1 °C, 0.1 °F | Status value | |
| | | Stator L3 | | | 0.1 °C, 0.1 °F | Status value | |
| | | Upper bearing | | | 0.1 °C, 0.1 °F | Status value | |
| | Lower bearing | | | 0.1 °C, 0.1 °F | Status value | | |
| | Vibration | | | | 0.1 mm/s ² , 0.01 in/h | Status value | |
| | Best efficiency point | Filtered effic. index | | | [User defined Unit] | Status value | |
| | | Last raw effic. index | | | [User defined Unit] | Status value | |
| | | Drive start ramp | | | 1 s | Status value | |
| | | Energy efficiency | | | 0.0001 kWh/m ³ , 0.0001 kWh/Mgal | Status value | |
| | | BEP frequency | | | 0.01 Hz | Setting, System Password | |
| | | BEP last step direction | | | -Decrease-, -Increase-, Retune | Setting, System Password | |
| | | BEP step | | | 0.01 Hz | Setting, System Password | |
| | | BEP override | Pump at max. freq. | | | NO, YES | Status value |
| | | | Pump start counter | | | NO, YES | Status value |
| | | | All pumps running | | | NO, YES | Status value |
| | High level alarm | | | | NO, YES | Status value | |
| | Pump valve | Valve state | | | Closed, Open | Status value | |
| | | Open detect | | | NO, YES | Status value | |
| | | Close detect | | | NO, YES | Status value | |
| | Logs | Running time | Total | | 1 s, displayed as h:m:s | Setting, System Password | |
| | | | Today | | 1 s, displayed as h:m:s | Setting, System Password | |
| | | | Yesterday | | 1 s, displayed as h:m:s | Setting, System Password | |

| Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | | |
|---------|--------------------|--------------------|--------------------|---|---------------------------------|---------------------------------|--------------|
| Pump1 | Logs | Number of starts | Total | 1 [Unitless] | Setting, System Password | | |
| | | | Today | 1 [Unitless] | Setting, System Password | | |
| | | | Yesterday | 1 [Unitless] | Setting, System Password | | |
| | | Energy consumption | Total | 0.1 kWh | Setting, System Password | | |
| | | | Today | 0.1 kWh | Setting, System Password | | |
| | | | Yesterday | 0.1 kWh | Setting, System Password | | |
| | | Pump efficiency | Average | 0.001 kWh/m3, 1 kWh/Mgal | Setting, System Password | | |
| | | | Today | 0.001 kWh/m3, 1 kWh/Mgal | Setting, System Password | | |
| | | | Yesterday | 0.001 kWh/m3, 1 kWh/Mgal | Setting, System Password | | |
| | | Pumped volume | Total | 1 l, 0.1 gal | Setting, System Password | | |
| | | | Today | 1 l, 0.1 gal | Setting, System Password | | |
| | | | Yesterday | 1 l, 0.1 gal | Setting, System Password | | |
| | | Pump capacity | Reference head | 0.01 m, 0.01 ft | Status value | | |
| | | | Today | 0.1 l/s, 1 GPM | Setting, System Password | | |
| | | | Yesterday | 0.1 l/s, 1 GPM | Setting, System Password | | |
| | | Pwr.mon. | Pwr. mon. | Connected | | -Not connected-, -Connected- | Status value |
| | | | | Pwr. mon. Com. error | | -OK-, -Error- | Status value |
| | | | Status | Current | 0.1 A | Status value | |
| | | | | Line current L1 | 0.1 A | Status value | |
| | | | | Line current L2 | 0.1 A | Status value | |
| | | | | Line current L3 | 0.1 A | Status value | |
| | Average LN voltage | | | 0.1 V | Status value | | |
| | Line voltage L1 | | | 0.1 V | Status value | | |
| | Line voltage L2 | | | 0.1 V | Status value | | |
| | Line voltage L3 | | | 0.1 V | Status value | | |
| | Average LL voltage | | | 0.1 V | Status value | | |
| | L1-L2 voltage | | | 0.1 V | Status value | | |
| | L2-L3 voltage | | | 0.1 V | Status value | | |
| | L3-L1 voltage | | | 0.1 V | Status value | | |
| | Power | | | 0.1 kW | Status value | | |
| | Current frequency | | | 0.01 Hz | Status value | | |
| | Power factor | | 0.01 [Unitless] | Status value | | | |
| | M Drive | | M Drive Connected | | -Not connected-, -Connected- | Status value | |
| | | | M Drive error | | -OK-, -Error- | Status value | |
| | | | M Drive Com. error | | -OK-, -Error- | Status value | |
| | | | Drive status | M Drive not ready | OFF, ON | Status value | |
| | | Drive status | | OFF, Running, Tune in, Fault, Unknown state | Status value | | |
| | | Current frequency | | 0.01 Hz | Status value | | |
| | | Rotation speed | | 1 rpm | Status value | | |
| | | Motor voltage | | 0.1 V | Status value | | |
| | Motor power | 0.1 kW | Status value | | | | |
| | Current | 0.1 A | Status value | | | | |

| Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment |
|--|---------|--------------|-----------|-----------------|--------------|
| Pump1 | M.Drive | Drive status | Torque Nm | 1 Nm, 1 lbf.ft | Status value |
| | | | Torque % | 0.1 % | Status value |
| Pump 2 - 6 = Menu selection, Identical to above. | | | | | |

5.15 Detailed status: PID regulator

Table 5.15 shows the complete view for detailed status under the submenu **PID regulator**.

Table 5.15

| Submenu | Setting / Value | Comment |
|------------------|-----------------------|----------------------------|
| Output flags | AUTO, MANUAL, Blocked | Setting, Operator Password |
| Setpoint flags | Internal, External | Setting, Operator Password |
| Process value | 0.01 m, 0.01 ft | Status value |
| Current setpoint | 0.01 m, 0.01 ft | Setting, Operator Password |
| Output signal | 0.1 % | Setting, Operator Password |

5.16 Detailed status: Clock functions

Table 5.16 shows the complete view for detailed status under the submenu **Clock functions**.

Table 5.16

| Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | |
|---|-------------------|-----------------------|-----------------------|---|---|--------------|
| Time relays | Time relay 1 | Status | | OFF, ON | Status value | |
| | | Time until next event | | 1 s, displayed as h:m:s | Status value | |
| | | Active | | OFF, ON | Status value | |
| | | Sequence 1 | Status | | OFF, ON | Status value |
| | | | Time until next event | | 1 s, displayed as h:m:s | Status value |
| | | Sequence 2 | | | Menu selection, with preview, identical to above. | |
| | | Sequence 3 | | | Menu selection, with preview, identical to above. | |
| | Sequence 4 | | | Menu selection, with preview, identical to above. | | |
| | Time relay 2 | | | | Menu selection, with preview, identical to above. | |
| | Time relay 3 | | | | Menu selection, with preview, identical to above. | |
| | Time relay 4 | | | | Menu selection, with preview, identical to above. | |
| | Time relay 5 | | | | Menu selection, with preview, identical to above. | |
| | Time relay 6 | | | | Menu selection, with preview, identical to above. | |
| | Time relay 7 | | | | Menu selection, with preview, identical to above. | |
| | Time relay 8 | | | | Menu selection, with preview, identical to above. | |
| | Count down timers | Count down timer 1 | Output signal | | OFF, ON | Status value |
| | | | Status | | OFF, ON, Manual off, Repet. expired (retrigger) | Status value |
| | | Manual control | | AUTO, ON, OFF | Setting, Operator Password | |
| | | Repetition(s) | | 1 [Unitless] | Status value | |
| | | Delay time | | 1 s, displayed as h:m:s | Status value | |
| Count down timer 2 - 12 = Menu selection, with preview, identical to above. | | | | | | |

5.17 Detailed status: Pulse channels

Table 5.17 shows the complete view for detailed status under the submenu **Pulse channels**.

Table 5.17

| Submenu | Submenu | Submenu | Setting / Value | Comment | |
|-------------|---|-----------|-----------------------------|-----------------|--------------------------|
| Pulse ch. 1 | Function | | Precipitation, Energy, Flow | Status value | |
| | One or none of lines below, depending on other settings. | | | | |
| | Current value | | 0.1 l/s/ha, 0.01 in/h | Status value | |
| | Current value | | 0.1 kW | Status value | |
| | Current value | | 0.1 m3/h, 1 GPM | Status value | |
| | One or none of lines below, depending on other settings. | | | | |
| | Accumulated values | Total | | 0.1 mm, 0.01 in | Setting, System Password |
| | | Today | | 0.1 mm, 0.01 in | Setting, System Password |
| | | Yesterday | | 0.1 mm, 0.01 in | Setting, System Password |
| | Accumulated values | Total | | 0.1 kWh | Setting, System Password |
| | | Today | | 0.1 kWh | Setting, System Password |
| | | Yesterday | | 0.1 kWh | Setting, System Password |
| | Accumulated values | Total | | 0.1 m3, 0.1 gal | Setting, System Password |
| | | Today | | 0.1 m3, 0.1 gal | Setting, System Password |
| | | Yesterday | | 0.1 m3, 0.1 gal | Setting, System Password |
| | Pulse ch. 2 - 4 = Menu selection, with preview, identical to above. | | | | |

5.18 Detailed status: Inputs and outputs

Table 5.18 shows the complete view for detailed status under the submenu **Inputs and outputs**.

Table 5.18

| Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | | |
|---------------|----------|-------------|-----------------|---|--------------|---|--------------|
| Analog inputs | Module 1 | Module 1 | | -Not connected-, -Reconnecting-, -Not connected-, -Connected-, -Error-, -Error-, -Not connected-, CAN ID error, CAN ID error | Status value | | |
| | | | Signal function | OFF, Pit level, Motor current, Outlet pressure, Vibrations, Outflow meter, Motor temperature, Secondary pit level, Free choice | Status value | | |
| | | AI1 | AI1 | One or none of lines below, depending on port function. | | | |
| | | | | Current value | | 0.1 A | Status value |
| | | | | Current value | | 0.1 bar, 0.1 PSI | Status value |
| | | | | Current value | | 0.1 mm/s2, 0.01 in/h | Status value |
| | | | | Current value | | 0.1 l/s, 1 GPM | Status value |
| | | | | Current value | | 0.1 °C, 0.1 °F | Status value |
| | | | | Current value | | 0.01 m, 0.01 ft | Status value |
| | | | | Current value | | [User defined Unit] | Status value |
| | | | | One or none of lines below, depending on port function. | | | |
| | | | | Object | | Pump pit, Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6 | Status value |
| | | Object | | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6 | Status value | | |
| | | Designation | | [Text String] | Status value | | |

| Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | | |
|--|----------|---|---|--|--------------|--------------|--|
| Analog inputs | Module 1 | AI1 | One or none of lines below, depending on port function. | | | | |
| | | | Measure point | Generic, Stator L1, Stator L2, Stator L3, Upper bearing, Lower bearing | Status value | | |
| | | | Current | 0.01 mA | Status value | | |
| | | AI2 - AI6 = Menu selection, with preview, identical to above. | | | | | |
| Module 2 - 9 = Menu selection, with preview, identical to above. | | | | | | | |
| RTD temp. inputs | Module 1 | Module 1 | | -Not connected-, -Reconnecting-, -Not connected-, -Connected-, -Error-, -Error-, -Not connected-, CAN ID error, CAN ID error | Status value | | |
| | | | Signal function | OFF, Motor temperature, Free choice | Status value | | |
| | | One or none of lines below, depending on port function. | | | | | |
| | | RTD1 | Object | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6 | Status value | | |
| | | | One or none of lines below, depending on port function. | | | | |
| | | | Measure point | Generic, Stator L1, Stator L2, Stator L3, Upper bearing, Lower bearing | Status value | | |
| | | | Designation | [Text String] | Status value | | |
| | | | One or none of lines below, depending on port function. | | | | |
| | | | Current value | 0.1 °C, 0.1 °F | Status value | | |
| | | | Current value | -OK-, -Tripped- | Status value | | |
| | | RTD2 - RTD6 = Menu selection, with preview, identical to above. | | | | | |
| Module 2 - 9 = Menu selection, with preview, identical to above. | | | | | | | |
| Analog outputs | Module 1 | Module 1 | | -Not connected-, -Reconnecting-, -Not connected-, -Connected-, -Error-, -Error-, -Not connected-, CAN ID error, CAN ID error | Status value | | |
| Analog outputs | Module 1 | AO1 | Signal function | OFF, Pit level, Pit inflow, Pit outflow, Pit overflow, Pulse channel 1, Pulse channel 2, Pulse channel 3, Pulse channel 4, PID control output, Data register, Data register 2 compl., Set freq. P1, Set freq. P2, Set freq. P3, Set freq. P4, Set freq. P5, Set freq. P6 | Status value | | |
| | | | | Current value | 0.01 mA | Status value | |
| | | AO2 - AO6 = Menu selection, with preview, identical to above. | | | | | |
| Module 2 - 9 = Menu selection, with preview, identical to above. | | | | | | | |

| Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment |
|----------------|---------------------|---------|---|---|--------------|
| Digital inputs | Local at controller | D11 | Signal function | OFF, Run indication, Manual start, Set manual, Set auto, Start float, Pump failure, Motor protector, High motor temp. pump, Leakage pump, Stop float, Low level float, Overflow sensor, High level float, Start float drain pump, Local mode, Alarm reset, Power fail, DI pulse channel 1-4, Block PID controller, Alarm input, Block operation, Leakage mixer-drain pump, High temp. mixer-drain p., Emergency power mode, Block remote data, Ackn. pump alarms, Valve open, Valve close | Status value |
| | | | One or none of lines below, depending on other settings. | | |
| | | | Pulses ch1 | 1 [Unitless] | Status value |
| | | | Pulses ch2 | 1 [Unitless] | Status value |
| | | | Pulses ch3 | 1 [Unitless] | Status value |
| | | | Pulses ch4 | 1 [Unitless] | Status value |
| | | | Status | -OFF-, -ON- | Status value |
| | | | One or none of lines below, depending on other settings. | | |
| | | | Object | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6 | Status value |
| | | | Object | Pulse channel 1, Pulse channel 2, Pulse channel 3, Pulse channel 4 | Status value |
| | | | Object | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6, Mixer, Drain pump, All | Status value |
| | | | Object | Mixer, Drain pump | Status value |
| | | | Allow set clock | NO, YES | Status value |
| | | | Object | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6, All | Status value |
| | | | Object | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6, Pump pit | Status value |
| | | | D11 One or none of lines below, depending on port function. | | |
| | | | Measure point | Generic, Stator L1, Stator L2, Stator L3, Upper bearing, Lower bearing | Status value |
| | | | Measure point | Generic, Oil chamber, Motor housing, Electr. con. box | Status value |
| | | | Normally open/closed | NO input terminal, NC input terminal, True IO number, Inv. IO number | Status value |
| | | | D12 - D14 = Menu selection, with preview, identical to above. | | |

| Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | |
|----------------|----------|----------|-----------------|---|--|--------------|
| Digital inputs | Module 1 | Module 1 | | -Not connected-, -Reconnecting-, -Not connected-, -Connected-, -Error-, -Error-, -Not connected-, CAN ID error, CAN ID error | Status value | |
| | | | Signal function | OFF, Run indication, Manual start, Set manual, Set auto, Start float, Pump failure, Motor protector, High motor temp. pump, Leakage pump, Stop float, Low level float, Overflow sensor, High level float, Start float drain pump, Local mode, Alarm reset, Power fail, DI pulse channel 1-4, Block PID controller, Alarm input, Block operation, Leakage mixer- drain pump, High temp. mixer-drain p., Emergency power mode, Block remote data, Ackn. pump alarms, Valve open, Valve close | Status value | |
| | | | | One or none of lines below, depending on port function. | | |
| | | | | Pulses ch1 | 1 [Unitless] | Status value |
| | | | | Pulses ch2 | 1 [Unitless] | Status value |
| | | | | Pulses ch3 | 1 [Unitless] | Status value |
| | | | | Pulses ch4 | 1 [Unitless] | Status value |
| | | | | Status | -OFF-, -ON- | Status value |
| | | | | One or none of lines below, depending on port function. | | |
| | | | | Object | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6 | Status value |
| | | | | Object | Pulse channel 1, Pulse channel 2, Pulse channel 3, Pulse channel 4 | Status value |
| | | | | Object | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6, Mixer, Drain pump, All | Status value |
| | | | | Object | Mixer, Drain pump | Status value |
| | | | | Allow set clock | NO, YES | Status value |
| | | | | Object | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6, All | Status value |
| | | | | Object | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6, Pump pit | Status value |
| | | | | One or none of lines below, depending on port function. | | |
| | | | | Measure point | Generic, Stator L1, Stator L2, Stator L3, Upper bearing, Lower bearing | Status value |

| Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | |
|--|---|--|---|---|--|--------------|
| Digital inputs | Module 1 | DI1 | Measure point | Generic, Oil chamber, Motor housing, Electr. con. box | Status value | |
| | | | Normally open/closed | NO input terminal, NC input terminal, True IO number, Inv. IO number | Status value | |
| | | DI2 - DI12 = Menu selection, with preview, identical to above. | | | | |
| Module 2 - 9 = Menu selection, with preview, identical to above. | | | | | | |
| Digital outputs | Local at controller | DO1 | Signal function | OFF, Pump control, Reset motor protector, Pump fail, Not enough pumps avail., One pump fail, Mixer control, Drain pump control, Cleaner control, Com. timeout pulse, Remote control, Personnel alarm, High level, Alarm alert, Not ackn. alarm, Active alarm, Pump reversing, Logic IO, Data register setpoint, Auto reset alert, Valve control, Valve open, Valve close, Time relay, Pulse timer | Status value | |
| | | | Status | -OFF-, -ON- | Status value | |
| | | | One or none of lines below, depending on port function. | | | |
| | | | Object | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6, Mixer, Drain pump, All | Status value | |
| | | | Communication port | Modem port (RS232), RS485 port 1, RS485 port 2, USB port, GPRS data, Ethernet port (TCP/IP) | Status value | |
| | | | Object | B-Alarm, A-Alarm, All alarms | Status value | |
| | | | Object | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6 | Status value | |
| | | | Object | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6, Pump pit | Status value | |
| | DO2 - DO4 = Menu selection, with preview, identical to above. | | | | | |
| | | Module 1 | Module 1 | | -Not connected-, -Reconnecting-, -Not connected-, -Connected-, -Error-, -Error-, -Not connected-, CAN ID error, CAN ID error | Status value |

| Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | | |
|-----------------|----------|----------|--|---|--------------|--|--|
| Digital outputs | Module 1 | DO1 | Signal function | OFF, Pump control, Reset motor protector, Pump fail, Not enough pumps avail., One pump fail, Mixer control, Drain pump control, Cleaner control, Com. timeout pulse, Remote control, Personnel alarm, High level, Alarm alert, Not ackn. alarm, Active alarm, Pump reversing, Logic IO, Data register setpoint, Auto reset alert, Valve control, Valve open, Valve close, Time relay, Pulse timer | Status value | | |
| | | | Status | -OFF-, -ON- | Status value | | |
| | | | One or none of lines below, depending on port function. | | | | |
| | | | Object | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6, Mixer, Drain pump, All | Status value | | |
| | | | Communication port | Modem port (RS232), RS485 port 1, RS485 port 2, USB port, GPRS data, Ethernet port (TCP/IP) | Status value | | |
| | | | Object | B-Alarm, A-Alarm, All alarms | Status value | | |
| | | | Object | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6 | Status value | | |
| | | | Object | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6, Pump pit | Status value | | |
| | | | DO2 - DO8 = Menu selection, with preview, identical to above. | | | | |
| | | | Module 2 - 9 = Menu selection, with preview, identical to above. | | | | |
| Leakage inputs | Module 1 | Module 1 | | -Not connected-, -Reconnecting-, -Not connected-, -Connected-, -Error-, -Error-, -Not connected-, CAN ID error, CAN ID error | Status value | | |
| | | DI1 | Signal function | OFF, Leakage pump, Leakage mixer-drain pump | Status value | | |
| | | | Status | -OFF-, -ON- | Status value | | |
| | | | One or none of lines below, depending on port function. | | | | |
| | | | Object | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6 | Status value | | |
| | | | Object | Mixer, Drain pump | Status value | | |
| | | | One or none of lines below, depending on port function. | | | | |
| | | | Measure point | Generic, Oil chamber, Motor housing, Electr. con. box | Status value | | |
| | | | DI2 - DI 6 = Menu selection, with preview, identical to above. | | | | |
| | | | Module 2 - 9 = Menu selection, with preview, identical to above. | | | | |

5.19 Detailed status: Communication

Table 5.19 shows the complete view for detailed status under the submenu **Communication**.

Table 5.19

| Submenu | Submenu | Submenu | Setting / Value | Comment |
|--------------------|----------------------|--------------|---|--------------|
| USB port | Port status | | [Graphical representation] | Status value |
| | Protocol ID | | 1 [Unitless] | Status value |
| | Application protocol | | Modbus slave, Modbus master | Status value |
| | Protocol type | | Modbus RTU, Modbus TCP | Status value |
| | No. OK messages | | 1 [Unitless] | Status value |
| | No. Error messages | | 1 [Unitless] | Status value |
| | No. Checksum errors | | 1 [Unitless] | Status value |
| Modem port (RS232) | Port status | | [Graphical representation] | Status value |
| | Baud rate | | None, 300, 600, 1200, 2400, 4800, 9600, 19200, 38400, 57600, 115200, 230400, 460800 | Status value |
| | Parity | | None, Odd, Even, Mark | Status value |
| | Protocol ID | | 1 [Unitless] | Status value |
| | Application protocol | | GPRS Hayes enable, Transparent | Status value |
| | Protocol type | | Modbus RTU, Modbus TCP | Status value |
| | No. OK messages | | 1 [Unitless] | Status value |
| | No. Error messages | | 1 [Unitless] | Status value |
| | No. Checksum errors | | 1 [Unitless] | Status value |
| | No. Overflows | | 1 [Unitless] | Status value |
| | No. Parity errors | | 1 [Unitless] | Status value |
| | No. Framing errors | | 1 [Unitless] | Status value |
| | No. Break | | 1 [Unitless] | Status value |
| RS485 port 1 | Port status | | [Graphical representation] | Status value |
| | Baud rate | | None, 300, 600, 1200, 2400, 4800, 9600, 19200, 38400, 57600, 115200, 230400, 460800 | Status value |
| | Parity | | None, Odd, Even, Mark | Status value |
| | Protocol ID | | 1 [Unitless] | Status value |
| | Application protocol | | Modbus slave, Modbus master | Status value |
| RS485 port 1 | Protocol type | | Modbus RTU, Modbus TCP | Status value |
| | No. OK messages | | 1 [Unitless] | Status value |
| | No. Error messages | | 1 [Unitless] | Status value |
| | No. Checksum errors | | 1 [Unitless] | Status value |
| | No. Overflows | | 1 [Unitless] | Status value |
| | No. Parity errors | | 1 [Unitless] | Status value |
| | No. Framing errors | | 1 [Unitless] | Status value |
| No. Break | | 1 [Unitless] | Status value | |
| RS485 port 2 | Port status | | [Graphical representation] | Status value |
| | Baud rate | | None, 300, 600, 1200, 2400, 4800, 9600, 19200, 38400, 57600, 115200, 230400, 460800 | Status value |
| | Parity | | None, Odd, Even, Mark | Status value |

| Submenu | Submenu | Submenu | Setting / Value | Comment | |
|------------------------|--|--------------------|---|----------------------------|--------------|
| RS485 port 2 | Protocol ID | | 1 [Unitless] | Status value | |
| | Application protocol | | Modbus slave, Modbus master | Status value | |
| | Protocol type | | Modbus RTU, Modbus TCP | Status value | |
| | No. OK messages | | 1 [Unitless] | Status value | |
| | No. Error messages | | 1 [Unitless] | Status value | |
| | No. Checksum errors | | 1 [Unitless] | Status value | |
| | No. Overflows | | 1 [Unitless] | Status value | |
| | No. Parity errors | | 1 [Unitless] | Status value | |
| | No. Framing errors | | 1 [Unitless] | Status value | |
| | No. Break | | 1 [Unitless] | Status value | |
| Ethernet port (TCP/IP) | Port status | | [Graphical representation] | Status value | |
| | Protocol ID | | 1 [Unitless] | Status value | |
| | Application protocol | | Modbus slave, Modbus master | Status value | |
| | Protocol type | | Modbus RTU, Modbus TCP | Status value | |
| | One or none of lines below, depending on other settings. | | | | |
| | Set static IP | IP address | | [Text String] | Status value |
| | | Net Mask | | [Text String] | Status value |
| | | Gateway | | [Text String] | Status value |
| | | Port number | | 1 [Unitless] | Status value |
| | Show dynamic IP | IP address | | [Text String] | Status value |
| | | Net Mask | | [Text String] | Status value |
| | | Gateway | | [Text String] | Status value |
| | | Port number | | 1 [Unitless] | Status value |
| | MAC ID | | [Text String] | Status value | |
| No. OK messages | | 1 [Unitless] | Status value | | |
| No. Error messages | | 1 [Unitless] | Status value | | |
| No. Checksum errors | | 1 [Unitless] | Status value | | |
| GPRS status | Port status | | [Graphical representation] | Status value | |
| | Signal 0-31 (99=NA) | | 1 [Unitless] | Status value | |
| | Local IP address | | [Text String] | Status value | |
| | Connect status | | -Not connected-, -Reconnecting-, -Connected-, Force reconnect, -TCP Server waiting- | Setting, Operator Password | |
| | Protocol ID | | 1 [Unitless] | Status value | |
| GPRS status | Application protocol | | Modbus slave, Modbus master | Status value | |
| | Protocol type | | Modbus RTU, Modbus TCP | Status value | |
| | Status counters | Connect counter | | 1 [Unitless] | Status value |
| | | No. OK messages | | 1 [Unitless] | Status value |
| | | No. Error messages | | 1 [Unitless] | Status value |
| No. Checksum errors | | | 1 [Unitless] | Status value | |
| IO Modules (CAN bus) | Online | | 1 [Unitless] | Status value | |
| | No. Tx OK messages | | 1 [Unitless] | Status value | |
| | No. Rx OK messages | | 1 [Unitless] | Status value | |
| | No. Error messages | | 1 [Unitless] | Status value | |

5.20 Detailed status: Field bus modules (RS485)

Table 5.20 shows the complete view for detailed status under the submenu **Field bus modules (RS485)**.

Table 5.20

| Submenu | Submenu | Submenu | Setting / Value | Comment | |
|---|----------------------|--------------------|------------------------------|---|--------------|
| Main pwr. mon. | Pwr. mon. Connected | | -Not connected-, -Connected- | Status value | |
| | Pwr. mon. Com. error | | -OK-, -Error- | Status value | |
| | Status | Current | | 0.1 A | Status value |
| | | Line current L1 | | 0.1 A | Status value |
| | | Line current L2 | | 0.1 A | Status value |
| | | Line current L3 | | 0.1 A | Status value |
| | | Average LN voltage | | 0.1 V | Status value |
| | | Line voltage L1 | | 0.1 V | Status value |
| | | Line voltage L2 | | 0.1 V | Status value |
| | | Line voltage L3 | | 0.1 V | Status value |
| | | Average LL voltage | | 0.1 V | Status value |
| | | L1-L2 voltage | | 0.1 V | Status value |
| | | L2-L3 voltage | | 0.1 V | Status value |
| | | L3-L1 voltage | | 0.1 V | Status value |
| | | Power | | 0.1 kW | Status value |
| | | Current frequency | | 0.01 Hz | Status value |
| Power factor | | 0.01 [Unitless] | Status value | | |
| Pwr.mon.P1 | Pwr. mon. Connected | | -Not connected-, -Connected- | Status value | |
| | Pwr. mon. Com. error | | -OK-, -Error- | Status value | |
| | Status | Current | | 0.1 A | Status value |
| | | Line current L1 | | 0.1 A | Status value |
| | | Line current L2 | | 0.1 A | Status value |
| | | Line current L3 | | 0.1 A | Status value |
| | | Average LN voltage | | 0.1 V | Status value |
| | | Line voltage L1 | | 0.1 V | Status value |
| | | Line voltage L2 | | 0.1 V | Status value |
| | | Line voltage L3 | | 0.1 V | Status value |
| | | Average LL voltage | | 0.1 V | Status value |
| | | L1-L2 voltage | | 0.1 V | Status value |
| | | L2-L3 voltage | | 0.1 V | Status value |
| | | L3-L1 voltage | | 0.1 V | Status value |
| | | Power | | 0.1 kW | Status value |
| | | Current frequency | | 0.01 Hz | Status value |
| Power factor | | 0.01 [Unitless] | Status value | | |
| Pwr.mon.P2 - P6 = Menu selection, with preview, identical to above. | | | | | |
| M.Drive P1 | M.Drive Connected | | -Not connected-, -Connected- | Status value | |
| | M.Drive error | | -OK-, -Error- | Status value | |
| | M.Drive Com. error | | -OK-, -Error- | Status value | |
| | Drive status | M.Drive not ready | | OFF, ON | Status value |
| | | Drive status | | OFF, Running, Tune in, Fault, Unknown state | Status value |
| | | Current frequency | | 0.01 Hz | Status value |
| | | Rotation speed | | 1 rpm | Status value |
| | | Motor voltage | | 0.1 V | Status value |
| | | Motor power | | 0.1 kW | Status value |
| | | Current | | 0.1 A | Status value |
| | | Torque Nm | | 1 Nm, 1 lbf.ft | Status value |
| Torque % | | 0.1 % | Status value | | |
| M.Drive P2 - P6 = Menu selection, with preview, identical to above. | | | | | |

5.21 Settings: System

Table 5.21 shows the complete list of **System settings**.

Table 5.21

| Submenu | Submenu | Submenu | Setting / Value | Comment | |
|----------------------------|--------------------------|-----------------------------|--|----------------------------|--------------------------|
| Select language | | | English, French, German, Spanish, Danish, Dutch, Italian, Norwegian, Polish, Portuguese (Brazil), Swedish, Turkish | Setting, Operator Password | |
| Station ID | | | 1 [Unitless] | Setting, System Password | |
| Station name | | | [Text String] | Setting, System Password | |
| Date format | | | YYYY.MM.DD, DD.MM.YYYY, MM.DD.YYYY | Setting, System Password | |
| Set date | | | [Text String] | Setting, Operator Password | |
| Set time | | | [Text String] | Setting, Operator Password | |
| Select units | | | Metric units, U.S. units | Setting, System Password | |
| Main nominal voltage | | | 1 V | Setting, System Password | |
| Main nominal frequency | | | 1 Hz | Setting, System Password | |
| Ackn. all alarms w reg 333 | | | NO, YES | Setting, System Password | |
| System Alarms | Power fail | | | | |
| | High PCB temp. EC 541 | | | | |
| | Low supply voltage | | | | |
| | Personnel alarm | Max. time to reset | 1 min | Setting, System Password | |
| | | EC 541 time lost | | | |
| | EC 541 power lost | | | | |
| Graphical display | Backlight timeout | | 1 min | Setting, System Password | |
| | Backlight strength | | 1% | Setting, System Password | |
| | Touch screen sensitivity | | 1% | Setting, System Password | |
| | Calibrate touch screen | | NO, YES | Setting, System Password | |
| Graphical display | Scaling 100% | | 0.01 m, 0.01 ft | Setting, System Password | |
| | Show overflow outlet | | OFF, ON | Setting, System Password | |
| | Mixer | | OFF, ON | Setting, System Password | |
| | Start/stop levels | | OFF, ON | Setting, System Password | |
| | Header line source | | AUTO, None, AI1, AI2, AI3, AI4, AI5, AI6 | Setting, System Password | |
| | AI Module | | 1, 2, 3, 4, 5, 6, 7, 8, 9 | Setting, System Password | |
| | Information pump1 | Hide electrical current | | OFF, ON | Setting, System Password |
| | | Temp. symb. override enable | | NO, YES | Setting, System Password |
| | | Temp. symbol override I/O | | 1 [Unitless] | Setting, System Password |
| | | Leak. symb. override enable | | NO, YES | Setting, System Password |

| Submenu | Submenu | Submenu | Setting / Value | Comment |
|---------------------|---|-----------------------------|--|----------------------------|
| Graphical display | Information pump1 | Leak. symbol override I/O | 1 [Unitless] | Setting, System Password |
| | | Electr. symbol override en. | NO, YES | Setting, System Password |
| | | Electr. symb. override I/O | 1 [Unitless] | Setting, System Password |
| | | Vibrat. symbol override en. | NO, YES | Setting, System Password |
| | | Vibrat. symb. override I/O | 1 [Unitless] | Setting, System Password |
| | Information pump2 - pump6 = Menu selection, identical to above. | | | |
| SD card settings | Auto load FW from SD card | | Never, Ask if file found, Always if higher version | Setting, System Password |
| | Auto load cfg. from SD card | | Never, Ask if file found, Always if file found | Setting, System Password |
| | Copy cfg. data to SD card | | Ready, Configuration, Config. and reg. logs | Status value |
| | Copy event list to SD | | Ready, To .txt file | Status value |
| | Copy AI log to SD card | | Ready, Today's log data, All log data | Status value |
| | Copy AI log to SD daily | | OFF, To .txt file, To .xls file | Setting, System Password |
| | Save crash log to SD | | Ready, Last crash log, All crash logs | Status value |
| Change passcode | Operator | | 1 [Unitless] | Setting, Operator Password |
| | System | | 1 [Unitless] | Setting, System Password |
| History/alarm reset | All history log | | Cancel, Reset | Status value |
| | All alarms | | Cancel, Reset | Status value |

5.22 Settings: Pump pit

Table 5.22 shows the complete list of **Pump pit settings**.

Table 5.22

| Submenu | Submenu | Submenu | Setting / Value | Comment |
|--------------|-----------------------|---------------------------|----------------------|--------------------------|
| Station flow | Measurment parameters | Calculate inflow | OFF, ON | Setting, System Password |
| | | Pit shape | Rectangular, Conical | Setting, System Password |
| | | Inflow calc. interval | 1 s | Setting, System Password |
| | | Flow compensation 2 pumps | 1% | Setting, System Password |
| | | Flow compensation 3 pumps | 1% | Setting, System Password |
| | | Flow compensation 4 pumps | 1% | Setting, System Password |
| | | Flow compensation 5 pumps | 1% | Setting, System Password |
| | | Flow compensation 6 pumps | 1% | Setting, System Password |
| | Pit area | Level 0 | 0.01 m, 0.01 ft | Setting, System Password |
| | | Area 0 | 0.01 m2, 0.01 ft2 | Setting, System Password |
| | | Level 1 | 0.01 m, 0.01 ft | Setting, System Password |
| | | Area 1 | 0.01 m2, 0.01 ft2 | Setting, System Password |
| | | Level 2 | 0.01 m, 0.01 ft | Setting, System Password |
| | | Area 2 | 0.01 m2, 0.01 ft2 | Setting, System Password |
| | | Level 3 | 0.01 m, 0.01 ft | Setting, System Password |
| | | Area 3 | 0.01 m2, 0.01 ft2 | Setting, System Password |
| | | Level 4 | 0.01 m, 0.01 ft | Setting, System Password |
| | | Area 4 | 0.01 m2, 0.01 ft2 | Setting, System Password |
| | | Level 5 | 0.01 m, 0.01 ft | Setting, System Password |

| Submenu | Submenu | Submenu | Setting / Value | Comment |
|-----------------------|---------------------------|------------------------|--|--------------------------|
| Station flow | Pit area | Area 5 | 0.01 m2, 0.01 ft2 | Setting, System Password |
| | | Level 6 | 0.01 m, 0.01 ft | Setting, System Password |
| | | Area 6 | 0.01 m2, 0.01 ft2 | Setting, System Password |
| | | Level 7 | 0.01 m, 0.01 ft | Setting, System Password |
| | | Area 7 | 0.01 m2, 0.01 ft2 | Setting, System Password |
| | | Level 8 | 0.01 m, 0.01 ft | Setting, System Password |
| | | Area 8 | 0.01 m2, 0.01 ft2 | Setting, System Password |
| | | Level 9 | 0.01 m, 0.01 ft | Setting, System Password |
| Overflow | Overflow detect | | OFF, Overflow sensor, Level limit | Setting, System Password |
| | Overflow calculation | | Exponent & constant, Lock on inflow | Setting, System Password |
| | High level limit | | 0.001 m, 0.001 ft | Setting, System Password |
| | Exponent 1 | | 0.0001 [Unitless] | Setting, System Password |
| | Constant 1 | | 0.0001 [Unitless] | Setting, System Password |
| | Exponent 2 | | 0.0001 [Unitless] | Setting, System Password |
| | Constant 2 | | 0.0001 [Unitless] | Setting, System Password |
| Pit alarms | High level | | | |
| | Low level | | | |
| | High float | | | |
| | Pit alarms | Block alarm high float | Never block, 1 pump running, 2 pumps running | Setting, System Password |
| | Low float | | | |
| | High inflow | | | |
| | Low inflow | | | |
| | Backup run | | | |
| | Remote block | | | |
| | High pressure | | | |
| | Low pressure | | | |
| | Overflow | | | |
| | Pressure block | | | |
| | High pit level difference | | | |
| | Emergency power mode | | | |
| | Sensor | | | |
| | To few pumps available | | | |
| | Drain pump | | | |
| | Leakage mixer | | | |
| | High temp. mixer | | | |
| | Leakage drain pump | | | |
| | High temp. drain pump | | | |
| | No run indic. drain pump | | | |
| | Motor prot. drain pump | | | |
| | No run indication mixer | | | |
| | Motor prot. mixer | | | |
| | Motor prot. rst.drain/mix | | | |
| Pit valve error | | | | |
| Pit valve open error | | | | |
| Pit valve close error | | | | |

| Submenu | Submenu | Submenu | Setting / Value | Comment | |
|---|------------------------|-----------------|-----------------------------|---------------------------|--------------------------|
| Pump pit valve | Pump open delay | | 1 s | Setting, System Password | |
| | Pump close delay | | 1 s | Setting, System Password | |
| | Max. time to open | | 1 s | Setting, System Password | |
| | Max. time to close | | 1 s | Setting, System Password | |
| | Max. time to reopen | | 1 s | Setting, System Password | |
| | Close retry delay time | | 1 s | Setting, System Password | |
| Cleaning control | Flush at: | | At pump start, At pump stop | Setting, System Password | |
| | Running time | | 1 s | Setting, System Password | |
| | Start count interval | | 1 [Unitless] | Setting, System Password | |
| Mixer control | Stop pump during mix | | NO, YES | Setting, System Password | |
| | Mixer time | | 1 s | Setting, System Password | |
| | Start count interval | | 1 [Unitless] | Setting, System Password | |
| | Timer interval | | 1 min, displayed as hh:mm | Setting, System Password | |
| | Max. level | | 0.01 m, 0.01 ft | Setting, System Password | |
| | Min. level | | 0.01 m, 0.01 ft | Setting, System Password | |
| Mixer control | Select run indication | | OFF, Digital inputs | Setting, System Password | |
| Drain pump control | Start delay | | 1 s | Setting, System Password | |
| | Stop delay | | 1 s | Setting, System Password | |
| | Select run indication | | OFF, Digital inputs | Setting, System Password | |
| Motor prot. auto reset | Pulse time | | 1 s | Setting, System Password | |
| | Delay time | | 1 s | Setting, System Password | |
| | Max. No. attempts | | 0, 1, 2, 3 | Setting, System Password | |
| Level-sensor check | At high-level float | | OFF, ON | Setting, System Password | |
| | Level at high float | | 0.01 m, 0.01 ft | Setting, System Password | |
| | Max. deviation +/- | | 0.01 m, 0.01 ft | Setting, System Password | |
| | At low-level float | | OFF, ON | Setting, System Password | |
| | Level at low float | | 0.01 m, 0.01 ft | Setting, System Password | |
| | Max. deviation +/- | | 0.01 m, 0.01 ft | Setting, System Password | |
| | Level change check | | OFF, ON | Setting, System Password | |
| | Level change time | | 1 s | Setting, System Password | |
| Tariff control | Min. level change +/- | | 0.01 m, 0.01 ft | Setting, System Password | |
| | Tariff control | | OFF, ON | Setting, System Password | |
| | Lead time | | 1 min | Setting, System Password | |
| | Pump down level | | 0.01 m, 0.01 ft | Setting, System Password | |
| | Peak Monday | Peak time 1 ON | | 1 min, displayed as hh:mm | Setting, System Password |
| | | Peak time 1 OFF | | 1 min, displayed as hh:mm | Setting, System Password |
| | | Peak time 2 ON | | 1 min, displayed as hh:mm | Setting, System Password |
| | | Peak time 2 OFF | | 1 min, displayed as hh:mm | Setting, System Password |
| Peak Tuesday - Sunday = Menu selection, Identical to above. | | | | | |
| Level above sea | Set level | | 0.01 m, 0.01 ft | Setting, System Password | |

5.23 Settings: Pumps

Table 5.23 shows the complete list of **Pump settings**.

Table 5.23

| Submenu | Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | |
|--------------|-----------------|---------------------------|------------------|---------|---------------------------|--------------------------|--------------------------|
| Common P1-P6 | Log pump events | | | | NO, YES | Setting, System Password | |
| | Pump exercising | Max. standstill time | | | 1 min, displayed as hh:mm | Setting, System Password | |
| | | Running time | | | 1 s | Setting, System Password | |
| | | Start if level > | | | 0.01 m, 0.01 ft | Setting, System Password | |
| | Pump exercising | Start if level < | | | 0.01 m, 0.01 ft | Setting, System Password | |
| | | Exercise P1 | | | NO, YES | Setting, System Password | |
| | | Exercise P2 | | | NO, YES | Setting, System Password | |
| | | Exercise P3 | | | NO, YES | Setting, System Password | |
| | | Exercise P4 | | | NO, YES | Setting, System Password | |
| | | Exercise P5 | | | NO, YES | Setting, System Password | |
| | | Exercise P6 | | | NO, YES | Setting, System Password | |
| | Pump reversing | Enable per pump | Reversing P1 | | | NO, YES | Setting, System Password |
| | | | Reversing P2 | | | NO, YES | Setting, System Password |
| | | | Reversing P3 | | | NO, YES | Setting, System Password |
| | | | Reversing P4 | | | NO, YES | Setting, System Password |
| | | | Reversing P5 | | | NO, YES | Setting, System Password |
| | | | Reversing P6 | | | NO, YES | Setting, System Password |
| | | Start reverse delay | | | | 1 s | Setting, System Password |
| | | Reverse run time | | | | 1 s | Setting, System Password |
| | | Max. No. attempts | | | | 0, 1, 2, 3, 4, 5 | Setting, System Password |
| | | Max. attempts reset time | | | | 1 min | Setting, System Password |
| | | Max. attempts block time | | | | 1 h | Setting, System Password |
| | | Manual reverse reset | | | | NO, YES | Setting, System Password |
| | | Stop other pumps | | | | NO, YES | Setting, System Password |
| | | Pump relay when rev. | | | | OFF, ON | Setting, System Password |
| | | Rev. on pump fail | | | | NO, YES | Setting, System Password |
| | | Rev. on fallen m.prot. | | | | NO, YES | Setting, System Password |
| | | Rev. on overcurrent | | | | NO, YES | Setting, System Password |
| | | Rev. on low pump capacity | | | | NO, YES | Setting, System Password |
| | | After No. starts | After No. starts | | | | NO, YES |

| Submenu | Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | | |
|--------------|-------------------------|--|-----------------------------|---------|-----------------|---------------------------|-----------------------------------|--------------------------|
| Common P1-P6 | Pump reversing | | Pump1 | | 1 [Unitless] | Setting, System Password | | |
| | | | Pump2 | | 1 [Unitless] | Setting, System Password | | |
| | | | Pump3 | | 1 [Unitless] | Setting, System Password | | |
| | | | Pump4 | | 1 [Unitless] | Setting, System Password | | |
| | | | Pump5 | | 1 [Unitless] | Setting, System Password | | |
| | | | Pump6 | | 1 [Unitless] | Setting, System Password | | |
| | Max. No. pumps running | Max. No. pumps running | | | | 1, 2, 3, 4, 5, 6 | Setting, System Password | |
| | | Emergency power mode | Max. No. pumps running | | | 1, 2, 3, 4, 5, 6 | Setting, System Password | |
| | | | Block P1 in emgcy.pwr. mode | | | NO, YES | Setting, System Password | |
| | | | Block P2 in emgcy.pwr. mode | | | NO, YES | Setting, System Password | |
| | | | Block P3 in emgcy.pwr. mode | | | NO, YES | Setting, System Password | |
| | | | Block P4 in emgcy.pwr. mode | | | NO, YES | Setting, System Password | |
| | | | Block P5 in emgcy.pwr. mode | | | NO, YES | Setting, System Password | |
| | | Block P6 in emgcy.pwr. mode | | | NO, YES | Setting, System Password | | |
| | Min. no pumps available | Min. no pumps available | | | | 1, 2, 3, 4, 5, 6 | Setting, System Password | |
| | Min. relay interval | Min. time | | | | 1 s | Setting, System Password | |
| | Pump alternation | Altern. function | | | | OFF, Normal, Asymmetrical | Setting, System Password | |
| | | Enable per pump | | Pump1 | | | NO, YES | Setting, System Password |
| | | | | Pump2 | | | NO, YES | Setting, System Password |
| | | | | Pump3 | | | NO, YES | Setting, System Password |
| | | | | Pump4 | | | NO, YES | Setting, System Password |
| | | | | Pump5 | | | NO, YES | Setting, System Password |
| | | | | Pump6 | | | NO, YES | Setting, System Password |
| | | One or none of lines below, depending on other settings. | | | | | | |
| | | Alternation after | | | | | Each pump stop, All pumps stopped | Setting, System Password |
| | | Run time ratio | | Pump1 | | | 1% | Setting, System Password |
| | | | | Pump2 | | | 1% | Setting, System Password |
| | | | Pump3 | | | 1% | Setting, System Password | |
| | | | Pump4 | | | 1% | Setting, System Password | |
| | Pump5 | | | | 1% | Setting, System Password | | |

| Submenu | Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | | |
|--------------|------------------------------|-----------------------------|-----------------------|---------|---------------------------|--------------------------|--------------------------|--------------------------|
| Common P1-P6 | Pump alternation | Run time ratio | Pump6 | | 1% | Setting, System Password | | |
| | | After cont. runtime | | | 1 min, displayed as hh:mm | Setting, System Password | | |
| | Pump blocking | Remote blocking | Remote blocking | | | OFF, ON | Setting, System Password | |
| | | | Block timeout | | | 1 s | Setting, System Password | |
| | | | Active | | | NO, YES | Setting, No Password | |
| | | Low-level float | Low-level float | | | OFF, ON | Setting, System Password | |
| | Pump blocking | Pressure blocking | Pressure blocking | | | OFF, ON | Setting, System Password | |
| | | Pressure blocking | Block delay | | | 1 s | Setting, System Password | |
| | | | Block pressure | | | 0.1 bar, 0.1 PSI | Setting, System Password | |
| | | | Block timeout | | | 1 s | Setting, System Password | |
| | | Power | Phase missing | | | | NO, YES | Setting, System Password |
| | | | Over voltage | | | | NO, YES | Setting, System Password |
| | | | Under voltage | | | | NO, YES | Setting, System Password |
| | | | Unbalanced voltage | | | | NO, YES | Setting, System Password |
| | | Pump pit valve | Pit valve error | | | | NO, YES | Setting, System Password |
| | | | Pit valve open error | | | | NO, YES | Setting, System Password |
| | | | Pit valve close error | | | | NO, YES | Setting, System Password |
| | | Manual rst. on hi pump temp | | | | NO, YES | Setting, System Password | |
| | | Pwr.mon. block off delay | | | | 1 s | Setting, System Password | |
| | | Calc. pump capacity | Function | | | | OFF, ON | Setting, System Password |
| | Min. level p.cap. calc. | | | | | 0.01 m, 0.01 ft | Setting, System Password | |
| | Start delay | | | | | 1 s | Setting, System Password | |
| | Calculation time | | | | | 1 s | Setting, System Password | |
| | Stop delay | | | | | 1 s | Setting, System Password | |
| | Static head | | | | | 0.01 m, 0.01 ft | Setting, System Password | |
| | Press. sens. inlet offset | | | | | 0.01 m, 0.01 ft | Setting, System Password | |
| | Max. level pump capac. calc. | | | | | 0.01 m, 0.01 ft | Setting, System Password | |
| | No. pump starts to alarm | | | | | 1 [Unitless] | Setting, System Password | |
| | Auto set warning thresh. @ | | | | | 1% | Setting, System Password | |
| | Auto set alarm thresh. @ | | | | | 1% | Setting, System Password | |

| Submenu | Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment |
|--------------|------------------------|--|--------------------------|---------------------------|--|--------------------------|
| Common P1-P6 | Calc. pump capacity | Station flow | Measurment parameters | Calculate inflow | OFF, ON | Setting, System Password |
| | | | | Pit shape | Rectangular, Conical | Setting, System Password |
| | | | | Inflow calc. interval | 1 s | Setting, System Password |
| | | | | Flow compensation 2 pumps | 1% | Setting, System Password |
| | | | | Flow compensation 3 pumps | 1% | Setting, System Password |
| | | | | Flow compensation 4 pumps | 1% | Setting, System Password |
| | Calc. pump capacity | Station flow | Measurment parameters | Flow compensation 5 pumps | 1% | Setting, System Password |
| | | | | Flow compensation 6 pumps | 1% | Setting, System Password |
| | | | Pit area | Level 0 | 0.01 m, 0.01 ft | Setting, System Password |
| | | | | Area 0 | 0.01 m ² , 0.01 ft ² | Setting, System Password |
| | | | | Level 1 | 0.01 m, 0.01 ft | Setting, System Password |
| | | | | Area 1 | 0.01 m ² , 0.01 ft ² | Setting, System Password |
| | | | | Level 2 | 0.01 m, 0.01 ft | Setting, System Password |
| | | | | Area 2 | 0.01 m ² , 0.01 ft ² | Setting, System Password |
| | | | | Level 3 | 0.01 m, 0.01 ft | Setting, System Password |
| | | | | Area 3 | 0.01 m ² , 0.01 ft ² | Setting, System Password |
| | | | | Level 4 | 0.01 m, 0.01 ft | Setting, System Password |
| | | | | Area 4 | 0.01 m ² , 0.01 ft ² | Setting, System Password |
| | | | | Level 5 | 0.01 m, 0.01 ft | Setting, System Password |
| | | | | Area 5 | 0.01 m ² , 0.01 ft ² | Setting, System Password |
| | | | | Level 6 | 0.01 m, 0.01 ft | Setting, System Password |
| | | | | Area 6 | 0.01 m ² , 0.01 ft ² | Setting, System Password |
| | | | | Level 7 | 0.01 m, 0.01 ft | Setting, System Password |
| | | | | Area 7 | 0.01 m ² , 0.01 ft ² | Setting, System Password |
| | | | | Level 8 | 0.01 m, 0.01 ft | Setting, System Password |
| | | | | Area 8 | 0.01 m ² , 0.01 ft ² | Setting, System Password |
| | Level 9 | 0.01 m, 0.01 ft | Setting, System Password | | | |
| | Area 9 | 0.01 m ² , 0.01 ft ² | Setting, System Password | | | |
| | Alternative stop level | After No. starts | | | 1 [Unitless] | Setting, System Password |
| | | Stop level | | | 0.01 m, 0.01 ft | Setting, System Password |
| Stop delay | | | | 1 s | Setting, System Password | |

| Submenu | Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | |
|--------------|----------------------|-----------------------------|--|---------|--|---|--------------------------|
| Common P1-P6 | Start on fast change | Start on fast change | | | OFF, ON | Setting, System Password | |
| | | Start level change | | | 0.01 m, 0.01 ft | Setting, System Password | |
| | | Per | | | 1 min | Setting, System Password | |
| | | Min. No. pumps running | | | 0, 1, 2, 3, 4, 5, 6 | Setting, System Password | |
| | | Max. No. pumps running | | | 0, 1, 2, 3, 4, 5, 6 | Setting, System Password | |
| | | Stop on fast change | | | OFF, ON | Setting, System Password | |
| | | Stop level change | | | 0.01 m, 0.01 ft | Setting, System Password | |
| | Per | Per | Per | | | 1 min | Setting, System Password |
| | | | Min. No. pumps running | | | 0, 1, 2, 3, 4, 5, 6 | Setting, System Password |
| | | | Max. No. pumps running | | | 0, 1, 2, 3, 4, 5, 6 | Setting, System Password |
| | Backup running | Backup running | Running time | | | 1 s | Setting, System Password |
| | | | Pump 1 backup start | | | OFF, ON | Setting, System Password |
| | | | Pump 2 backup start | | | OFF, ON | Setting, System Password |
| | | | Pump 3 backup start | | | OFF, ON | Setting, System Password |
| | | | Pump 4 backup start | | | OFF, ON | Setting, System Password |
| | | | Pump 5 backup start | | | OFF, ON | Setting, System Password |
| | | | Pump 6 backup start | | | OFF, ON | Setting, System Password |
| Pump1 | Copy pump setup from | | | | None, Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6, Default | Status value | |
| | Pump control | Type of pump control | | | Pump disabled, On/Off control, VFD manual speed, VFD PID control, VFD Best effic. point | Setting, System Password | |
| | | Select run indication | | | Any discrete source, Output signal, Digital inputs, Motor current, Field bus modules (RS485) | Setting, System Password | |
| | | Current threshold (if apl.) | | | 0.1 A | Setting, System Password | |
| | | Pwr.mon. | Slave ID | | | 1 [Unitless] | Setting, System Password |
| | | | Bus selection | | | RS485 port 1, RS485 port 2 | Setting, System Password |
| | | | Manufacturer | | | None, Accuenergy, Schneider, Lumel, Carlo Gavazzi | Setting, System Password |
| | | | One or none of lines below, depending on manufacturer settings | | | | |
| | | | Model | | | None, Acuvim II | Setting, System Password |
| | | | Model | | | None, PM 710, PM 5110 | Setting, System Password |

| Submenu | Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | |
|-------------------|-------------------|-------------------------|-------------------------|---------|-----------------|---------------------------|----------------------------|
| Pump1 | Pump control | Pwr.mon. | Model | | None, ND 10 | Setting, System Password | |
| | | | Model | | None, EM210 | Setting, System Password | |
| | | | Alarm com. error | | | | |
| | Start/stop levels | Start level | Stop level | | | 0.01 m, 0.01 ft | Setting, Operator Password |
| | | | Stop level | | | 0.01 m, 0.01 ft | Setting, Operator Password |
| | | | Random start range+- | | | 0.01 m, 0.01 ft | Setting, Operator Password |
| | Start/stop levels | Start level high tariff | Stop level high tariff | | | 0.01 m, 0.01 ft | Setting, Operator Password |
| | | | Stop level high tariff | | | 0.01 m, 0.01 ft | Setting, Operator Password |
| | | | Random start range+- | | | 0.01 m, 0.01 ft | Setting, Operator Password |
| | | | Alternative stop level | | | OFF, ON | Setting, Operator Password |
| | Time settings | Threshold-on delay | Threshold-off delay | | | 1 s | Setting, System Password |
| | | | Threshold-off delay | | | 1 s | Setting, System Password |
| | | | Max. cont. runtime | | | 1 min, displayed as hh:mm | Setting, System Password |
| | Pump curve (QH) | Point 1 head (max.) | Point 1 flow (min.) | | | 0.01 m, 0.01 ft | Setting, System Password |
| | | | Point 1 flow (min.) | | | 0.1 l/s, 1 GPM | Setting, System Password |
| | | | Point 2 head (mid.) | | | 0.01 m, 0.01 ft | Setting, System Password |
| | | | Point 2 flow (mid.) | | | 0.1 l/s, 1 GPM | Setting, System Password |
| | | | Point 3 head (min.) | | | 0.01 m, 0.01 ft | Setting, System Password |
| | | | Point 3 flow (max.) | | | 0.1 l/s, 1 GPM | Setting, System Password |
| | | | Total head | | | 0.01 m, 0.01 ft | Setting, System Password |
| | | | Pump curve Q-H exponent | | | 0.0001 [Unitless] | Status value |
| | Pump alarms | No run indication | Fallen motor prot. | | | | |
| | | | Motor prot. reset error | | | | |
| | | | Not in auto | | | | |
| | | | DI pump error | | | | |
| | | | Max. run time | | | | |
| | | | Alarm blocked | | | | |
| | | | Max. reverse attempts | | | | |
| | | | Phase missing | | | | |
| | | | Pump valve error | | | | |
| Valve open error | | | | | | | |
| Valve close error | | | | | | | |
| Low pump capacity | | | Alarm | | | | |
| | | | Warning | | | | |

| Submenu | Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | |
|-------------------|---------------------|--------------------|-----------------------------|---------|---|--------------------------|--------------------------|
| Pump1 | Pump alarms | Low pump capacity | Auto-set low cap. threshold | | Inactive, Trigger auto-set, Auto-set running | Setting, System Password | |
| | | | Auto-set calc. counter | | 1 [Unitless] | Setting, System Password | |
| | | | Auto sequence options | | Inactive, Detect ramp-up time, Forced auto sequence, Both options | Setting, System Password | |
| | | | Pump cap. calc. start delay | | 1 s | Setting, System Password | |
| | | | High vibrations | | | | |
| | | Leakage | Generic | | | | |
| | | | Oil chamber | | | | |
| | | | Motor housing | | | | |
| | | | Electr. con. box | | | | |
| | | High temperature | Generic | | | | |
| | | | Stator L1 | | | | |
| | | | Stator L2 | | | | |
| | | | Stator L3 | | | | |
| | | | Upper bearing | | | | |
| | | Lower bearing | | | | | |
| | High motor current | | | | | | |
| | Low motor current | | | | | | |
| | Block pump on alarm | High temperature | Generic | | | NO, YES | Setting, System Password |
| | | | Stator L1 | | | NO, YES | Setting, System Password |
| | | | Stator L2 | | | NO, YES | Setting, System Password |
| | | | Stator L3 | | | NO, YES | Setting, System Password |
| | | | Upper bearing | | | NO, YES | Setting, System Password |
| | | | Lower bearing | | | NO, YES | Setting, System Password |
| | | Leakage | Generic | | | NO, YES | Setting, System Password |
| | | | Oil chamber | | | NO, YES | Setting, System Password |
| | | | Motor housing | | | NO, YES | Setting, System Password |
| | | | Electr. con. box | | | NO, YES | Setting, System Password |
| | | High motor current | | | | NO, YES | Setting, System Password |
| | | Fallen motor prot. | | | | NO, YES | Setting, System Password |
| | | No run indication | | | | NO, YES | Setting, System Password |
| DI pump error | | | | | NO, YES | Setting, System Password | |
| High vibrations | | | | | NO, YES | Setting, System Password | |
| Pump valve error | | | | | NO, YES | Setting, System Password | |
| Valve open error | | | | NO, YES | Setting, System Password | | |
| Valve close error | | | | NO, YES | Setting, System Password | | |

| Submenu | Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment |
|---|-----------------------|------------------------------|------------------|---------------|--------------------------|--------------------------|
| Pump1 | Hold pump on alarm | Temperature | Generic | | NO, YES | Setting, System Password |
| | | | Stator L1 | | NO, YES | Setting, System Password |
| | | | Stator L2 | | NO, YES | Setting, System Password |
| | | | Stator L3 | | NO, YES | Setting, System Password |
| | | | Upper bearing | | NO, YES | Setting, System Password |
| | | | Lower bearing | | NO, YES | Setting, System Password |
| | Hold pump on alarm | Leakage | Generic | | NO, YES | Setting, System Password |
| | | | Oil chamber | | NO, YES | Setting, System Password |
| | | | Motor housing | | NO, YES | Setting, System Password |
| | | | Electr. con. box | | NO, YES | Setting, System Password |
| | | Vibration | | | NO, YES | Setting, System Password |
| | Best efficiency point | Start at max., every x start | | | 1 [Unitless] | Setting, System Password |
| | | Max. freq. run time | | | 1 s | Setting, System Password |
| | | Max. freq. if all pump run | | | NO, YES | Setting, System Password |
| | | All pumps max. freq. delay | | | 1 s | Setting, System Password |
| | | Max. freq. on hi lvi alarm | | | NO, YES | Setting, System Password |
| | Pump valve | Pump open delay | | | 1 s | Setting, System Password |
| | | Pump close delay | | | 1 s | Setting, System Password |
| | | Max. time to open | | | 1 s | Setting, System Password |
| | | Max. time to close | | | 1 s | Setting, System Password |
| | | Max. time to reopen | | | 1 s | Setting, System Password |
| Close retry delay time | | | | 1 s | Setting, System Password | |
| Tag name | | | | [Text String] | Setting, System Password | |
| Pump2 - Pump3 = Menu selection, Identical to above. | | | | | | |

5.24 Settings: Clock functions

Table 5.24 shows the complete list of **Clock functions settings**.

Table 5.24

| Submenu | Submenu | Setting | Submenu | Submenu | Setting / Value | Comment | | |
|-------------|--------------|------------|--|-----------|-----------------|---|--------------------------|-------------------------------------|
| Time relays | Time relay 1 | Active | | | OFF, ON | Setting, System Password | | |
| | | Sequence 1 | Interval base | | | OFF, Day, Week, Month-date, 1st week of month, 2nd week of month, 3rd week of month, 4th week of month, 5th week of month | Setting, System Password | |
| | | | One or none of lines below, depending on other settings. | | | | | |
| | | | Repeat every... | | | day, 2nd day, 3rd day, 4th day, 5th day, 6th day, 7th day | Setting, System Password | |
| | | | Repeat every... | | | week, 2nd week, 3rd week, 4th week, 5th week | Setting, System Password | |
| | | | Repeat every... | January | | | OFF, ON | Setting, System Password |
| | | | | February | | | OFF, ON | Setting, System Password |
| | | | | March | | | OFF, ON | Setting, System Password |
| | | | | April | | | OFF, ON | Setting, System Password |
| | | | | May | | | OFF, ON | Setting, System Password |
| | | | | June | | | OFF, ON | Setting, System Password |
| | | | | July | | | OFF, ON | Setting, System Password |
| | | | | August | | | OFF, ON | Setting, System Password |
| | | | | September | | | OFF, ON | Setting, System Password |
| | | | | October | | | OFF, ON | Setting, System Password |
| | | | | November | | | OFF, ON | Setting, System Password |
| | | | | December | | | OFF, ON | Setting, System Password |
| | | | Repeat every... | | | | | Menu selection, identical to above. |
| | | | One or none of lines below, depending on other settings. | | | | | |
| | | | Turn on day(s) | Monday | | | OFF, ON | Setting, System Password |
| | | | | Tuesday | | | OFF, ON | Setting, System Password |
| | | Wednesday | | | | OFF, ON | Setting, System Password | |
| | | Thursday | | | | OFF, ON | Setting, System Password | |
| | | Friday | | | | OFF, ON | Setting, System Password | |
| | | Saturday | | | | OFF, ON | Setting, System Password | |
| | | Sunday | | | | OFF, ON | Setting, System Password | |

| Submenu | Submenu | Setting | Submenu | Submenu | Setting / Value | Comment | |
|---|--------------------|--|----------------|---------|--|---------------------------------------|--------------------------|
| Time relays | Time relay 1 | Sequence 1 | Turn on day(s) | | 1 [Unitless] | Setting, System Password | |
| | | | Turn on day(s) | | | Menu selection, Identical to above. | |
| | | | Turn on time | | 1 s, displayed as h:m:s | Setting, System Password | |
| | | | Duration | | 1 d | Setting, System Password | |
| | | | Duration | | 1 s, displayed as h:m:s | Setting, System Password | |
| | | Sequence 2 - 4 = Menu selection, with preview, identical to above. | | | | | |
| | | Tag name | | | | [Text String] | Setting, System Password |
| Time relay 2 - 8 = Menu selection, with preview, identical to above. | | | | | | | |
| Count down timers | Count down timer 1 | Trigger source | | | OFF, DI on, DI off, IO on, IO off, Reg. not equal (!=), Reg. less than (<), Reg. less or equal to (<=), Reg. equal to (==), Reg. more or equal to (>=), Reg. more than (>) | Setting, System Password | |
| Count down timers | Count down timer 1 | One or none of lines below, depending on other settings. | | | | | |
| | | Module | | | | 1, 2, 3, 4, 5, 6, 7, 8, 9 | Setting, System Password |
| | | IO number | | | | 1 [Unitless] | Setting, System Password |
| | | Data register | | | | 1 [Unitless] | Setting, System Password |
| | | One or none of lines below, depending on other settings. | | | | | |
| | | Signal source | | | | 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12 | Setting, System Password |
| | | Threshold value | | | | 1 [Unitless] | Setting, System Password |
| | | Repetition(s) | | | | Continuous, 1, 2, 3, 4, 5, 6, 7, 8, 9 | Setting, System Password |
| | | Duration | | | | 1 s, displayed as h:m:s | Setting, System Password |
| | | Tag name | | | | [Text String] | Setting, System Password |
| Count down timer 2 - 12 = Menu selection, with preview, identical to above. | | | | | | | |

5.25 Settings: IO-bit controlled data

Table 5.25 shows the complete list of IO-bit controlled data settings.

Table 5.25

| Submenu | Submenu | Setting / Value | Comment |
|---|-----------------------------|---------------------------|--------------------------|
| IO controlled data 1 | Register control | OFF, ON | Setting, System Password |
| | IO number | 1 [Unitless] | Setting, System Password |
| | Controls data register | 1 [Unitless] | Setting, System Password |
| | Source data when IO off (0) | Data value, Data register | Setting, System Password |
| | Data when IO off (0) | 1 [Unitless] | Setting, System Password |
| | Source data when IO on (1) | Data value, Data register | Setting, System Password |
| | Data when IO on (1) | 1 [Unitless] | Setting, System Password |
| IO controlled data 2 - 32 = Menu selection, with preview, identical to above. | | | |

5.27 Settings: PID regulator

Table 5.27 shows the complete list of **PID regulator settings**.

Table 5.27

| Submenu | Setting / Value | Comment |
|------------------------------|--|--------------------------|
| Extern setpoint input | OFF, AI1, AI2, AI3, AI4, AI5, AI6 | Setting, System Password |
| AI Module | 1, 2, 3, 4, 5, 6, 7, 8, 9 | Setting, System Password |
| Setpoint tracking | NO, YES | Setting, System Password |
| Setpoint when start | Last, Setup start, External | Setting, System Password |
| Max. setpoint | 0.01 m, 0.01 ft | Setting, System Password |
| Min. setpoint | 0.01 m, 0.01 ft | Setting, System Password |
| Setpoint | 0.01 m, 0.01 ft | Setting, System Password |
| Setpoint high tariff | 0.01 m, 0.01 ft | Setting, System Password |
| Start setpoint | 0.01 m, 0.01 ft | Setting, System Password |
| Output state when start | Last state, AUTO, MANUAL, Internally blocked | Setting, System Password |
| Output when blocked | Freeze output, Setup block signal | Setting, System Password |
| Block output | 0.1 % | Setting, System Password |
| Max. output change | 0.1 %/s | Setting, System Password |
| Max. output | 0.1 % | Setting, System Password |
| Min. output | 0.1 % | Setting, System Password |
| Start output | 0.1 % | Setting, System Password |
| Direct/Reverse effect | Reverse, Direct | Setting, System Password |
| P-Band | 0.001 [Unitless] | Setting, System Password |
| I-Time | 0.01 s | Setting, System Password |
| D-Time | 0.01 s | Setting, System Password |
| Zero deviation output | 0.1 % | Setting, System Password |
| Calc. pump cap. @ max. speed | NO, YES | Setting, System Password |
| Min. speed | 0.1 % | Setting, System Password |
| Locked speed pumping out | 0.1 % | Setting, System Password |
| Lock speed delay | 1 s | Setting, System Password |

5.28 Settings: Pulse channels

Table 5.28 shows the complete list of **Pulse channel settings**.

Table 5.28

| Submenu | Submenu | Setting / Value | Comment |
|-------------|---|------------------------------------|--------------------------|
| Pulse ch. 1 | Function | Precipitation, Energy, Flow | Setting, System Password |
| | One or none of lines below, depending on other settings. | | |
| | 1 Pulse | 0.0001 mm, 0.0001 in | Setting, System Password |
| | 1 Pulse | 0.0001 kWh | Setting, System Password |
| | 1 Pulse | 0.0001 m ³ , 0.0001 gal | Setting, System Password |
| | One or none of lines below, depending on other settings. | | |
| | Set high alarm | | |
| | Set high alarm | | |
| | Set high alarm | | |
| | One or none of lines below, depending on other settings. | | |
| | Set low alarm | | |
| | Pulse ch. 2 - 4 = Menu selection, with preview, identical to above. | | |

5.29 Settings: Analog logging

Table 5.29 shows the complete list of **Analog logging settings**.

Table 5.29

| Submenu | Submenu | Setting / Value | Comment | |
|--|--|---|--------------------------|--|
| Log channel 1 | Log signal | OFF, Level pit, Inflow pit, Outflow, Overflow level, Overflow flow, Outlet pressure, Motor current, Pump capacity, Power factor, Temperature motor, Temp. stator wiring L1, Temp. stator wiring L2, Temp. stator wiring L3, Temp. upper bearing, Temp. lower bearing, Vibration, Main voltage, Main frequency, Free choice AI, Free choice RTD, Power supply, Pulse channel 1-4, PID controller output, Data register, Data register 2 compl., Set frequency, Actual frequency, Motor power, Motor voltage, Torque, Outflow meter, Total head, PCB temperature EC 541, BEP frequency, BEP efficiency, Mains power, Actual head, Secondary pit level, Pit level difference | Setting, System Password | |
| | Log function | Closed, Actual value, Average value, Min. value, Max. value | Setting, System Password | |
| | Log interval | 1 min | Setting, System Password | |
| | One or none of lines below, depending on other settings. | | | |
| | Object | Pump pit, Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6 | Setting, System Password | |
| | Analog input number (1-6) | 1, 2, 3, 4, 5, 6 | Setting, System Password | |
| | Object | Pulse channel 1, Pulse channel 2, Pulse channel 3, Pulse channel 4 | Setting, System Password | |
| | Data register number | 1 [Unitless] | Setting, System Password | |
| | Object | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6 | Setting, System Password | |
| | One or none of lines below, depending on other settings. | | | |
| AI Module | 1, 2, 3, 4, 5, 6, 7, 8, 9 | Setting, System Password | | |
| Log channel 2 - 32 = Menu selection, with preview, identical to above. | | | | |

5.30 Settings: Inputs and outputs

Table 5.30 shows the complete list of **Inputs and output settings**.

Table 5.30

| Submenu | Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | |
|---------------|---|----------|---|---------|--|--|--------------------------|
| Analog inputs | Module 1 | Module 1 | | | -Not connected-, -Reconnecting-, -Not connected-, -Connected-, -Error-, -Error-, -Not connected-, CAN ID error, CAN ID error | Status value | |
| | | | Signal function | | OFF, Pit level, Motor current, Outlet pressure, Vibrations, Outflow meter, Motor temperature, Secondary pit level, Free choice | Setting, System Password | |
| | Module 1 | AI1 | One or none of lines below, depending on port function. | | | | |
| | | | Measure point | | | Generic, Stator L1, Stator L2, Stator L3, Upper bearing, Lower bearing | Setting, System Password |
| | | | One or none of lines below, depending on port function. | | | | |
| | | | Object | | | Pump pit, Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6 | Setting, System Password |
| | | | Object | | | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6 | Setting, System Password |
| | One or none of lines below, depending on port function. | | | | | | |

| Submenu | Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment |
|---------------|----------|---------|----------|----------------------------|-----------------------------------|--------------------------|
| Analog inputs | Module 1 | AI1 | Settings | Scaling 0% | 0.01 m, 0.01 ft | Setting, System Password |
| | | | | Scaling 100% | 0.01 m, 0.01 ft | Setting, System Password |
| | | | | Filter constant | 1 s | Setting, System Password |
| | | | | Zero offset | 0.01 m, 0.01 ft | Setting, System Password |
| | | | | Dead band | 0.1 % | Setting, System Password |
| | | | | Set sensor/ cable alarm | | |
| | | | | Scaling 0% | 0.1 A | Setting, System Password |
| | | | | Scaling 100% | 0.1 A | Setting, System Password |
| | | | | Filter constant | 1 s | Setting, System Password |
| | | | | Zero offset | 0.1 A | Setting, System Password |
| | | | | Dead band | 0.1 % | Setting, System Password |
| | | | | Set sensor/ cable alarm | | |
| | | | | Scaling 0% | 0.1 bar, 0.1 PSI | Setting, System Password |
| | | | | Scaling 100% | 0.1 bar, 0.1 PSI | Setting, System Password |
| | | | | Filter constant | 1 s | Setting, System Password |
| | | | | Zero offset | 0.1 bar, 0.1 PSI | Setting, System Password |
| | | | | Dead band | 0.1 % | Setting, System Password |
| | | | | Set sensor/ cable alarm | | |
| | | | | Scaling 0% | 0.1 mm/s ² , 0.01 in/h | Setting, System Password |
| | | | | Scaling 100% | 0.1 mm/s ² , 0.01 in/h | Setting, System Password |
| | | | | Filter constant | 1 s | Setting, System Password |
| | | | | Zero offset | 0.1 mm/s ² , 0.01 in/h | Setting, System Password |
| | | | | Dead band | 0.1 % | Setting, System Password |
| | | | | Set sensor/ cable alarm | | |
| | | | | Scaling 0% | 0.1 l/s, 1 GPM | Setting, System Password |
| | | | | Scaling 100% | 0.1 l/s, 1 GPM | Setting, System Password |
| | | | | Filter constant | 1 s | Setting, System Password |
| | | | | Zero offset | 0.1 l/s, 1 GPM | Setting, System Password |
| | | | | Dead band | 0.1 % | Setting, System Password |
| | | | | Set sensor/ cable alarm | | |
| | | | | Scaling 0% | 0.1 °C, 0.1 °F | Setting, System Password |
| | | | | Scaling 100% | 0.1 °C, 0.1 °F | Setting, System Password |
| | | | | Filter constant | 1 s | Setting, System Password |

| Submenu | Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | | | |
|------------------|----------|---|--|----------------------------|---|--------------------------|--|--|--|
| Analog inputs | Module 1 | AI1 | Settings | Zero offset | 0.1 °C, 0.1 °F | Setting, System Password | | | |
| | | | | Dead band | 0.1 % | Setting, System Password | | | |
| | | | | Set sensor/ cable alarm | | | | | |
| | | | | Scaling 0% | 0.01 m, 0.01 ft | Setting, System Password | | | |
| | | | | Scaling 100% | 0.01 m, 0.01 ft | Setting, System Password | | | |
| | | | | Filter constant | 1 s | Setting, System Password | | | |
| | | | | Zero offset | 0.01 m, 0.01 ft | Setting, System Password | | | |
| | | | | Dead band | 0.1 % | Setting, System Password | | | |
| | | | | Set sensor/ cable alarm | | | | | |
| | | | | Designation | [Text String] | Setting, System Password | | | |
| | | | | No. of decimals | 1 [Unitless] | Setting, System Password | | | |
| | | | | Select units | [Text String] | Setting, System Password | | | |
| | | | | Scaling 0% | [User defined Unit] | Setting, System Password | | | |
| | | | | Scaling 100% | [User defined Unit] | Setting, System Password | | | |
| | | | | Filter constant | 1 s | Setting, System Password | | | |
| | | | | Zero offset | [User defined Unit] | Setting, System Password | | | |
| | | | | Dead band | 0.1 % | Setting, System Password | | | |
| | | | | Set high alarm | | | | | |
| | | | | Set hi-high alarm | | | | | |
| | | | | Set low alarm | | | | | |
| | | | Set low-low alarm | | | | | | |
| | | | Set sensor/ cable alarm | | | | | | |
| | | | One or none of lines below, depending on port function. | | | | | | |
| | | | Current value | | 0.1 A | Status value | | | |
| | | | Current value | | 0.1 bar, 0.1 PSI | Status value | | | |
| | | | Current value | | 0.1 mm/s ² , 0.01 in/h | Status value | | | |
| | | | Current value | | 0.1 l/s, 1 GPM | Status value | | | |
| | | | Current value | | 0.1 °C, 0.1 °F | Status value | | | |
| | | | Current value | | 0.01 m, 0.01 ft | Status value | | | |
| | | | Current value | | [User defined Unit] | Status value | | | |
| | | | Current | | 0.01 mA | Status value | | | |
| | | | AI2 - AI6 = Menu selection, with preview, identical to above. | | | | | | |
| | | | Module 2 - 9 = Menu selection, with preview, identical to above. | | | | | | |
| RTD temp. inputs | Module 1 | Module 1 | | | -Not connected-, -Reconnecting-, -Not connected-, -Connected-, -Error-, -Error-, -Not connected-, CAN ID error, CAN ID error | Status value | | | |
| | | RTD1 | Signal function | | OFF, Motor temperature, Free choice | Setting, System Password | | | |
| | | | Signal type | | Pt100 (temp. sensor), PTC/ Bimetal switch | Setting, System Password | | | |
| | | One or none of lines below, depending on port function. | | | | | | | |

| Submenu | Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | | |
|--|----------|---|--|-------------------------|--|--|--------------------------|--|
| RTD temp. inputs | Module 1 | RTD1 | Object | | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6 | Setting, System Password | | |
| | | | One or none of lines below, depending on port function. | | | | | |
| | | | Object | | Generic, Stator L1, Stator L2, Stator L3, Upper bearing, Lower bearing | Setting, System Password | | |
| | | | One or none of lines below, depending on other settings. | | | | | |
| | | | One or none of lines below, depending on port function. | | | | | |
| | | | Settings | Filter constant | 1 s | Setting, System Password | | |
| | | | | Zero offset | 0.1 °C, 0.1 °F | Setting, System Password | | |
| | | | | Set sensor/ cable alarm | | | | |
| | | | | Designation | [Text String] | Setting, System Password | | |
| | | | | Filter constant | 1 s | Setting, System Password | | |
| | | | | Zero offset | 0.1 °C, 0.1 °F | Setting, System Password | | |
| | | | | Set high alarm | | | | |
| | | | | Set hi-high alarm | | | | |
| | | | | Set low alarm | | | | |
| | | Set sensor/ cable alarm | | | | | | |
| | | One or none of lines below, depending on port function. | | | | | | |
| | | Settings | Designation | [Text String] | Setting, System Password | | | |
| | | RTD1 | One or none of lines below, depending on other settings. | | | | | |
| | | | Current value | 0.1 °C, 0.1 °F | Status value | | | |
| | | | Current value | -OK-, -Tripped- | Status value | | | |
| | | RTD2 - RTD6 = Menu selection, with preview, identical to above. | | | | | | |
| Module 2 - 9 = Menu selection, with preview, identical to above. | | | | | | | | |
| Analog outputs | Module 1 | Module 1 | | | -Not connected-, -Reconnecting-, -Not connected-, -Connected-, -Error-, -Error-, -Not connected-, CAN ID error, CAN ID error | Status value | | |
| | | | AO1 | Signal function | | OFF, Pit level, Pit inflow, Pit outflow, Pit overflow, Pulse channel 1, Pulse channel 2, Pulse channel 3, Pulse channel 4, PID control output, Data register, Data register 2 compl., Set freq. P1, Set freq. P2, Set freq. P3, Set freq. P4, Set freq. P5, Set freq. P6 | Setting, System Password | |
| | | Current value | | 0.01 mA | Status value | | | |
| | | Filter constant | | 1 s | Setting, System Password | | | |
| | | One or none of lines below, depending on port function. | | | | | | |
| | | Settings | | Scaling 0% | 0.01 m, 0.01 ft | Setting, System Password | | |
| | | | | Scaling 100% | 0.01 m, 0.01 ft | Setting, System Password | | |
| | | | | Scaling 0% | 0.1 l/s, 1 GPM | Setting, System Password | | |
| | | | | Scaling 100% | 0.1 l/s, 1 GPM | Setting, System Password | | |
| | | | | Scaling 0% | 0.1 m3/h, 1 GPM | Setting, System Password | | |
| | | | | Scaling 100% | 0.1 m3/h, 1 GPM | Setting, System Password | | |
| | | One or none of lines below, depending on other settings. | | | | | | |

| Submenu | Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | | | |
|--|---------------------|---------|-----------------|--|---|--|--------------------------|--|--|
| Analog outputs | Module 1 | AO1 | Settings | Scaling 0% | 0.1 l/s/ha, 0.1 in/h | Setting, System Password | | | |
| | | | | Scaling 100% | 0.1 l/s/ha, 0.1 in/h | Setting, System Password | | | |
| | | | | Scaling 0% | 0.1 kW | Setting, System Password | | | |
| | | | | Scaling 100% | 0.1 kW | Setting, System Password | | | |
| | | | | Scaling 0% | 0.1 m3/h, 1 GPM | Setting, System Password | | | |
| | | | | Scaling 100% | 0.1 m3/h, 1 GPM | Setting, System Password | | | |
| | | | | Set data register | 1 [Unitless] | Setting, System Password | | | |
| | | | | Scaling 0% | 1 [Unitless] | Setting, System Password | | | |
| | | | | Scaling 100% | 1 [Unitless] | Setting, System Password | | | |
| | | | | Set data register | 1 [Unitless] | Setting, System Password | | | |
| | | | | Scaling 0% | 1 [Unitless] | Setting, System Password | | | |
| | | | | Scaling 100% | 1 [Unitless] | Setting, System Password | | | |
| | | | | Scaling 0% | 0.01 Hz | Setting, System Password | | | |
| | | | | Scaling 100% | 0.01 Hz | Setting, System Password | | | |
| AO2 - AO6 = Menu selection, with preview, identical to above. | | | | | | | | | |
| Module 2 - 9 = Menu selection, with preview, identical to above. | | | | | | | | | |
| Digital inputs | Local at controller | DI1 | Signal function | | OFF, Run indication, Manual start, Set manual, Set auto, Start float, Pump failure, Motor protector, High motor temp. pump, Leakage pump, Stop float, Low level float, Overflow sensor, High level float, Start float drain pump, Local mode, Alarm reset, Power fail, DI pulse channel 1-4, Block PID controller, Alarm input, Block operation, Leakage mixer-drain pump, High temp. mixer-drain p., Emergency power mode, Block remote data, Ackn. pump alarms, Valve open, Valve close | Setting, System Password | | | |
| | | | | One or none of lines below, depending on port function. | | | | | |
| | | | | One or none of lines below, depending on other settings. | | | | | |
| | | | | Pulses ch1 | | 1 [Unitless] | Status value | | |
| | | | | Pulses ch2 | | 1 [Unitless] | Status value | | |
| | | | | Pulses ch3 | | 1 [Unitless] | Status value | | |
| | | | | Pulses ch4 | | 1 [Unitless] | Status value | | |
| | | | | Status | | -OFF-, -ON- | Status value | | |
| | | | | One or none of lines below, depending on port function. | | | | | |
| | | | | Measure point | | Generic, Stator L1, Stator L2, Stator L3, Upper bearing, Lower bearing | Setting, System Password | | |
| | | | | Measure point | | Generic, Oil chamber, Motor housing, Electr. con. box | Setting, System Password | | |
| | | | | One or none of lines below, depending on port function. | | | | | |
| | | | | Object | | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6 | Setting, System Password | | |
| | | | | Alarm reset delay | | 1 s | Setting, System Password | | |

| Submenu | Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | | |
|---|---------------------|---|--|--------------------------|--|---|--------------------------|--|
| Digital inputs | Local at controller | DI1 | Object | | Pulse channel 1, Pulse channel 2, Pulse channel 3, Pulse channel 4 | Setting, System Password | | |
| | | | Alarm settings | Alarm text | [Text String] | Setting, System Password | | |
| | | | Object | | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6, Mixer, Drain pump, All | Setting, System Password | | |
| | | | Object | | Mixer, Drain pump | Setting, No Password | | |
| | | | Allow set clock | | NO, YES | Setting, System Password | | |
| | | | Object | | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6, All | Setting, System Password | | |
| | | | Object | | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6, Pump pit | Setting, System Password | | |
| | | | Signal source | | NO input terminal, NC input terminal, True IO number, Inv. IO number | Setting, System Password | | |
| | | | One or none of lines below, depending on other settings. | | | | | |
| | | | IO number | | 1 [Unitless] | Setting, System Password | | |
| | Event trigger | | OFF, ON | Setting, System Password | | | | |
| | Local at controller | DI2 - DI4 = Menu selection, with preview, identical to above. | | | | | | |
| | Module 1 | Module 1 | Module 1 | | | -Not connected-, -Reconnecting-, -Not connected-, -Connected-, -Error-, -Error-, -Not connected-, CAN ID error, CAN ID error | Status value | |
| | | | | Signal function | | OFF, Run indication, Manual start, Set manual, Set auto, Start float, Pump failure, Motor protector, High motor temp. pump, Leakage pump, Stop float, Low level float, Overflow sensor, High level float, Start float drain pump, Local mode, Alarm reset, Power fail, DI pulse channel 1-4, Block PID controller, Alarm input, Block operation, Leakage mixer-drain pump, High temp. mixer-drain p., Emergency power mode, Block remote data, Ackn. pump alarms, Valve open, Valve close | Setting, System Password | |
| | | One or none of lines below, depending on port function. | | | | | | |
| | | One or none of lines below, depending on other settings. | | | | | | |
| | | Pulses ch1 | | 1 [Unitless] | Status value | | | |
| | | Pulses ch2 | | 1 [Unitless] | Status value | | | |
| | | Pulses ch3 | | 1 [Unitless] | Status value | | | |
| | | Pulses ch4 | | 1 [Unitless] | Status value | | | |
| Status | | | -OFF-, -ON- | Status value | | | | |
| One or none of lines below, depending on port function. | | | | | | | | |
| Measure point | | | Generic, Stator L1, Stator L2, Stator L3, Upper bearing, Lower bearing | Setting, System Password | | | | |
| Measure point | | | Generic, Oil chamber, Motor housing, Electr. con. box | Setting, System Password | | | | |
| One or none of lines below, depending on port function. | | | | | | | | |
| Object | | | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6 | Setting, System Password | | | | |
| Alarm reset delay | | 1 s | Setting, System Password | | | | | |

| Submenu | Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | | | |
|--|---------------------|---------|--|-----------------------|---|---|--------------------------|--|--|
| Digital inputs | Module 1 | DI1 | Object | | Pulse channel 1, Pulse channel 2, Pulse channel 3, Pulse channel 4 | Setting, System Password | | | |
| | | | Alarm settings | | | | | | |
| | | | | Alarm text | [Text String] | Setting, System Password | | | |
| | | | Object | | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6, Mixer, Drain pump, All | Setting, System Password | | | |
| | | | Object | | Mixer, Drain pump | Setting, No Password | | | |
| | | | Allow set clock | | NO, YES | Setting, System Password | | | |
| | | | Object | | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6, All | Setting, System Password | | | |
| | | | Object | | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6, Pump pit | Setting, System Password | | | |
| | | | Signal source | | NO input terminal, NC input terminal, True IO number, Inv. IO number | Setting, System Password | | | |
| | | | One or none of lines below, depending on other settings. | | | | | | |
| | | | IO number | | 1 [Unitless] | Setting, System Password | | | |
| | | | Event trigger | | OFF, ON | Setting, System Password | | | |
| | | | DI2 - DI12 = Menu selection, with preview, identical to above. | | | | | | |
| Module 2 - 9 = Menu selection, with preview, identical to above. | | | | | | | | | |
| Digital outputs | Local at controller | DO1 | Signal function | | OFF, Pump control, Reset motor protector, Pump fail, Not enough pumps avail., One pump fail, Mixer control, Drain pump control, Cleaner control, Com. timeout pulse, Remote control, Personnel alarm, High level, Alarm alert, Not ackn. alarm, Active alarm, Pump reversing, Logic IO, Data register setpoint, Auto reset alert, Valve control, Valve open, Valve close, Time relay, Pulse timer | Setting, System Password | | | |
| | | | Status | | -OFF-, -ON- | Status value | | | |
| | | | One or none of lines below, depending on port function. | | | | | | |
| | | | Object | | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6, Mixer, Drain pump, All | Setting, System Password | | | |
| | | | Settings | Communication port | | Modem port (RS232), RS485 port 1, RS485 port 2, USB port, GPRS data, Ethernet port (TCP/IP) | Setting, System Password | | |
| | | | | Pulse time | | 1 s | Setting, System Password | | |
| | | | | Communication timeout | | 1 s | Setting, System Password | | |
| | | | | Object | | B-Alarm, A-Alarm, All alarms | Setting, System Password | | |
| | | | | Alert source | | Unackn. alarms, Active alarms, Unackn. + active alarms | Setting, System Password | | |
| | | | | On time | | 1 s | Setting, System Password | | |
| | | | Pause time | | 1 s | Setting, System Password | | | |
| | | | Object | | B-Alarm, A-Alarm, All alarms | Setting, System Password | | | |
| | | | Object | | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6 | Setting, System Password | | | |

| Submenu | Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | |
|-----------------|---|----------------|----------|---|--|---|--------------------------|
| Digital outputs | Local at controller | DO1 | Settings | IO signal 1 | OFF, True OR, Inverse OR, True AND, Inverse AND | Setting, System Password | |
| | | | | IO number 1 | 1 [Unitless] | Setting, System Password | |
| | | | | IO signal 2 | OFF, True OR, Inverse OR, True AND, Inverse AND | Setting, System Password | |
| | | | | IO number 2 | 1 [Unitless] | Setting, System Password | |
| | | | | IO signal 3 | OFF, True OR, Inverse OR, True AND, Inverse AND | Setting, System Password | |
| | | | | IO number 3 | 1 [Unitless] | Setting, System Password | |
| | | | | IO signal 4 | OFF, True OR, Inverse OR, True AND, Inverse AND | Setting, System Password | |
| | | | | IO number 4 | 1 [Unitless] | Setting, System Password | |
| | | | | Data register | 1 [Unitless] | Setting, System Password | |
| | | | | Setpoint on | 1 [Unitless] | Setting, System Password | |
| | | | | Setpoint off | 1 [Unitless] | Setting, System Password | |
| | | | | Setpoint delay | 1 s | Setting, System Password | |
| | | Pre-alert time | 1 s | Setting, System Password | | | |
| | Local at controller | DO1 | Settings | Object | | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6, Pump pit | Setting, System Password |
| | | | | Time relay | Time relay | 1, 2, 3, 4, 5, 6, 7, 8 | Setting, System Password |
| | | | | | Sequence | All, 1, 2, 3, 4 | Setting, System Password |
| | | | | | Signal source | Count down timer, IO on, IO off | Setting, System Password |
| | | | | | One or none of lines below, depending on other settings. | | |
| | | | | | Count down timer | 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12 | Setting, System Password |
| | | | | | IO | 1 [Unitless] | Setting, System Password |
| | | | | | Pulse time | 1 s | Setting, System Password |
| | | | | Normally open/closed | | NO Normally open, NC Normally closed | Setting, System Password |
| | | | | Event trigger | | OFF, ON | Setting, System Password |
| | | | | DO2 - DO4 = Menu selection, with preview, identical to above. | | | |
| | Module 1 | Module 1 | DO1 | Signal function | | -Not connected-, -Reconnecting-, -Not connected-, -Connected-, -Error-, -Error-, -Not connected-, CAN ID error, CAN ID error | Status value |
| | | | | | | OFF, Pump control, Reset motor protector, Pump fail, Not enough pumps avail., One pump fail, Mixer control, Drain pump control, Cleaner control, Com. timeout pulse, Remote control, Personnel alarm, High level, Alarm alert, Not ackn. alarm, Active alarm, Pump reversing, Logic IO, Data register setpoint, Auto reset alert, Valve control, Valve open, Valve close, Time relay, Pulse timer | Setting, System Password |
| | | | Status | | -OFF-, -ON- | Status value | |
| | One or none of lines below, depending on port function. | | | | | | |

| Submenu | Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | |
|-----------------|----------|---------|----------|--|--|---|--------------------------|
| Digital outputs | Module 1 | DO1 | Object | | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6, Mixer, Drain pump, All | Setting, System Password | |
| | | | Settings | Communication port | | Modem port (RS232), RS485 port 1, RS485 port 2, USB port, GPRS data, Ethernet port (TCP/IP) | Setting, System Password |
| | | | | Pulse time | | 1 s | Setting, System Password |
| | | | | Communication timeout | | 1 s | Setting, System Password |
| | | | | Object | | B-Alarm, A-Alarm, All alarms | Setting, System Password |
| | | | | Alert source | | Unackn. alarms, Active alarms, Unackn. + active alarms | Setting, System Password |
| | | | | On time | | 1 s | Setting, System Password |
| | | | | Pause time | | 1 s | Setting, System Password |
| | | | Object | | B-Alarm, A-Alarm, All alarms | Setting, System Password | |
| | | | Object | | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6 | Setting, System Password | |
| | | | Settings | IO signal 1 | | OFF, True OR, Inverse OR, True AND, Inverse AND | Setting, System Password |
| | | | | IO number 1 | | 1 [Unitless] | Setting, System Password |
| | | | | IO signal 2 | | OFF, True OR, Inverse OR, True AND, Inverse AND | Setting, System Password |
| | | | | IO number 2 | | 1 [Unitless] | Setting, System Password |
| | | | | IO signal 3 | | OFF, True OR, Inverse OR, True AND, Inverse AND | Setting, System Password |
| | | | | IO number 3 | | 1 [Unitless] | Setting, System Password |
| | | | | IO signal 4 | | OFF, True OR, Inverse OR, True AND, Inverse AND | Setting, System Password |
| | | | | IO number 4 | | 1 [Unitless] | Setting, System Password |
| | | | | Data register | | 1 [Unitless] | Setting, System Password |
| | | | | Setpoint on | | 1 [Unitless] | Setting, System Password |
| | | | | Setpoint off | | 1 [Unitless] | Setting, System Password |
| | | | | Setpoint delay | | 1 s | Setting, System Password |
| | | | | Pre-alert time | | 1 s | Setting, System Password |
| | | | Object | | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6, Pump pit | Setting, System Password | |
| | | | Settings | Time relay | | 1, 2, 3, 4, 5, 6, 7, 8 | Setting, System Password |
| | | | | Sequence | | All, 1, 2, 3, 4 | Setting, System Password |
| | | | | Signal source | | Count down timer, IO on, IO off | Setting, System Password |
| | | | | One or none of lines below, depending on other settings. | | | |
| | | | | Count down timer | | 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11, 12 | Setting, System Password |
| | | | | IO | | 1 [Unitless] | Setting, System Password |
| Pulse time | | 1 s | | Setting, System Password | | | |

| Submenu | Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment |
|-----------------|--|---------|---|--------------------------|---|--------------------------|
| Digital outputs | Module 1 | DO1 | Normally open/closed | | NO Normally open, NC Normally closed | Setting, System Password |
| | | | Event trigger | | OFF, ON | Setting, System Password |
| | DO2 - DO8 = Menu selection, with preview, identical to above. | | | | | |
| | Module 2 - 9 = Menu selection, with preview, identical to above. | | | | | |
| Leakage inputs | Module 1 | DI1 | Signal function | | OFF, Leakage pump, Leakage mixer-drain pump | Setting, System Password |
| | | | Status | | -OFF-, -ON- | Status value |
| | One or none of lines below, depending on port function. | | | | | |
| | Measure point | | Generic, Oil chamber, Motor housing, Electr. con. box | Setting, System Password | | |
| | One or none of lines below, depending on port function. | | | | | |
| | Object | | Pump 1, Pump 2, Pump 3, Pump 4, Pump 5, Pump 6 | Setting, System Password | | |
| | Object | | Mixer, Drain pump | Setting, No Password | | |
| | DI2 - DI6 = Menu selection, with preview, identical to above. | | | | | |
| | Module 2 - 9 = Menu selection, with preview, identical to above. | | | | | |

5.31 Settings: Communication

Table 5.31 shows the complete list of **Communication settings**.

Table 5.31

| Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | |
|--------------------|--|---------------|---------|---|--------------------------|--------------------------|
| USB port | Protocol type | | | Modbus RTU, Modbus TCP | Setting, System Password | |
| | Message timeout | | | 1 s | Setting, System Password | |
| | Cross reference | | | OFF, ON | Setting, System Password | |
| Modem port (RS232) | Baud rate | | | None, 300, 600, 1200, 2400, 4800, 9600, 19200, 38400, 57600, 115200, 230400 | Setting, System Password | |
| | Parity | | | None, Odd, Even, Mark | Setting, System Password | |
| | Station ID | | | 1 [Unitless] | Setting, System Password | |
| | Sim card PIN code | | | [Text String] | Setting, System Password | |
| | Modem type | | | OFF, CA 521, CA 523, CA 524, Generic SMS | Setting, System Password | |
| | Heart beat timeout | | | 1 min | Setting, System Password | |
| | Alarm OFF heart beat | | | NO, YES | Setting, System Password | |
| | Application protocol | | | GPRS Hayes enable, Transparent | Setting, System Password | |
| | One or none of lines below, depending on other settings. | | | | | |
| | Settings Modbus | Protocol type | | | Modbus RTU, Modbus TCP | Setting, System Password |
| Protocol ID | | | | 1 [Unitless] | Setting, System Password | |
| Message timeout | | | | 1 s | Setting, System Password | |

| Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | |
|-----------------------|--|------------------------|---|--|--------------------------|--------------------------|
| Modem port (RS232) | Settings Modbus | Cross reference | | OFF, ON | Setting, System Password | |
| | Settings GPRS | TCP type | | Aquaweb client, TCP server (fixed IP), TCP server + heart beat | Setting, System Password | |
| | | Server IP address | | [Text String] | Setting, System Password | |
| | | Server TCP port number | | 1 [Unitless] | Setting, System Password | |
| | | GPRS APN part 1 | | [Text String] | Setting, System Password | |
| | | GPRS APN part 2 | | [Text String] | Setting, System Password | |
| | | GPRS User name | | [Text String] | Setting, System Password | |
| | | GPRS Password | | [Text String] | Setting, System Password | |
| | | Protocol type | | Modbus RTU, Modbus TCP | Setting, System Password | |
| | | Protocol ID | | 1 [Unitless] | Setting, System Password | |
| | | Message timeout | | 1 s | Setting, System Password | |
| | | Cross reference | | OFF, ON | Setting, System Password | |
| | | Settings Modbus | Protocol type | | Modbus RTU, Modbus TCP | Setting, System Password |
| | Protocol ID | | | 1 [Unitless] | Setting, System Password | |
| | Message timeout | | | 1 s | Setting, System Password | |
| | Cross reference | | | OFF, ON | Setting, System Password | |
| | One or none of lines below, depending on other settings. | | | | | |
| | Settings SMS | SMS alarm enable | | Disabled, A-ON, A-ON/OFF, A+B-ON, A+B-ON/OFF | Setting, System Password | |
| | | Second SMS number | | Backup only, Send always | Setting, System Password | |
| | | First SMS number | | [Text String] | Setting, System Password | |
| Second SMS number | | | [Text String] | Setting, System Password | | |
| RS485 port 1 | Baud rate | | None, 300, 600, 1200, 2400, 4800, 9600, 19200, 38400, 57600, 115200, 230400, 460800 | Setting, System Password | | |
| | Parity | | None, Odd, Even, Mark | Setting, System Password | | |
| | Application protocol | | Modbus slave, Modbus master | Setting, System Password | | |
| | Protocol type | | Modbus RTU, Modbus TCP | Setting, System Password | | |
| | One or none of lines below, depending on other settings. | | | | | |
| | Protocol ID | | | 1 [Unitless] | Setting, System Password | |
| | Poll interval | | | 1 s | Setting, System Password | |
| | One or none of lines below, depending on other settings. | | | | | |
| | Cross reference | | | OFF, ON | Setting, System Password | |
| | Message timeout | | | 1 s | Setting, System Password | |

| Submenu | Submenu | Submenu | Submenu | Setting / Value | Comment | |
|--|--|-----------------------|-------------|---|-------------------------------------|--------------------------|
| RS485 port 2 | Baud rate | | | None, 300, 600, 1200, 2400, 4800, 9600, 19200, 38400, 57600, 115200, 230400, 460800 | Setting, System Password | |
| | Parity | | | None, Odd, Even, Mark | Setting, System Password | |
| | Application protocol | | | Modbus slave, Modbus master | Setting, System Password | |
| | Protocol type | | | Modbus RTU, Modbus TCP | Setting, System Password | |
| | One or none of lines below, depending on other settings. | | | | | |
| | Protocol ID | | | 1 [Unitless] | Setting, System Password | |
| | Poll interval | | | 1 s | Setting, System Password | |
| | One or none of lines below, depending on other settings. | | | | | |
| | Cross reference | | | OFF, ON | Setting, System Password | |
| | Message timeout | | | 1 s | Setting, System Password | |
| | Ethernet port (TCP/IP) | Hardware | | | OFF, ON | Setting, System Password |
| Protocol type | | | | Modbus RTU, Modbus TCP | Setting, System Password | |
| Ethernet port (TCP/IP) | Protocol ID | | | 1 [Unitless] | Setting, System Password | |
| | Message timeout | | | 1 s | Setting, System Password | |
| | Cross reference | | | OFF, ON | Setting, System Password | |
| | Port number | | | 1 [Unitless] | Setting, System Password | |
| | Static/Dynamic IP | | | Static IP, Dynamic IP (DHCP) | Setting, System Password | |
| | One or none of lines below, depending on other settings. | | | | | |
| | Set static IP | | IP address | | [Text String] | Setting, System Password |
| | | | Net Mask | | [Text String] | Setting, System Password |
| | | | Gateway | | [Text String] | Setting, System Password |
| | Show dynamic IP | | IP address | | [Text String] | Status value |
| | | | Net Mask | | [Text String] | Status value |
| | | | Gateway | | [Text String] | Status value |
| | | | Port number | | 1 [Unitless] | Status value |
| | IO Modules (CAN bus) | IO Module lost alarms | CA 811 | ID:1 | | |
| ID:2 | | | | | Menu selection, Identical to above. | |
| ID:3 | | | | | Menu selection, Identical to above. | |
| ID:4 | | | | | Menu selection, Identical to above. | |
| ID:5 | | | | | Menu selection, Identical to above. | |
| ID:6 | | | | | Menu selection, Identical to above. | |
| ID:7 | | | | | Menu selection, Identical to above. | |
| ID:8 | | | | | Menu selection, Identical to above. | |
| ID:9 | | | | | Menu selection, Identical to above. | |
| CA 821, CA 831, CA 832. CA 841, CA 861 = Menu selection, Identical to above. | | | | | | |

5.32 Settings: Field bus modules (RS485)

Table 5.32 shows the complete list of **Field bus modules (RS485) settings**.

Table 5.32

| Submenu | Submenu | Submenu | Setting / Value | Comment | |
|---|--|----------------------|--|--------------------------|--------------------------|
| Main pwr. mon. | Slave ID | | 1 [Unitless] | Setting, System Password | |
| | Bus selection | | RS485 port 1, RS485 port 2 | Setting, System Password | |
| | Manufacturer | | None, Accuenergy, Schneider, Lumel, Carlo Gavazzi | Setting, System Password | |
| | One or none of lines below, depending on manufacturer settings | | | | |
| | Model | | | None, Acuvim II | Setting, System Password |
| | | | | None, PM 710, PM 5110 | Setting, System Password |
| | | | | None, ND 10 | Setting, System Password |
| | | | | None, EM210 | Setting, System Password |
| Main pwr. mon. | Alarm settings | Phase missing | | | |
| | | Pwr. mon. Com. error | | | |
| | | Over voltage | | | |
| | | Under voltage | | | |
| | | Unbalanced voltage | | | |
| | | High frequency | | | |
| | | Low frequency | | | |
| | Use P1 PM for main pwr data | | NO, YES | Setting, System Password | |
| Pwr.mon.P1 | Slave ID | | 1 [Unitless] | Setting, System Password | |
| | Bus selection | | RS485 port 1, RS485 port 2 | Setting, System Password | |
| | Manufacturer | | None, Accuenergy, Schneider, Lumel, Carlo Gavazzi | Setting, System Password | |
| | One or none of lines below, depending on manufacturer settings | | | | |
| | Model | | None, Acuvim II | Setting, System Password | |
| | Model | | None, PM 710, PM 5110 | Setting, System Password | |
| | Model | | None, ND 10 | Setting, System Password | |
| | Model | | None, EM210 | Setting, System Password | |
| | Alarm com. error | | | | |
| Pwr.mon.P2 - Pwr.mon.P6 = Menu selection, with preview, identical to above. | | | | | |
| M.Drive P1 | Slave ID | | 1 [Unitless] | Setting, System Password | |
| | Bus selection | | RS485 port 1, RS485 port 2 | Setting, System Password | |
| | Manufacturer | | None, Invertek, Schneider, Danfoss, ABB, Emotron, NFO drives, Vacon, YASKAWA | Setting, System Password | |
| | One or none of lines below, depending on manufacturer settings | | | | |

| Submenu | Submenu | Submenu | Setting / Value | Comment |
|---|----------------------------|-------------------------|---|--------------------------|
| M.Drive P1 | Model | | None, Optidrive | Setting, System Password |
| | | | None, ATV 61, ATS 48, ATV 600 series, ATV 12, ATS 22, ATV 320 | Setting, System Password |
| | | | None, FC 200, MCD 200, MCD 500 | Setting, System Password |
| | | | None, ACQ 810, ACS 580, ACS 550, PSTX, ACQ580, ACS880 | Setting, System Password |
| | | | None, TSA Softstarter, FDU 2 | Setting, System Password |
| | | | None, Sinus | Setting, System Password |
| | | | None, Vacon 100, Vacon 20 | Setting, System Password |
| | | | None, P1000 <= 11KW, P1000 > 11KW | Setting, System Password |
| | Modbus control | | Monitor, & Control on/off, & Manual speed, & Auto speed | Setting, System Password |
| | Max. set frequency VFD | | 0.1 Hz | Setting, System Password |
| | Min. set frequency VFD | | 0.1 Hz | Setting, System Password |
| | Pump cap at min. freq. | | 0.1 % | Setting, System Password |
| | Set manual frequency | | 0.1 Hz | Setting, System Password |
| | Set reverse frequency | | 0.1 Hz | Setting, System Password |
| | Control frequency | | 0.01 Hz | Setting, System Password |
| | A-0 sw. blocks Modbus com. | | NO, YES | Setting, System Password |
| | Drive fault alarm | Motor drive alarm | | |
| | | Enable auto reset | NO, YES | Setting, System Password |
| | | Ackn. alarm reset drive | NO, YES | Setting, System Password |
| | Alarm com. error | | | |
| M.Drive P2 - M.Drive P6 = Menu selection, with preview, identical to above. | | | | |

5.33 Select language

Table 5.33 shows the complete list of **language settings**.

Table 5.33

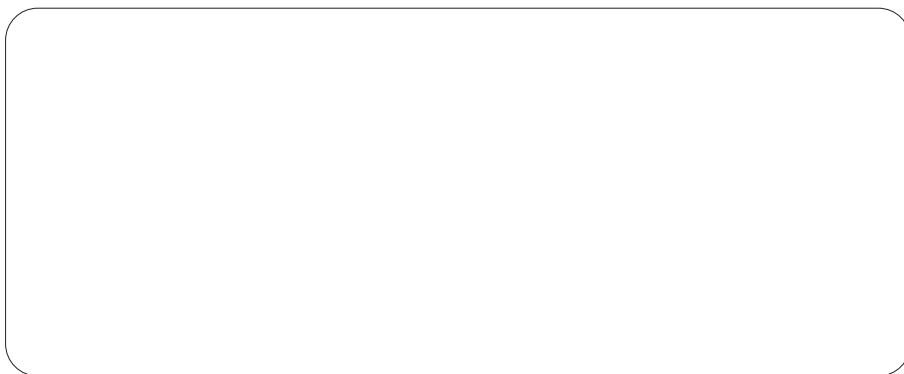
| Submenu | Setting / Value | Comment |
|-----------------|--|----------------------|
| System language | English, French, German, Spanish, Danish, Dutch, Italian, Norwegian, Polish, Portuguese (Brazil), Swedish, Turkish | Setting, No Password |

5.34 Calibrate touch screen

Table 5.34 shows the complete list of **calibration settings**.

Table 5.34

| Submenu | Setting / Value | Comment |
|------------------------|-----------------|----------------------|
| Calibrate touch screen | NO, YES | Setting, No Password |



SULZER

Sulzer Pump Solutions Ireland Ltd., Clonard Road, Wexford, Ireland
Tel. +353 53 91 63 200, www.sulzer.com